## M. Sc. Electronics and Instrumentation

# Syllabus

### UNIVERSITY DEPARTMENT

### **Program Code: ELIA**

### 2021 – 2022 onwards



### **BHARATHIAR UNIVERSITY**

(A State University, Accredited with "A" Grade by NAAC, Ranked 13<sup>th</sup> among Indian Universities by MHRD-NIRF, World Ranking: Times -801-1000,Shanghai -901-1000, URAP - 982)

Coimbatore - 641 046, Tamil Nadu, India

#### **Program Educational Objectives (PEOs)**

The **M. Sc. Electronics and Instrumentation** program describe accomplishments that graduates are expected to attain within five to seven years after graduation

| PEO1 | To provide the necessary foundation and advanced techniques on computational<br>and software platforms related to the field of Electronics and Instrumentation |
|------|--|
| PEO2 | To be successful in their respective professional careers in the field of Electronics & Instrumentation  |
| PEO3 | To engross in life long process of learning that keep themselves abreast of new developments in the field of Electronics & Instrumentation                     |



After the successful completion of M. Sc. Electronics and Instrumentation program, the students are expected to

| PSO1 | Be able to Select, install, calibrate and maintain instruments used formeasurement<br>and analysis and interpret the data obtained to arrive at a significant<br>conclusion.                  |  |  |  |  |  |  |  |  |
|------|---|--|--|--|--|--|--|--|--|
| PSO2 | Be able to analyze, design and develop signal conditioning circuits for sensors, actuators and select a suitable Embedded System for realizing various control schemes and smart instruments. |  |  |  |  |  |  |  |  |
| PSO3 | Be able to design, develop and implement control schemes for various industrial processes and gain hands on experience in configuring Industrial Automation System such as PLC and LabVIEW.   |  |  |  |  |  |  |  |  |



| Program  | n Outcomes (POs)  |
|----------|---|
| On succe | ssful completion of the M. Sc. Electronics and Instrumentation program  |
| PO1      | Understand and apply the Mathematical knowledge of Signals and systems,<br>Electro Magnetic theory, Control Theory, VLSI Design, Medical Electronics and<br>Signal Processing concepts to solve the problems pertaining in the field of<br>Electronics and Instrumentation. |
| PO2      | Identify, analyze and solve the Electronics and Instrumentation problems from literatures using the imported concepts.  |
| PO3      | Understand, analyze and apply Embedded Systems, LabVIEW, PLC VLSI<br>Design, Medical Electronics and Robotics Automation concepts in various<br>industrial applications.  |
| PO4      | Demonstrate the knowledge and understanding of Electronics and Instrumentation principles and to apply these to one's own work as a member / leader in a team to manage Electronics / Instrumentation / Control and Robotics Automation projects.                           |
| PO5      | Self and life-long learning, keeping pace with advanced technological challenges in the broadest sense.   |
| PO6      | Ability to analyze complex problems in Instrumentation domain and recommend<br>right solutions with acquired mastery technical knowledge in Electronics and<br>Instrumentation.   |
| PO7      | Draw well-founded conclusions applying the knowledge acquired from research<br>and research methods including design of experiments, analysis and interpretation<br>of data and synthesis of information and to arrive at significant conclusion.                           |
| PO8      | An ability to independently carry out research and developmental work and arrive<br>at well-founded solutions for complex Electronics and Instrumentation problems  |
| PO9      | Select and apply relevant techniques, Engineering and IT tools for Engineering activities like modelling and control of systems/processes and also being conscious of the limitations.  |
| PO10     | Comprehend professional and ethical responsibility in the field of Electronics and Instrumentation  |

#### **BHARATHIAR UNIVERSITY : : COIMBATORE 641 046** M. Sc. Electronics and Instrumentation Curriculum(UniversityDepartment)

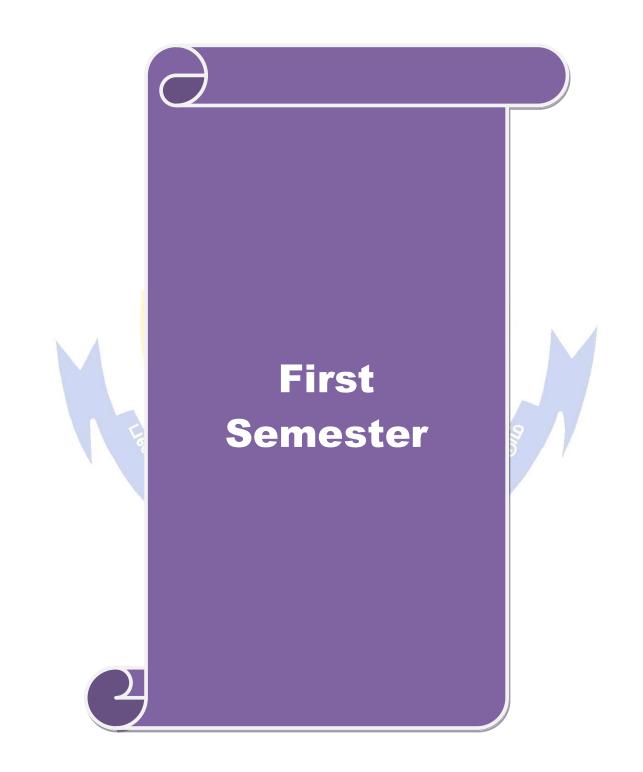
| Course           |  | <b>C I</b> ''    | Н            | ours        | Ma               | aximum   | Marks      |
|------------------|--|------------------|--------------|-------------|------------------|----------|------------|
| Code             | Title of the Course  | Credits          | Theory       | Practical   | CIA              | ESE      | Total      |
|                  |  | ST SEMES         | STER         |             |                  |          |            |
| 13A              | Sensors and Transducers  | 4                | 4            | -           | 50               | 50       | 100        |
| 13B              | Signals and systems  | 4                | 4            | -           | 50               | 50       | 100        |
| 13C              | Embedded Systems   | 4                | 4            | -           | 50               | 50       | 100        |
| 13D              | Electro Magnetic Theory  | 4                | 4            | -           | 50               | 50       | 100        |
| 13P              | PIC Micro Controller<br>Laboratory                                 | 3                | -            | 3           | 30               | 45       | 75         |
| 13Q              | Instrumentation Laboratory   | 3                | 6.12         | 3           | 30               | 45       | 75         |
| 1EA              | Elective   | 4                | 4            |             | 50               | 50       | 100        |
| Supportiv        |  | 2                | 2            | × - >       | 25               | 25       | 50         |
|                  | Total  | 28               | 22           | 06          | 335              | 365      | 700        |
|                  | SECO   | OND SEMI         |              | 18          | 1                | 1        |            |
| 23A              | Control Systems  | 4                | 4            |             | 50               | 50       | 100        |
| 23B              | ARM Processor  |                  | 4            | 1-2         | <mark>5</mark> 0 | 50       | 100        |
| 23C              | Intelligent Instrumentation  | 4                | 4            | A 1-2.      | <mark>5</mark> 0 | 50       | 100        |
| 23D              | Introduction to Industry 4.0                                       | 4                | 4            | 3           | <mark>5</mark> 0 | 50       | 100        |
| 23P              | ARM Processor Laboratory   | 3                | 20           | 3           | <mark>3</mark> 0 | 45       | 75         |
| 23Q              | Intelligent Instrumentation &<br>Medical Electronics<br>Laboratory | 3                | Bullion and  | 3           | 30               | 45       | 75         |
| 2EB              | Elective   | 4                | 4            |             | 50               | 50       | 100        |
| Supportiv        | ve Offered by other Departments                                    | 2                | 2            | 5 - /       | 25               | 25       | 50         |
|                  | Total  | 28               | 22           | 06          | 335              | 365      | 700        |
|                  |  | RD SEME          | STER         |             | S .              |          | 1          |
| 33A              | Process Control  | 4                | 4            | - 00        | 50               | 50       | 100        |
| 33B              | Digital Signal Processing  | Con 4 pertor     | 4            | -0-         | 50               | 50       | 100        |
| 33C              | VLSI Design  | 4                | 4            | 21-         | 50               | 50       | 100        |
| 33P              | Digital Signal Processing<br>Laboratory                            | பாரை             | 2_1-115      | 3           | 30               | 45       | 75         |
| 33Q              | VLSI Laboratory 50000<br>Elective                                  | 175 - 30 EL      | EVATE        | 3           | 30               | 45<br>50 | 75         |
| 3EC<br>Supportiv |  | 2                | 4            | -           | 50<br>25         | 25       | 100<br>50  |
| Support          | Total  | 24               | <u> </u>     | 06          | <b>23</b>        | 315      | <b>600</b> |
|                  |  | L 24<br>RTH SEMI |              | UU          | 203              | 515      | 000        |
| 43A              | PLC and Its Applications   | 4                | 4            | _           | 50               | 50       | 100        |
| 43P              | PLC, SCADA Laboratory  | 3                | -            | 3           | 30               | 45       | 75         |
| 47V              | Project, Viva-Voce and<br>Industrial Visit                         | 3                | _            | 3           | 30               | 45       | 75         |
|                  | Total  | 10               | 04           | 06          | 110              | 140      | 250        |
|                  | Grand Total  | 90               | 66           | 24          | 1065             | 1185     | 2250       |
|                  | ONI  | LINE COU         | RSES         |             |                  |          |            |
|                  |  |                  | 2            |             |                  |          |            |
|                  | SWAYAM – MOOC – Online Course*                                     | Not              | n-scholastic | with Credit | s                | I        |            |

(For the students admitted during the academic year 2021–22 onwards)

| Digital Tools<br>(Lab Integrated Theory)                   | 2        | 15  | 15 | 25 | 25 | 5<br>0      |
|--|----------|-----|----|----|----|-------------|
| NLP and NLP (Theory)                                       | 2        | 30  |    | 50 | -  | 5<br>0      |
| JOB ORIENT   | ED COURS | SES |    |    |    |             |
| DSP Using MATLAB   | 2        | 40  | 40 | 50 | 50 | 1<br>0<br>0 |
| Embedded System Design Using<br>ARM/Cortex Microcontroller | 2        | 40  | 40 | 50 | 50 | 1<br>0<br>0 |

\*SWAYAM – MOOC – online course shall be of duration at least 4 weeks with at least 2 credits. The course shall be mandatory and shall be completed within third semester (i.e., before the beginning of fourth semester).





| Course Code          | 13A                             | SENSORS AND TRANSDUCERS   | L           | Т             | Р           | С     |
|----------------------|---------------------------------|---|-------------|---------------|-------------|-------|
| Core/Elective/S      | -                               | Core  | 4           | 0             | 0           | 4     |
|                      | Stude                           | nt should have the good knowledge on Basic  | Syllabus    |               | 2021        | -22   |
| Pre-requisite        | of Ser                          | sors and Transducer   | Version     |               |             |       |
| <b>Course Object</b> | ives:                           |   |             |               |             |       |
| The main object      | tives of thi                    | s course are to:  |             |               |             |       |
| 1. Provide an        | adequate l                      | knowledge in resistance, inductance and capacita  | nce trans   | duce          | rs.         |       |
| 2. Study the         | characterist                    | ics of Transducers, sensors and MEMS  |             |               |             |       |
| 3. To explore        | e on various                    | s types of transducers, sensors.  |             |               |             |       |
| -                    |                                 | brication of the sensors  |             |               |             |       |
|                      | 0                               |   |             |               |             |       |
| <b>Expected</b> Cou  | rse Outcon                      | nes:  |             |               |             |       |
| On the success       | sful comple                     | tion of the course, student will be able to:  |             |               |             |       |
|                      |                                 | he fundamentals and standards of sensors and tra  |             |               | K1          |       |
|                      |                                 | and functioning of latest sensor can be understo  |             |               | K4          |       |
| K1 - Rememb          | er; <b>K2 <mark>- U</mark>1</b> | <mark>nderstand; K3</mark> - Apply; K4 - Analyze <mark>; K5 - Eva</mark> l                          | uate; K6    | - Cre         | eate        |       |
|                      |                                 |   |             |               |             |       |
| Unit:1               | 6                               | Sensors and Transducers   | ~ .         |               | 12 ho       |       |
|                      |                                 | - Classification of errors - Error analysis   |             |               |             |       |
|                      |                                 | cers – Performance measures of sensors – Cla  | ssification | n of          | sensc       | ors – |
| Sensor calibra       | tion technic                    | ques – Sensor Output Signal Types.  |             |               |             | (     |
| Unit:2               |                                 | Transducers and its types   |             |               | 12 ho       | urs   |
| -                    |                                 | construction details, Characteristics and app   |             |               | resist      |       |
| potentiometer,       |                                 | auge, Resistance Thermometer, Thermistor,   |             |               | emor        |       |
|                      |                                 | Humidity Sensor, Induction potentiometer-Variable<br>active transducer and types-Capacitor Micropho |             |               |             |       |
|                      |                                 | agnetostrictive - IC Sensor-Digital Transducers-S   |             |               |             |       |
|                      |                                 | Im sensors. Ultrasonic sensors – IR sensors   | G           | /             |             | oput  |
|                      | es .                            | Han unit  | 13          |               |             |       |
| Unit:3               | N Solo                          | Signal Conditioning and DAQ Systems   | 8           |               | 10 ho       | urs   |
| Amplification        | n – Filterin                    | g – Sample and Hold circuits – Data Acquisiti   | on: Singl   | e ch          | annel       | and   |
|                      |                                 | sition – Data logging - applications - Automo   | bile, Aer   | ospa          | ce, H       | ome   |
| appliances, M        | anufacturin                     | g, Environmental monitoring.  |             |               |             |       |
| TT . • 4 . 4         |                                 | EDUCMEMON ELEVATE   |             |               | 10.1        |       |
| Unit:4               | w of MEM                        | S and Microsystems-Working principles of Microsystems   | atoma: Mic  | <b>r</b> o co | <u>12 h</u> |       |
|                      |                                 | th Microactuators- Micro accelerometers   | stems. wh   | 10 50         | 115015-     | •     |
| microactulation      |                                 |   |             |               |             |       |
| Unit:5               | MIC                             | ROSYSTEMS FABRICATION PROCESSES   |             |               | 12 ho       | urs   |
| Introduction-        |                                 | ography-Ion Implementation-Diffusion-Oxida  |             |               |             | apor  |
|                      |                                 | por deposition- Deposition by Epitaxy-Etching   |             |               |             | licro |
| Manufacturing        | g: Bulk Mic                     | cro Manufacturing-Surface Micromachining-Th   | e LIGA F    | roce          | SS.         |       |
| Unit:6               |                                 | Contemporary Issues   |             |               | 2 h         | ours  |
| Biosensor, Na        | no electron                     |   |             |               |             |       |
|                      |                                 | Total Lecture hour  | rs 🛛        |               | 60 h        | ours  |
| Text Book(s)         |                                 |   |             |               |             |       |
|                      |                                 |   |             |               |             |       |
| 1 A.K.Sa             | •                               | course in Electrical & Electronic Measuremen<br>Co (P) Ltd.2015.                                    | nt and Ins  | trum          | entati      | on"   |

| 2.    | E.O.Doebelin, "Measurement Systems-Applications and Design", Tata McGraw Hill,       |
|-------|--|
| ۷.    |  |
|       | New Work, 1990   |
| 3.    | D.V.S Murthy, "Transducer and Instrumentation", Prentice Hall of India, 1995.        |
| 4.    | Tai-Ran Hsu "MEMS and microsystems: design and manufacture "McGraw-Hill, 2002.       |
| Refe  | rence Books  |
| 1.    | John P.Bentley, "Principles of Measurement Systems", III Edition, Pearson Education, |
|       | 2000.  |
| 2.    | Hermann K.P.Neubert, "Instrument Transducers", Oxford University Press, 2000.        |
| 3.    | D.V.S.Murthy, "Transducers and Instrumentation", Prentice Hall of India, 2001.       |
| 4.    | D.Patranabis, "Sensors and Transducers", Prentice Hall of India, 1999                |
|       |  |
| Relat | ted Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]                             |
| 1.    | https://nptel.ac.in/content/storage2/courses/112103174/pdf/mod2.pdf                  |
| 2.    | https://lecturenotes.in/notes/2143-notes-for-sensors-and-transducers-st-by-anita-    |
|       | mohanty?reading  |
| 3.    | https://nptel.ac.in/content/storage2/courses/108105063/pdf                           |
|       |  |
| Cours | se Designed By: Dr.K.G.Padmasine   |

| Mapping with Programme Outcomes |     |     |     |      |        |       |            |     |     |      |  |
|---------------------------------|-----|-----|-----|------|--------|-------|------------|-----|-----|------|--|
| COs                             | PO1 | PO2 | PO3 | PO4  | PO5    | PO6   | <b>PO7</b> | PO8 | PO9 | PO10 |  |
| CO1                             | S   | S   | М   | L    | L      | М     | M          | S   | S   | S    |  |
| CO2                             | S   | S   | M   | L    | L      | S     | M          | М   | S   | S    |  |
|                                 |     |     | 1 K | T.A. | - Jose | 1.1.1 | ~.7        | SIL |     |      |  |

\*S-Strong; M-Medium; L-Low

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sal- Colé

| Course code<br>Core/Elective/Sup  | 13B  | SIGNALS AND SYSTEMS Core  | L<br>4   | T<br>0                                       | P<br>0  | C 4  |
|---|--|---|--|--|---|--|
| Pre-requisite   | portive  | Basic mathematics knowledge is Essential  | Sylla  | bus  | 2021-   |  |
| Course Objective  | 26.  |   | Versi  | lon  | _   |  |
| The main objective  |  | ourse are to:   |  |  |   |  |
|   |  |   |  |  |   |  |
|   |  | operties of signal & systems<br>naracterization of LTI systems in time domain   |  |  |   |  |
|   |  | e signals and system in the Fourier and Laplace do  | main   |  |   |  |
|   |  | gnals and system in the Fourier and Z transform do  |  |  |   |  |
| •   |  | - ·   |  |  |   |  |
| <b>Expected Course</b>  |  |   |  |  |   |  |
|   | <b>A</b>   | n of the course, student will be able to:   |  |  |   |  |
|   |  | rstem is linear/causal/stable   |  |  |   | K2   |
| 2 Capable of<br>3 Capable of  | determining  | the frequency components present in a determinis  | stic sig   | gnal   |   | K4<br>K4   |
| b Capable of domain   | characteriz  | zing LTI systems in the time domain and frequ   | uency  |  | 1   | <b>Ν</b> 4   |
|   | e output of  | an LTI system in the time and frequency domains   |  |  | 1   | K4   |
|   |  | rstand; K3 - Apply; K4 - Analyze; K5 - Evaluate;  |  | reate  |   |  |
|   | TS.  |   |  |  |   |  |
| Unit:1  | 95   | Classification of Signals and Systems   |  |  | 12 ho   |  |
| Standard signals  | - Sten R   |   |  |  |   |  |
|   | -  | amp, Pulse, Impulse, Real and complex expone  |  |  |   | _  |
| Classification of   | -  | Continuous time (CT) and Discrete Time (DT  |  |  |   | _  |
|   | f s <mark>ign</mark> als –   |   | ) signa  | als, l                                       | Periodi   | c &  |
| Aperiodic signal  | s, Determin  | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa   | ) signa<br>als - C   | als, l<br>Classi                             | Periodi<br>ificatio   | c &<br>n of  |
| Aperiodic signal  | f <mark>signals –</mark><br>s, Determin<br>stems and   | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia   | ) signa<br>als - C   | als, l<br>Classi                             | Periodi<br>ificatio   | c &<br>n of  |
| Aperiodic signal<br>systems- CT sys<br>Causal & Non-ca  | f <mark>signals –</mark><br>s, Determin<br>stems and   | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.  | ) signa<br>als - C   | als, l<br>Classi                             | Periodi<br>ificatio<br>-invari  | ic &<br>n of<br>iant,  |
| Aperiodic signal<br>systems- CT sys<br>Causal & Non-ca<br>Unit:2  | signals –<br>s, Deterministems and<br>stable stable stabl | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals   | <mark>)</mark> signa<br>als - C<br>unt & '                 | als, l<br>Classi<br>Time                     | Periodi<br>ificatio<br>e-invari<br>12 ho  | n of iant,   |
| Aperiodic signal<br>systems- CT sys<br>Causal & Non-ca<br>Unit:2  | signals –<br>s, Deterministems and<br>stable stable stabl | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.  | <mark>)</mark> signa<br>als - C<br>unt & '                 | als, l<br>Classi<br>Time                     | Periodi<br>ificatio<br>e-invari<br>12 ho  | n of iant,   |
| Aperiodic signal<br>systems- CT sys<br>Causal & Non-ca<br>Unit:2<br>Fourier series for<br>properties  | signals –<br>s, Deterministems and<br>susal, Stable<br>or periodic   | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap  | <mark>)</mark> signa<br>als - C<br>unt & '                 | als, l<br>Classi<br>Time                     | Periodi<br>ficatio<br>-invari<br>12 ho<br>forms   | or & n of iant,  |
| Aperiodic signal<br>systems- CT sys<br>Causal & Non-ca<br>Unit:2<br>Fourier series for<br>properties<br>Unit:3  | s signals –<br>s, Determin<br>stems and<br>susal, Stable<br>or periodic<br>Line  | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap<br>ar Time Invariant Continuous Time Systems   | ) signa<br>als - C<br>nt & '                               | als, l<br>Classi<br>Time<br>ransf            | Periodi<br>ficatio<br>-invari<br>12 ho<br>forms a<br>12 ho  | c &<br>n of<br>iant,<br>ours<br>and  |
| Aperiodic signal<br>systems- CT sys<br>Causal & Non-ca<br>Unit:2<br>Fourier series for<br>properties<br>Unit:3<br>Impulse respons   | signals –<br>s, Deterministems and<br>nusal, Stable<br>or periodic<br>Line<br>e - convolu  | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap  | ) signa<br>als - C<br>nt & '<br>olace t                    | als, l<br>Classi<br>Time<br>ransf            | Periodi<br>ficatio<br>-invari<br>12 ho<br>forms a<br>12 ho  | c &<br>n of<br>iant,<br>ours<br>and  |
| Aperiodic signal<br>systems- CT sys<br>Causal & Non-ca<br>Unit:2<br>Fourier series for<br>properties<br>Unit:3<br>Impulse respons<br>Analysis of CT s   | signals –<br>s, Deterministems and<br>nusal, Stable<br>or periodic<br>Line<br>e - convolu  | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap<br>ar Time Invariant Continuous Time Systems<br>tion integrals- Differential Equation- Fourier and I<br>ystems connected in series / parallel.   | ) signa<br>als - C<br>nt & '<br>olace t                    | als, l<br>Classi<br>Time<br>ransf            | Periodi<br>ficatio<br>-invari<br>12 ho<br>forms a<br>12 ho<br>nsform  | c &<br>n of<br>iant,<br>ours<br>and<br>ours<br>is in                                       |
| Aperiodic signal<br>systems- CT sys<br>Causal & Non-ca<br>Unit:2<br>Fourier series for<br>properties<br>Unit:3<br>Impulse respons<br>Analysis of CT s<br>Unit:4   | s signals –<br>s, Determin<br>stems and<br>uusal, Stable<br>or periodic<br>Line<br>e - convolu<br>ystems - Sy  | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap<br>ar Time Invariant Continuous Time Systems<br>tion integrals- Differential Equation- Fourier and I<br>stems connected in series / parallel.<br>Analysis of Discrete Time Signals   | ) signa<br>als - C<br>nt & '<br>olace t<br>Laplac          | als, 1<br>Classi<br>Time<br>ransf            | Periodi<br>ficatio<br>invari<br>12 ho<br>forms a<br>12 ho<br>nsform   | c &<br>n of<br>iant,<br>ours<br>and<br>ours<br>as in<br>ours                               |
| Aperiodic signal<br>systems- CT sys<br>Causal & Non-ca<br>Unit:2<br>Fourier series for<br>properties<br>Unit:3<br>Impulse respons<br>Analysis of CT s<br>Unit:4   | signals –<br>s, Determine<br>stems and<br>susal, Stable<br>or periodic<br>Line<br>e - convolu<br>ystems - Sy<br>Sampling   | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap<br>ar Time Invariant Continuous Time Systems<br>tion integrals- Differential Equation- Fourier and I<br>stems connected in series / parallel.<br>Analysis of Discrete Time Signals<br>– Fourier Transform of discrete time signals (D  | ) signa<br>als - C<br>nt & '<br>olace t<br>Laplac          | als, 1<br>Classi<br>Time<br>ransf            | Periodi<br>ficatio<br>invari<br>12 ho<br>forms a<br>12 ho<br>nsform   | c &<br>n of<br>iant,<br>ours<br>and<br>ours<br>as in<br>ours                               |
| Aperiodic signal<br>systems- CT sys<br>Causal & Non-ca<br>Unit:2<br>Fourier series for<br>properties<br>Unit:3<br>Impulse respons<br>Analysis of CT s<br>Unit:4<br>Baseband signal  | s signals –<br>s, Determin<br>stems and<br>uusal, Stable<br>or periodic<br><b>Line</b><br>e - convolu<br>ystems - Sy<br>Sampling<br>form & Prop  | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap<br>ar Time Invariant Continuous Time Systems<br>tion integrals- Differential Equation- Fourier and I<br>stems connected in series / parallel.<br>Analysis of Discrete Time Signals<br>– Fourier Transform of discrete time signals (D  | ) signa<br>als - C<br>nt & '<br>olace t<br>Laplac          | als, 1<br>Classi<br>Time<br>ransf            | Periodi<br>ficatio<br>invari<br>12 ho<br>forms a<br>12 ho<br>nsform   | c &<br>n of<br>iant,<br>ours<br>and<br>ours<br>is in<br>ours<br>s of                       |
| Aperiodic signal<br>systems- CT systems- systems | s signals –<br>s, Determine<br>stems and<br>susal, Stable<br>or periodic<br><u>Line</u><br>e - convolu-<br>ystems - Sy<br>Sampling<br>Form & Prop<br>Line<br>e – Differe   | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap<br>ar Time Invariant Continuous Time Systems<br>tion integrals- Differential Equation- Fourier and D<br>stems connected in series / parallel.<br>Analysis of Discrete Time Signals<br>– Fourier Transform of discrete time signals (D<br>perties<br>ear Time Invariant-Discrete Time Systems<br>ence equations-Convolution sum- Discrete Fourier   | ) signa<br>als - C<br>unt & '<br>olace t<br>Laplac<br>TFT) | als, 1<br>Classi<br>Time<br>ransf<br>ce tran | Periodi<br>ficatio<br>invari<br>12 ho<br>forms a<br>12 ho<br>pertie<br>12 ho<br>orm an                                  | c &<br>n of<br>iant,<br>ours<br>and<br>is in<br>ours<br>s of<br>d Z                        |
| Aperiodic signal<br>systems- CT systems- systems | s signals –<br>s, Determine<br>stems and<br>susal, Stable<br>or periodic<br><u>Line</u><br>e - convolu-<br>ystems - Sy<br>Sampling<br>Form & Prop<br>Line<br>e – Differe   | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap<br>ar Time Invariant Continuous Time Systems<br>tion integrals- Differential Equation- Fourier and D<br>stems connected in series / parallel.<br>Analysis of Discrete Time Signals<br>– Fourier Transform of discrete time signals (D<br>perties<br>ear Time Invariant-Discrete Time Systems   | ) signa<br>als - C<br>unt & '<br>olace t<br>Laplac<br>TFT) | als, 1<br>Classi<br>Time<br>ransf<br>ce tran | Periodi<br>ficatio<br>invari<br>12 ho<br>forms a<br>12 ho<br>pertie<br>12 ho<br>orm an                                  | c &<br>n of<br>iant,<br>ours<br>and<br>is in<br>ours<br>s of<br>d Z                        |
| Aperiodic signal<br>systems- CT systems- CT systems- CT systems- CT systems- CT systems- CT systems and systems for properties for properties for properties for properties for the system of the system  | s signals –<br>s, Determine<br>stems and<br>susal, Stable<br>or periodic<br><u>Line</u><br>e - convolu-<br>ystems - Sy<br>Sampling<br>Form & Prop<br>Line<br>e – Differe   | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap<br>ar Time Invariant Continuous Time Systems<br>tion integrals- Differential Equation- Fourier and D<br>stems connected in series / parallel.<br>Analysis of Discrete Time Signals<br>– Fourier Transform of discrete time signals (D<br>perties<br>ear Time Invariant-Discrete Time Systems<br>ence equations-Convolution sum- Discrete Fouriurs<br>ursive & Non-Recursive systems-DT systems con-                      | ) signa<br>als - C<br>unt & '<br>olace t<br>Laplac<br>TFT) | als, 1<br>Classi<br>Time<br>ransf<br>ce tran | Periodi<br>ificatio<br>-invari<br>12 ho<br>forms a<br>12 ho<br>nsform<br>10 ho<br>opertie<br>12 ho<br>orm an-<br>series | c &<br>n of<br>iant,<br>ours<br>and<br>ours<br>is in<br>ours<br>s of<br>ours<br>d Z<br>and |
| Aperiodic signal<br>systems- CT systems- CT systems- CT systems- CT systems- CT systems- CT systems and systems for the system of t | Signals –<br>s, Determine<br>stems and<br>susal, Stable<br>or periodic<br>Line<br>e - convolu-<br>ystems - Sy<br>Sampling<br>Form & Prop<br>Line<br>e – Differe<br>ysis of Rec   | Continuous time (CT) and Discrete Time (DT<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap<br>ar Time Invariant Continuous Time Systems<br>tion integrals- Differential Equation- Fourier and D<br>stems connected in series / parallel.<br>Analysis of Discrete Time Signals<br>– Fourier Transform of discrete time signals (D<br>perties<br>ear Time Invariant-Discrete Time Systems<br>ence equations-Convolution sum- Discrete Fourier   | ) signa<br>als - C<br>unt & '<br>olace t<br>Laplac<br>TFT) | als, 1<br>Classi<br>Time<br>ransf<br>ce tran | Periodi<br>ificatio<br>-invari<br>12 ho<br>forms a<br>12 ho<br>nsform<br>10 ho<br>opertie<br>12 ho<br>orm an-<br>series | c &<br>n of<br>iant,<br>ours<br>and<br>is in<br>ours<br>s of<br>d Z                        |
| Aperiodic signal<br>systems- CT systems- CT systems- CT systems- CT systems- CT systems- CT systems and the systems of the system | Signals –<br>s, Determine<br>stems and<br>susal, Stable<br>or periodic<br>Line<br>e - convolu-<br>ystems - Sy<br>Sampling<br>Form & Prop<br>Line<br>e – Differe<br>ysis of Rec   | Continuous time (CT) and Discrete Time (DT)<br>nistic & Random signals, Energy & Power signa<br>DT systems- – Linear & Nonlinear, Time-varia<br>e & Unstable.<br>Analysis of Continuous Time Signals<br>signals - Fourier Transform – properties- Lap<br>ar Time Invariant Continuous Time Systems<br>tion integrals- Differential Equation- Fourier and D<br>stems connected in series / parallel.<br>Analysis of Discrete Time Signals<br>– Fourier Transform of discrete time signals (D<br>perties<br>ear Time Invariant-Discrete Time Systems<br>ence equations-Convolution sum- Discrete Fouri<br>ursive & Non-Recursive systems-DT systems con-<br>Contemporary Issues | ) signa<br>als - C<br>unt & '<br>olace t<br>Laplac<br>TFT) | als, 1<br>Classi<br>Time<br>ransf<br>ce tran | Periodi<br>ificatio<br>-invari<br>12 ho<br>forms a<br>12 ho<br>nsform<br>10 ho<br>opertie<br>12 ho<br>orm an-<br>series | c &<br>n of<br>iant,<br>ours<br>and<br>ours<br>is in<br>ours<br>s of<br>d Z<br>and<br>ours |

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| Tex  | t Book(s)   |
|------|---|
| 1    | Allan V.Oppenheim, S.Wilsky and S.H.Nawab, Signals and Systems, Pearson, 2015           |
| 2    | John Alan Stuller, An Introduction to Signals and Systems <sup>I</sup> , Thomson, 2007. |
|      |   |
| Ref  | erence Books  |
| 1    | B. P. Lathi, Principles of Linear Systems and Signalsl, Second Edition, Oxford, 2009.   |
| 2    | R.E.Zeimer, W.H.Tranter and R.D.Fannin, Signals & Systems - Continuous and Discretel,   |
|      | Pearson, 2014.  |
|      |   |
| Rela | ated Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]                               |
| 1    | https://nptel.ac.in/courses/117/101/117101055/  |
|      |   |
| 2    | https://nptel.ac.in/courses/108/104/108104100/  |

Course Designed By: Dr.J.Vijayakumar

| Mappi      | Mapping with Programme Outcomes |     |     |     |      |     |            |     |     |      |  |  |
|------------|---------------------------------|-----|-----|-----|------|-----|------------|-----|-----|------|--|--|
| COs        | PO1                             | PO2 | PO3 | PO4 | PO5  | PO6 | <b>PO7</b> | PO8 | PO9 | PO10 |  |  |
| CO1        | S                               | S   | M   | M   | als/ | M   | М          | S   | S   | S    |  |  |
| CO2        | S                               | S   | L   | L   | M    | S   | М          | М   | S   | S    |  |  |
| CO3        | S                               | S   | L   | М   |      | М   | S          | M   | S   | S    |  |  |
| <b>CO4</b> | S                               | S   | M   | L   | L    | S   | S          | S   | S   | S    |  |  |

| Course<br>code           | 13C                                  | EMBEDDED SYSTEM DESIGN  | L                  | Т            | Р            | C     |
|--------------------------|--------------------------------------|---|--------------------|--------------|--------------|-------|
| Core/Electi              | ive/ Supportive                      | Core  | 4                  | 0            | 0            | 4     |
| Pre-requi                | site                                 | <b>Basic knowledge about Digital Electronics</b>  | Syllal<br>Versi    |              | 2021         | -22   |
| Course Ob                |                                      |   |                    |              |              |       |
|                          | bjectives of this co                 |   |                    |              |              |       |
|                          | -                                    | ibedded system design.  |                    |              |              |       |
|                          |                                      | ecture of PIC microcontroller.  |                    |              |              |       |
| 3. Fam                   | iliarize in PIC pro                  | gramming.   |                    |              |              |       |
| Exposted (               | Course Outcomes                      | •   |                    |              |              |       |
| A                        |                                      | n of the course, student will be able to:   |                    |              |              |       |
|                          |                                      | C Microcontroller in application perspective.   |                    |              | K4           |       |
|                          |                                      | C Microcontroller based embedded for industrial a   | pplicat            | ion          | K5&I         |       |
| Ŭ                        | A                                    | nowledge, Skill and also to identify, comprehend  | <u></u>            |              | K6           |       |
|                          |                                      | search and academics related to power, informatio   |                    |              |              |       |
| -                        | onics hardware.                      | C C C C   |                    |              |              |       |
| K1 - Reme                | ember; <b>K2</b> - <mark>Unde</mark> | rstand; K3 - Apply; K4 - Analyze; K5 - Evaluate;  | <b>K6 -</b> C      | reate        | 2            |       |
| Unit:1                   |                                      | ntroduction to Embedded Systems   |                    |              | 12 ho        | 11 PG |
|                          |                                      | embedded into a system-Components of Embedded   | d Syste            |              |              |       |
| (eHPC).                  | edded system des                     | igner- Battery Management-Embedded High-Per   | Torman             |              | ompu         | ung   |
| Unit:2                   | Ir                                   | ntroduction to PIC Microcontroller  | 97                 | /            | 12 ho        | mrs   |
| PIC 16F87<br>Organizatio | 7 – Features – I                     | Device overview and Architecture – WREG reg<br>- access bank – Status Register – Data types and | gister -<br>direct | - Me<br>ives | emory        |       |
| TT 1/ 2                  |                                      | Alite Hanne a Hill 59   |                    |              | 10 1         |       |
| Unit:3                   |                                      | PIC Programming   |                    |              | <u>12 ho</u> | urs   |
|                          |                                      | programming – Assembling and linking – Progra<br>architecture –Instruction set .                | m coun             | iter a       | nd           |       |
| Unit:4                   |                                      | PIC Peripherals   |                    |              | 11 ho        | nire  |
|                          | apture/ Compare                      | /PWM Module - MSSP: SPI - $I^2C$ - USART  | - Ana              | امع          |              |       |
|                          |                                      | ecial features – Interrupts – WDT– ADC, DAC   | 7 1110             |              |              | Bitur |
| Unit:5                   |                                      | PIC Application   |                    |              | 11 ho        | ours  |
|                          |                                      | g - Stepper motor- Ultrasonic interfacing- Tempera  | ature co           | ontro        | l- DC        |       |
| Motor Spee               | ed Control- LCD in                   | nterface - Keyboard interface-memory interface.   |                    |              |              |       |
| Unit:6                   |                                      | Contemporary Issues   |                    |              | 2 ho         | ours  |
| Servomotor               | control in robots-                   | IoT devices- case study accelerometer interfacing   | ·                  |              |              |       |
|                          |                                      | Total Lecture hour  | 5                  |              | 60 ha        | urs   |

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| Те | ext Book(s)   |
|----|---|
| 1  | Raj Kamal "Embedded Systems Design", TMH. 3 rd Edition 2009                         |
| 2  | Muhammed Ali Mazidi, "PIC microcontroller and Embedded Systems Using assembly and C |
|    | for PIC 18", Pearson Education .2008  |
|    |   |
| Re | eference Books  |
| 1  | John B Peatman, "Design with PIC microcontrollers", Pearson Education 2010          |
| 2  | Vahid ,"Embedded System Design: A Unified Hardware / Software Introduction", Wiley, |
|    | 2014.   |
|    |   |

#### Related Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]

- 1 https://nptel.ac.in/courses/108/102/108102045/
- 2 https://nptel.ac.in/courses/117/104/117104072/
- 3 http://nptel.unipune.ac.in/LocalG/listLectures.php?cid=1d964ef8dd297d44&bid=c6c45d988f6 70c72

Course Designed By: Dr.S.Rathinavel

| Mapping with Programme Outcomes |     |     |     |     |     |     |     |     |     |      |
|---------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|
| COs                             | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |
| CO1                             | M   | S   | S   | S   | S   | S   | S   | S   | S   | S    |
| CO2                             | S   | S   | S   | S   | S   | S   | M   | S   | S   | S    |
| CO3                             | S   | S   | S   | S   | S   | S   | S   | S   | S   | S    |

| Course code   | 13D                | ELECTRO MAGNETIC THEORY   | L             | Т             | Р            | С            |  |  |
|---|--------------------|---|---------------|---------------|--------------|--------------|--|--|
| Core/Elective/S   | upportive          | Core  | 4             | 0             | 0            | 4            |  |  |
| Pre-requisite   |                    | Basic mathematics   | Sylla<br>Vers |               | 2021         | -22          |  |  |
| Course Object   |                    |   |               |               |              |              |  |  |
| The main objec  | tives of this      | s course are to:  |               |               |              |              |  |  |
| 1. Understan  | d the basic        | mathematical operators required for electromagne  | tic pro       | blem          | solvi        | ng.          |  |  |
|   |                    | ncept of static and dynamic charges.  |               |               |              |              |  |  |
|   |                    | on the concept of wave equation and radiation ph  |               |               |              |              |  |  |
|   |                    | art measurement equipment's and facilities used f   | or ante       | enna          | resear       | ch.          |  |  |
| Expected Cour   |                    |   |               |               |              |              |  |  |
|   |                    | tion of the course, student will be able to:  |               |               | 1            | 120          |  |  |
| 1 Understanding the basic mathematics applicable to electromagnetic theory K2 |                    |   |               |               |              |              |  |  |
|   |                    | ge gained in analyzing advanced electromagnetic per period of the period of the period of the period and absence of the period and absence of the period of |               |               |              | K5<br>K2     |  |  |
|   | gnetic fields      |   | ciccu         | ic            |              | NZ           |  |  |
| L L   |                    | thusiasm by knowing the state of the art instrumen  | ts and        |               | 1            | K6           |  |  |
|   |                    | ntenna fabrication and measurements.  |               |               |              |              |  |  |
| K1 - Rememb   | er; <b>K2 -</b> Ur | <mark>1de</mark> rstand; <b>K3</b> - Apply; <b>K4</b> - An <mark>alyze; K5 - Evalua</mark>  | te; K6        | <b>ó</b> - Cr | eate         |              |  |  |
|   | -3                 |   |               |               |              |              |  |  |
| Unit:1  | 1975               | Fundamental Mathematics   | T             | 1             | <u>10 ho</u> |              |  |  |
|   |                    | rations, Coordinate systems and transformation,   |               |               |              |              |  |  |
|   |                    | calar field, Divergence of a vector field, Divergen   |               |               | , Curl       | of a         |  |  |
| vector field, S   | tokes's the        | orem, Physical Interpretation of Gradient, diverger   | nt and        | curl.         |              |              |  |  |
| Unit:2  |                    | Fl. A. A.   |               |               | 12 ho        |              |  |  |
|   | and field          | Electrostatics<br>ds, Postulates of electrostatics, Conductor, Insula   | ator          | Friba         |              |              |  |  |
|   |                    | ric flux, Electrostatic induction, dielectrics, Elec  |               |               |              |              |  |  |
|   |                    | ulomb's law, Gauss's law and applications, Ele  |               |               |              |              |  |  |
|   |                    | place's equations, Uniqueness theorem, Electrost  |               |               |              |              |  |  |
| problems.   | 200                |   | 7             |               |              |              |  |  |
| •   |                    | Coimbatore  | 1             |               |              |              |  |  |
| Unit:3  |                    | Magnetostatics  |               |               | 12 ho        |              |  |  |
|   |                    | t density and ohms law, Electromotive force and k   |               |               | -            |              |  |  |
| -   | -                  | nd Kirchhoff's current law, Biot-Savart Law, G  |               |               | Amp          |              |  |  |
| -   | -                  | oundary conditions for magnetostatic fields, Mag  | netic e       | energ         | y, En        | ergy         |  |  |
| stored in mag   | ietic field.       |   |               |               |              |              |  |  |
| Unit:4  |                    | Electromagnetic Fields And Waves  |               |               | 12 ho        | nurs         |  |  |
|   | v of electro       | magnetic induction, Inconsistency of Amperes  | aw N          | laxw          |              | <u>jui s</u> |  |  |
| •   |                    | differential forms, conduction current and displace   |               |               |              |              |  |  |
|   |                    | Electromagnetic fields, Helmholtz wave equation   |               |               |              | tion.        |  |  |
| •   |                    | erflow in EM field.   | ,             | г             |              | ,            |  |  |
|   | <b>^</b>           |   |               |               |              |              |  |  |
| Unit:5  |                    | Antennas & Radiating Systems  |               |               | 12 ho        |              |  |  |
|   |                    | Antenna parameters, Hertz dipole, Wire anten  |               | -             |              |              |  |  |
|   |                    | arrays. Printed microstrip antennas: Basic charact  |               |               |              |              |  |  |
|   | graphy, Int        | roduction to EMI and EMC, Anechoic chamb  | er and        | 1 RF          | Netw         | vork         |  |  |
| Analyzer.   |                    |   |               |               |              |              |  |  |

| Uı | nit:6       | Contemporary Issues  | 2 hours             |
|----|-------------|--|---------------------|
| Ho | orn Antenn  | as, Specific Absorption rate   |                     |
|    |             |  | 1                   |
|    |             | Total Lecture hours  | 60 hours            |
| Τe | ext Book(s) |  |                     |
| 1  | ^           | of Electromagnetics, M.N.O.Sadiku & SV Kulkarni, Oxford Un                   | ÷                   |
| 2  | Electroma   | agnetic Field Theory and Transmission Lines, G. S. N. Raju, Pea              | rson Education,2006 |
| 3  | Electroma   | agnetic Waves, R. K. Shevgaonkar, McGraw Hill, 2017.                         |                     |
| 4  | Electroma   | agnetic Field Theory, U A. Bakshi & A V Bakshi, Technical pul                | blication, 2009.    |
|    |             |  |                     |
| Re | eference B  |  |                     |
| 1  |             | ng Electromagnetics, Haytt, McGraw-Hill Education,2001                       |                     |
| 2  |             | Wave Electromagnetics, D. K. Cheng, Pearson, 2001.                           |                     |
| 3  |             | ng Electromagnetics, N. Ida, Springer, 2000.                                 |                     |
| 4  | Introducti  | on to Electrodynamics, J. Griffiths, PHI, 1999.                              |                     |
| 5  | Antenna     | Theory: Analysis and Design, C. A. Balanis, John Wiley, 2005                 |                     |
|    |             |  |                     |
| Re | elated Onli | ine Conte <mark>nts [M</mark> OOC, SWAYAM, NPTEL, Websites etc.]             |                     |
| 1  | https://w   | ww.fcc.g <mark>ov/con</mark> sumers/guides/specific-absorption-rate-sar-cell | -phones-what-it-    |
|    | means-y     |  |                     |
| 2  |             | ptel <mark>.ac.in/cou</mark> rses/108/101/108101092/                         |                     |
| 3  | https://n   | ptel.ac.in/courses/108/105/108105114/  |                     |
|    |             |  |                     |
| Co | ourse Desig | ned By: Dr.Sujith Raman  |                     |
|    |             | Tropic good or it  |                     |

| Mappin     | Mapping with Programme Outcomes |     |     |     |     |     |            |     |      |             |  |
|------------|---------------------------------|-----|-----|-----|-----|-----|------------|-----|------|-------------|--|
| COs        | <b>PO1</b>                      | PO2 | PO3 | PO4 | PO5 | PO6 | <b>PO7</b> | PO8 | PO9  | <b>PO10</b> |  |
| CO1        | S                               | S   | L   | S   | L   | L   | L          | L   | SL / | L           |  |
| <b>CO2</b> | S                               | S   | L   | M   | L   | L   | L          | L   | 2 L/ | L           |  |
| CO3        | S                               | S   | L   | M   | L   | L   | L          | M   | M    | L           |  |
| CO4        | S                               | Sog | L   | S   | M   | L   | L          | S   | S    | L           |  |

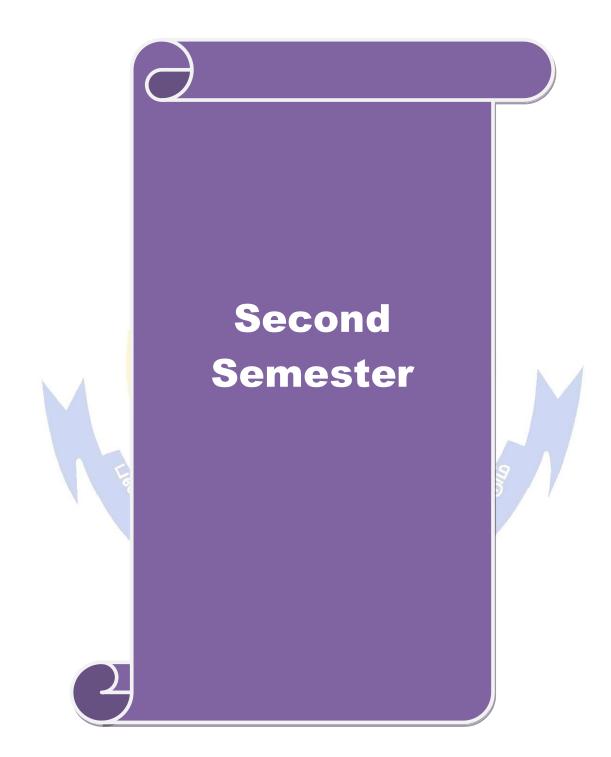


| code   | 13P   | PIC N  | MICROCON<br>LABORAT                          |                             | -                     | L<br>0           | Т<br>0  | P<br>3 | <u>C</u><br>3 |
|--|---|--|--|-----------------------------|-----------------------|------------------|---------|--------|---------------|
| Pre-requ   | isite   | Basic C Lan  | guage  |                             | e<br>N                | Syllab<br>Versio | us<br>n | 2021   | -22           |
| Course Ob  | ojectives:  | I  |  |                             |                       |                  | 1       |        |               |
|  |   | s course are to:   |  |                             |                       |                  |         |        |               |
|  |   | PIC microconti   |  |                             |                       |                  |         |        |               |
|  |   | nctions of peripl  |  |                             | r                     |                  |         |        |               |
| 3. Sol   | ve the real worl  | d problems thro  | ough embedde                                 | d System.                   |                       |                  |         |        |               |
| Expected (   | Course Outcor   | nes•   |  |                             |                       |                  |         |        |               |
|  |   | etion of the cou   | rse, student wi                              | ill be able to:             |                       |                  |         |        |               |
|  |   | ning knowledg  |  |                             |                       |                  |         | K3     | 3             |
|  | <u> </u>  | apability of em  |  | mming                       |                       |                  |         | K5     | 5             |
| 3 Desig  | gn embedded <mark>sy</mark>   | vstem to meet or   | ut industry neo                              | eds.                        |                       |                  |         | Ke     | 5             |
| <b>K1</b> - Rem  | ember; K2 <mark>- U</mark>  | nderstand; K3 -  | Apply; K4 -                                  | Anal <mark>yze; K5 -</mark> | <mark>Eva</mark> luat | e; K6 ·          | - Cre   | eate   |               |
|  |   |  |  | 10                          |                       |                  |         |        |               |
| 1 1 1 0  | D interface for   | List OF Exper  | iments (Any                                  | 12 experiment               | its)                  |                  |         |        |               |
|  |   |  | Mes K  | NA I                        |                       |                  |         |        |               |
|  | rasonic interfac  | e for an anning  |  |                             |                       |                  |         |        |               |
|  |   |  |  |                             |                       |                  |         |        |               |
| 3. DA  | C inter <mark>face for</mark>   | an application   |  |                             |                       |                  | N.      |        | (             |
| 3. DA<br>4. AD   | C inter <mark>face for</mark><br>C inter <mark>face for</mark>  | an application<br>an application.  |  |                             |                       |                  |         |        | 1             |
| <ol> <li>3. DA</li> <li>4. AD</li> <li>5. Ser</li> </ol>   | C inter <mark>face for</mark><br>C interface for<br>vomotor interfa   | an application<br>an application.<br>cing for an app   | lication                                     |                             |                       |                  |         |        | (             |
| <ol> <li>3. DA</li> <li>4. AD</li> <li>5. Ser</li> <li>6. Step</li> </ol>  | C inter <mark>face for</mark><br>C interface for<br>vomoto <mark>r interfa</mark><br>pper motor <mark>con</mark>  | an application<br>an application.<br>coing for an app<br>trol for an appli   | lication                                     |                             |                       |                  |         |        |               |
| <ol> <li>3. DA</li> <li>4. AD</li> <li>5. Ser</li> <li>6. Step</li> <li>7. Spece</li> </ol>  | C interface for<br>C interface for<br>vomotor interfa<br>pper motor con<br>eed control of D   | an application<br>an application.<br>cing for an app<br>trol for an appli<br>C motor using   | lication                                     |                             |                       |                  |         |        |               |
| <ol> <li>3. DA</li> <li>4. AD</li> <li>5. Ser</li> <li>6. Step</li> <li>7. Spection</li> <li>8. 4X4</li> </ol>   | C interface for<br>C interface for<br>vomotor interfa<br>pper motor con<br>ed control of D<br>4 matrix Keypa  | an application<br>an application.<br>cong for an app<br>trol for an appli<br>C motor using<br>d interfacing  | lication<br>cation<br>PWM                    |                             |                       | 9                |         |        | (             |
| <ol> <li>J. DA</li> <li>4. AD</li> <li>5. Ser</li> <li>6. Step</li> <li>7. Spection</li> <li>8. 4X4</li> <li>9. 5 cl</li> </ol>  | C interface for<br>C interface for<br>vomotor interfa<br>pper motor con<br>eed control of D<br>4 matrix Keypa<br>hannel blue too  | an application<br>an application.<br>cong for an application<br>for an application<br>C motor using<br>d interfacing<br>th system for co   | lication<br>cation<br>PWM                    | ce                          | 19.911                | 6)16             |         |        |               |
| <ol> <li>J. DA</li> <li>4. AD</li> <li>5. Ser</li> <li>6. Step</li> <li>7. Spec</li> <li>8. 4X4</li> <li>9. 5 cl</li> <li>10. SPI</li> </ol>   | C interface for<br>C interface for<br>vomotor interfa<br>pper motor con<br>ed control of D<br>4 matrix Keypa<br>hannel blue too   | an application<br>an application.<br>using for an applitrol for an appli<br>C motor using<br>d interfacing<br>th system for con  | lication<br>cation<br>PWM                    | ce                          | 19971                 | (Glub            |         |        |               |
| <ol> <li>J. DA</li> <li>4. AD</li> <li>5. Ser</li> <li>6. Step</li> <li>7. Spection</li> <li>8. 4X4</li> <li>9. 5 cl</li> <li>10. SPI</li> <li>11. UA</li> </ol>   | C interface for<br>C interface for<br>vomotor interfa<br>pper motor con<br>ed control of D<br>4 matrix Keypa<br>hannel blue too<br>communicatio<br>RT communica   | an application<br>an application.<br>ucing for an applitrol for an appli<br>C motor using 1<br>d interfacing<br>th system for conn<br>tion   | lication<br>cation<br>PWM                    | ce                          | 155III                | (Olio            |         |        | 1             |
| <ol> <li>J. DA</li> <li>4. AD</li> <li>5. Ser</li> <li>6. Step</li> <li>7. Spe</li> <li>8. 4X4</li> <li>9. 5 cl</li> <li>10. SPI</li> <li>11. UA</li> <li>12. I2C</li> </ol>   | C interface for<br>C interface for<br>vomotor interfa<br>pper motor con<br>ed control of D<br>4 matrix Keypa<br>hannel blue too<br>communicatio<br>RT communicatio  | an application<br>an application.<br>using for an applitrol for an appli<br>C motor using<br>d interfacing<br>th system for con<br>n<br>ution  | lication<br>cation<br>PWM                    | ce                          | -15SIT                | 97(9),           |         |        |               |
| <ol> <li>J. DA</li> <li>AD</li> <li>Ser</li> <li>Ser</li> <li>Step</li> <li>Spe</li> <li>4X4</li> <li>Solution</li> <li>SPI</li> <li>UA</li> <li>SPI</li> <li>UA</li> <li>UA</li> <li>UA</li> <li>UA</li> <li>CC</li> </ol>  | C interface for<br>C interface for<br>vomotor interface<br>pper motor con<br>ed control of D<br>4 matrix Keypa<br>hannel blue too<br>communicatio<br>RT communicatio<br>P module for ge                                   | an application<br>an application.<br>using for an applited<br>for an applited<br>C motor using<br>d interfacing<br>th system for connu-<br>tion<br>on<br>enerating delay   | lication<br>cation<br>PWM<br>ontrolling devi | INER                        | 1597m.                | (B)tb            |         |        |               |
| <ol> <li>J. DA</li> <li>AD</li> <li>Ser</li> <li>Step</li> <li>Step</li> <li>Spectrum</li> <li>Spectrum&lt;</li></ol>  | C interface for<br>C interface for<br>vomotor interfa<br>pper motor con<br>ed control of D<br>4 matrix Keypa<br>hannel blue too<br>Communicatio<br>RT communicatio<br>P module for goner1 module for                      | an application<br>an application.<br>cing for an application<br>trol for an appli<br>C motor using<br>d interfacing<br>th system for con<br>this<br>n<br>ation<br>on<br>enerating delay<br>generating del  | lication<br>cation<br>PWM<br>ontrolling devi | INER                        | 155IT                 | (Glub            |         |        |               |
| <ol> <li>J. DA</li> <li>AD</li> <li>Ser</li> <li>Step</li> <li>Step</li> <li>Spe</li> <li>4X4</li> <li>Solution</li> <li>SPI</li> <li>UA</li> <li>SPI</li> <li< td=""><td>C interface for<br/>C interface for<br/>vomotor interface<br/>pper motor con<br/>ed control of D<br/>4 matrix Keypa<br/>hannel blue too<br/>communicatio<br/>RT communicatio<br/>P module for gener1 module for<br/>ltiplexed seven</td><th>an application<br/>an application.<br/>using for an applited<br/>for an applited<br/>of app</th><th>lication<br/>cation<br/>PWM<br/>ontrolling devi</th><td>UNE<br/>LUITAA</td><td>1507n</td><th>616</th><th></th><th></th><td></td></li<></ol> | C interface for<br>C interface for<br>vomotor interface<br>pper motor con<br>ed control of D<br>4 matrix Keypa<br>hannel blue too<br>communicatio<br>RT communicatio<br>P module for gener1 module for<br>ltiplexed seven | an application<br>an application.<br>using for an applited<br>for an applited<br>of app | lication<br>cation<br>PWM<br>ontrolling devi | UNE<br>LUITAA               | 1507n                 | 616              |         |        |               |
| <ol> <li>J. DA</li> <li>AD</li> <li>Ser</li> <li>Ser</li> <li>Step</li> <li>Spe</li> <li>4X4</li> <li>Solution</li> <li>SPI</li> <li>UA</li> <li>SPI</li> <li>UA</li> <li>UA</li> <li>SPI</li> <li>UA</li> <li>UA</li> <li>SPI</li> <li>S</li></ol>   | C interface for<br>C interface for<br>vomotor interface<br>pper motor con<br>ed control of D<br>4 matrix Keypa<br>hannel blue too<br>communicatio<br>RT communicatio<br>P module for gener1 module for<br>ltiplexed seven | an application<br>an application.<br>cing for an applitrol for an applitrol for an applitrol for an applitrol for motor using<br>d interfacing<br>th system for connuction<br>ation<br>on<br>enerating delay<br>generating delay   | lication<br>cation<br>PWM<br>ontrolling devi | UNE<br>LUITAA               | Color                 | faci             | oad.    |        |               |
| <ol> <li>J. DA</li> <li>AD</li> <li>Ser</li> <li>Ser</li> <li>Step</li> <li>Spe</li> <li>4X4</li> <li>Solution</li> <li>SPI</li> <li>UA</li> <li>SPI</li> <li>UA</li> <li>UA</li> <li>SPI</li> <li>UA</li> <li>UA</li> <li>SPI</li> <li>S</li></ol>   | C interface for<br>C interface for<br>vomotor interface<br>pper motor con<br>ed control of D<br>4 matrix Keypa<br>hannel blue too<br>communicatio<br>RT communicatio<br>P module for gener1 module for<br>ltiplexed seven | an application<br>an application.<br>using for an applited<br>for an applited<br>of app | lication<br>cation<br>PWM<br>ontrolling devi | UNE<br>LUITAA               | -                     |                  | oad.    | 45 h   |               |

| Mapping with Programme Outcomes |     |     |     |     |     |     |            |     |     |      |
|---------------------------------|-----|-----|-----|-----|-----|-----|------------|-----|-----|------|
| COs                             | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | <b>PO7</b> | PO8 | PO9 | PO10 |
| CO1                             | M   | S   | S   | S   | S   | S   | S          | S   | М   | S    |
| CO2                             | S   | S   | S   | M   | S   | S   | M          | S   | S   | S    |
| CO3                             | S   | S   | S   | М   | S   | S   | М          | S   | S   | S    |

| Course code   | 13Q                                   | INSTRUMENTAT                                       | <b>FION LABORATORY</b>                              | L                      | T        | P<br>3  | C              |
|---|---------------------------------------|--|---|------------------------|----------|---------|----------------|
| Pre-requisite   | 100                                   | Knowledge gaining a                                |   |                        | Syllabus |         | <u>3</u><br>22 |
| <b>Course Object</b>                                  |                                       |  |   |                        |          |         |                |
| The main object                                       | tives of thi                          | course are to:                                     |   |                        |          |         |                |
| types of tra<br>2. To make th<br>transducers          | nsducers.<br>ne students<br>s.        |  | s of measurement and op<br>and dynamic characterist |                        |          |         | s of           |
| 5. 10 make ti   |                                       |  |   |                        |          |         |                |
| Expected Cour   | se Outcor                             | es:  | 2512  |                        |          |         |                |
|   |                                       | tion of the course, stud                           | ent will be able to:                                |                        |          |         |                |
|   |                                       | pts of measurement, e                              |   |                        |          | K2      |                |
|   |                                       | •  | ristics of measuring instr                          | uments.                |          | K2      |                |
|   |                                       | it the principle of oper<br>apacitance and inducta | ation and characteristics<br>nce transducers.       | of differ              | ent      | K3      |                |
| 4 Acquire k   | no <mark>wledge</mark>                | f analyzing different s                            | tages of signal conditioni                          | <mark>ng u</mark> nits |          | K4      |                |
| K1 - Remember   |                                       |  | K4 - Analyze; K5 - Eval                             |                        | 6 - Cı   | reate   |                |
|   |                                       |  | <b>NTS</b> (any 12 experiments                      | )                      |          |         |                |
|   |                                       | ment using LVDT.                                   | ELL.  |                        |          |         |                |
| <ol> <li>Characteris</li> <li>Study of The</li> </ol> |                                       | le Compensation.                                   |   |                        |          |         |                |
|   |                                       | inearization transmitte                            | rdesign   |                        |          |         |                |
| 5. Pressure C   |                                       |  | i design.   |                        |          |         |                |
|   |                                       | ow process using Con                               | npact Flow Control Unit                             | 23                     |          |         |                |
|   |                                       |  | Non – inverting Op-amp                              | configu                | ratio    | n.      |                |
|   |                                       |  | Difference amplifier usi                            |                        |          |         |                |
| •   | · · · · · · · · · · · · · · · · · · · | tation of Instrumentation                          | -   |                        | 1        |         |                |
| 10. Design of   | V-F conve                             | ter.   | batore  |                        |          |         |                |
| 11. Design of l                                       |                                       |  | intell  |                        |          |         |                |
|   |                                       |  | nitter with zero elevation                          | and zer                | o sup    | pressio | n.             |
| 0   | 0                                     | ircuit for any resistive                           |   |                        |          |         |                |
| -   | -                                     | ircuit for optical encod                           |   |                        |          |         |                |
| -   |                                       | ller for mathematically                            | -   | D                      |          |         |                |
| 16. Design and  | I implemen                            | tation of ON/OFF Con                               | troller for the Temperatu                           |                        | ss.      |         |                |
|   |                                       |  | <b>Total Practical hour</b>                         | *S                     |          | 45 ho   | urs            |
| Course Design   | ed By: Dr.                            | Azha. Periasamy                                    |   |                        |          |         |                |

|     | Mapping with Programme Outcomes |     |     |     |     |     |     |            |     |      |
|-----|---------------------------------|-----|-----|-----|-----|-----|-----|------------|-----|------|
| COs | PO1                             | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | <b>PO8</b> | PO9 | PO10 |
| CO1 | L                               | S   | L   | S   | S   | S   | S   | S          | S   | S    |
| CO2 | L                               | S   | L   | S   | S   | S   | S   | S          | S   | S    |
| CO3 | L                               | S   | L   | S   | S   | S   | S   | S          | S   | S    |
| CO4 | L                               | S   | L   | S   | S   | S   | S   | S          | S   | S    |



| Course code           | 23A                 | CONTROL SYSTEMS   | L              | T             | Р        | C            |
|-----------------------|---------------------|---|----------------|---------------|----------|--------------|
| Core/Elective/S       | upportive           | Core  | 4              | 0             | 0        | 4            |
| Pre-requisite         |                     | Mathematics knowledge is Essential  | Sylla<br>Versi |               | 2021-    | 22           |
| <b>Course Object</b>  | tives:              |   | 1              | I             |          |              |
| The main object       |                     |   |                |               |          |              |
|                       |                     | nts of control system and their modelling using various                         |                |               |          |              |
| 2. Introduc<br>system |                     | or analyzing the time response, the frequency response a                        | and the        | e stab        | ility of |              |
| -                     |                     | ariable analysis method.  |                |               |          |              |
| 0. macaac             | e me state v        |   |                |               |          |              |
| Expected Cou          | rse Outcon          | nes:  |                |               |          |              |
| On the success        | sful comple         | etion of the course, student will be able to:                                   |                |               |          |              |
|                       |                     | and frequency domain analysis of control systems requi                          | red for        | r             | K4       |              |
| stability an          |                     |   |                |               | TZ 4     |              |
|                       | -                   | ion technique that can be used to stabilize control system                      |                | <u> </u>      | K4       |              |
| KI - Kememo           | er; <b>K</b> 2 - UI | nderstand; K3 - Apply; K4 - Analyze; K5 - Evalua                                | ile; N         | <b>) -</b> CI | eale     |              |
| Unit:1                | - 6                 | Systems and Their Representation  |                |               | 12 ho    | urs          |
|                       | in control          | systems – Open and closed loop systems – Math                                   | emati          | cal m         | -        |              |
|                       |                     | rical analogy of mechanical and thermal systems –                               |                |               |          | -            |
| <b>v</b> 1            |                     | rvomotors – Block diagram reduction techniques –                                |                |               |          |              |
|                       | E                   |   | Ŭ              |               |          |              |
| Unit:2                |                     | Analyze of Time Response  |                |               | 12 ho    |              |
| _                     |                     | lomain specifications – Types of test input – I                                 |                |               |          |              |
| -                     |                     | nts – Generalized error series – Steady state error                             | – P, P         | PI, PI        | D mod    | es of        |
| feedback contro       | ol.                 |   | 19             |               |          |              |
| Unit:3                | 2                   | Analyze of European Descent   |                | -/            | 12 ha    |              |
|                       | nonco D             | Analyze of Frequency Response<br>and plot – Polar plot – Constant M an N circle |                | Jiaho         | 12 ho    |              |
| 1 4                   | A \                 | loop response from open loop response – Correl                                  |                |               |          | r <b>ı</b> — |
|                       |                     | ne domain specifications  | unon           | 0000          | con      |              |
| 1 2                   |                     | a altering with a   |                |               |          |              |
| Unit:4                |                     | Stability of Control System   |                |               | 12 ho    | ours         |
| Characteristics       | equation -          | Location of roots in S plane for stability - Rout                               | th Hu          | rwitz         | criteri  | on –         |
| Root locus con        | struction –         | Effect of pole, zero addition - Gain margin and pl                              | nase n         | nargi         | n – Ny   | quist        |
| stability criterio    | on.                 |   |                | -             | -        | -            |
| -                     |                     |   |                |               |          |              |
| Unit:5                |                     | Compensator Design  |                |               | 10 ho    | urs          |
| Performance c         | riteria- Fre        | equency response- Lag Compensator- lead Co                                      | mper           | isator        | - lag-   | lead         |
| Compensator-          | Compensat           | for design using bode plots.  |                |               |          |              |
| Unit:6                |                     | Contemporary Issues   |                |               | 2 ho     | ours         |
|                       | s for indust        | rial process applications(any two applications)                                 | - I            |               |          |              |
|                       |                     | Total Lecture hours   |                |               | 60 ha    | ours         |
|                       |                     |   |                |               |          |              |

AAL Col

| Te | xt Book(s)   |
|----|--|
| 1  | Nagrath, I.J., and Gopal, M., "Control systems Engineering", Wiley Eastern                     |
|    | Ltd., 2012.  |
| 2  | Katsuhiko Ogata, "Modern control Engineering", Fourth Edition, Pearson Education, First Indian |
|    | Reprint 2015.  |

#### **Reference Books**

- 1 A. Nagoor Kani, "Control Systems", Second Edition, RBA Publications 2014.
- 2 Richard C.Dorf and Robert H.Bishop, "Modern control systems", Addison Wesley, Eight Edition 2016.

#### Related Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]

- 1 <u>https://nptel.ac.in/courses/107/106/107106081/</u>
- 2 <u>https://nptel.ac.in/courses/108/106/108106098/</u>
- 3 <u>https://nptel.ac.in/courses/108/101/108101037/</u>

Course Designed By: Dr.J.Vijayakumar

| Mapping with Programme Outcomes |     |     |     |     |     |     |     |     |     |      |  |
|---------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|--|
| COs                             | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |  |
| CO1                             | S   | L   | S   | S   | L   | М   | S   | M   | S   | S    |  |
| CO2                             | S   | L   | M   | S   | L   | S   | S   | S   | S   | S    |  |

| Coursecode             | 23B                                 |        | ARM PROCESSOR  | L                 | Т      | P       | С      |
|------------------------|-------------------------------------|--------|--|-------------------|--------|---------|--------|
| Core/Elective/S        | upportive                           | Co     | re   | 4                 | 0      | 0       | 4      |
| Pre-requisite          |                                     | Bas    | ic 8 bit processor knowledge                             | Sylla<br>Versi    |        | 2021-22 |        |
| <b>Course Objectiv</b> |                                     |        |  |                   |        |         |        |
| The main objecti       |                                     |        |  |                   |        |         |        |
|                        |                                     |        | and overview of ARM7 Processor.                          |                   |        |         |        |
|                        |                                     | -      | in ARM7 processor<br>ith the usage of peripherals in ARM | rocessor          |        |         |        |
| Expected Cours         |                                     |        | ith the usage of peripherals in ARM                      | processor         |        |         |        |
| A                      |                                     |        | e course, student will be able to:                       |                   |        |         |        |
|                        | <u>.</u>                            |        | ocessor in application perspective.                      |                   |        | K.      | 5      |
| <u>^</u>               | -                                   | -      | d for industrial application                             |                   |        | K       | 5      |
| K1 - Remember          | r; <b>K2</b> - Und <mark>e</mark> r | rstand | ; <b>K3</b> - Apply; <b>K4</b> - Analyze; <b>K5</b> - Ev | valuate; <b>K</b> | 6 - Ci | reate   |        |
| <b>T</b> T •/ <b>4</b> |                                     | _ 61   |  |                   | 1      | 10.1    |        |
| Unit:1                 |                                     | Care   | Introduction to ARM                                      | mation Di         |        | 12 h    |        |
|                        |                                     |        | - Pin Diagram - Architecture - Inst                      |                   | -      |         | •      |
|                        | -                                   |        | - ARM State and Thumb State Reg                          | ister Set -       | Prog   | gram :  | Status |
| Registers, Safety      | and code en                         | crypti | on-Power dissipation.                                    |                   |        |         |        |
| Unit:2                 | 96                                  |        | Data Types and Signals                                   | <b>6</b> .        |        | 12 h    | ours   |
| Program"s Mode         | el <mark>– Memor</mark> y           |        | ats – Data Types – Exceptions – Int                      | errupt Lat        | encie  |         |        |
|                        |                                     |        | Addressing Signals – Address Timir                       |                   |        |         |        |
| Power-up Mode.         |                                     | 18.0   | Viceo Andre The T  | 1.                |        | 7       |        |
|                        |                                     | 1      |  |                   |        |         |        |
| Unit:3                 |                                     |        | sor and Debugging Techniques                             |                   |        | 12 ho   | ours   |
|                        |                                     |        | ce Signals – Pipeline Signals – Inter                    |                   |        | -       |        |
|                        |                                     |        | ned Instructions – Privileged Instru                     |                   | · · ·  |         |        |
| Debug Interface        | Signals – Ena                       | abling | and Disabling Embedded ICE – Cor                         | nmunicati         | on C   | hannel  | s.     |
| Unit:4                 |                                     | In     | troduction to LPC 2378                                   | <u>,</u>          |        | 11 h    | ours   |
|                        | eatures of LP                       |        | 8 – Block Diagram – Pin Description                      | n – Functio       | onal   |         |        |
|                        |                                     |        | - On-chip SRAM - Memory Map                              |                   |        |         |        |
|                        | y Controller                        | - Ger  | eral Purpose DMA Controller - Fas                        | t General         | Purp   | ose Pa  | rallel |
| I/O.                   |                                     |        | COATE TU ELEVIN  |                   |        |         |        |
| Unit:5                 |                                     |        | ARM Peripherals  |                   |        | 11 h    | ours   |
|                        | Interface – C                       | ANC    | Controller – ADC – DAC – UART –                          | SPI Serial        | I/O    |         |        |
|                        |                                     |        | llers – I2S Bus Serial I/O Controlle                     |                   |        |         |        |
|                        |                                     |        | dog Timer – R Ethernet – USB Inte                        |                   |        |         |        |
|                        |                                     |        | 1 I/O Controller – SSP – I2C Bus S                       |                   |        |         |        |
|                        | ontrollers Ge                       | eneral | Purpose 32-bit Timers/Counters – P                       | WM - W            | atchd  | log Ti  | mer –  |
| RTC.                   |                                     |        |  |                   |        |         |        |
| Unit:6                 |                                     |        | Contemporary Issues                                      |                   |        | 2 h     | ours   |
|                        | controlling d                       |        | s - ZigBee based monitoring devices                      | -wireless r       | odes   |         |        |
| processor              | ÷                                   |        |  |                   |        |         |        |
|                        |                                     |        | Total Lectur   | e hours           |        | 60 h    | ours   |

| Text Book(s) |
|--------------|
|--------------|

| 1 | David Seal, "ARM Architecture Reference Manual", Addison Wesley, 2 <sup>nd</sup> Edition, |  |
|---|---|--|
|   | 2000.   |  |

- 2 Steve Furber, "ARM System On-Chip Architecture", Addison Wesley, 2<sup>nd</sup> Edition, 2000.
- 3 Stuart A. Boyer: "SCADA-Supervisory Control and Data Acquisition", Instrument Society of America Publications, USA, 2011
- 4 David Bailey, Edwin Wright, Practical SCADA for industry, Newnes, 2010

#### **Reference Books**

- 1 ARM7TDMI-S Technical Reference Manual, 1999.
- 2 Larry D. Pyeatt , "Modern Assembly Language Programming with the ARM Processor", Newnes,2016.

#### Related Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]

- 1 <u>https://nptel.ac.in/courses/117/106/117106111/</u>
- 2 <u>https://nptel.ac.in/courses/106/105/106105193/</u>

Course Designed By: Dr. S. Rathinavel

| Mapping with Programme Outcomes |     |     |     |     |     |     |            |     |     |      |
|---------------------------------|-----|-----|-----|-----|-----|-----|------------|-----|-----|------|
| COs                             | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | <b>PO7</b> | PO8 | PO9 | PO10 |
| CO1                             | S   | S   | S   | S   | М   | M   | S          | S   | S   | S    |
| CO2                             | S   | S   | S   | S   | М   | S   | S          | S   | S   | S    |

\*S-Strong; M-Medium; L-Low

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பாத்திட வேச்

| <b>Course Code</b>  | 23C                | INTELLIGENT INSTRUMENTATION  | L         | Т     | Р       | С          |  |
|---|--------------------|--|-----------|-------|---------|------------|--|
| Core/Elective/S   |                    | Core   | 4         | 0     | 0       | 4          |  |
| Pre-requisite   |                    | Student with adequate knowledge on Basic   | Syllab    |       | 2021-   | <u>,</u> , |  |
| -   |                    | Computer Systems   | Versio    | n     | 2021-   |            |  |
| Course Object   |                    |  |           |       |         |            |  |
| The main object   |                    | s course are to:<br>about data acquisition and control an external                                     | maaguu    | ina   | davia   | o hu       |  |
|   | ng to a com        |  | measu     | mg    | uevic   | 5 Uy       |  |
|   | •                  | l conditioning and various processing tools.   |           |       |         |            |  |
|   | •                  | in designing virtual instruments for various in  | dustrial  | me    | asuren  | ients      |  |
| and appli   |                    |  |           |       |         |            |  |
| Expected Cou  |                    |  |           |       |         |            |  |
|   | •                  | etion of the course, student will be able to:  |           |       | K6      |            |  |
| 1 Design interfacing circuits to acquire real time data and process it using software |                    |  |           |       |         |            |  |
|   | terfacing c        | ircuits to acquire real time data and process it usin  | g         |       | K4      |            |  |
| software  | 6                  |  | 0         |       |         |            |  |
|   |                    | outfitted with hands-on knowledge in LabVIEW   |           |       | K5      |            |  |
| K1 - Rememb   | er; <b>K2 -</b> U1 | nderstand; K3 - Apply; K4 - Analyze; K5 - Evalua   | ate; K6   | - Cr  | eate    |            |  |
| Unit:1  |                    | Introduction   |           |       | 12 ho   |            |  |
|   | o Virtual II       | nstrumentation – Hardware and Software – Virtu   | al Instru | imei  |         |            |  |
|   |                    | n – Graphical System Design using LabVIEW  |           |       |         |            |  |
|   |                    |  |           | -     |         |            |  |
|   |                    | ng. Introduction to LabVIEW Software Environ   |           | · Fro | ont Pa  | nei:       |  |
| Control & Ind   | Icators – B        | lock diagram: Data types and Data Flow program   | nıng.     |       | 1       |            |  |
| Unit:2  |                    | Graphical Programming and LabVIEW  |           | - /   | 12 ho   |            |  |
|   | Is and sub         | VI – Case Structures - Loops: For Loop – Wh  | ile Loc   | n –   |         |            |  |
|   |                    | s – Feedback Nodes – Communication between   |           |       | 1       |            |  |
| and Graphs –  |                    |  |           | 100]  |         |            |  |
| una crapito   | <u></u>            | Coimbatore   | /         |       |         |            |  |
| Unit:3  |                    | Managing Files & Design Patterns   |           |       | 12 ho   | urs        |  |
| Implementing  | g file I/O :       | functions to read and write data to files - Bin  | ary File  | es –  | TDM     | S -        |  |
| sequential pro  | ogramming          | - Stata machine programming - Understandir   | ng and    | avoi  | iding 1 | race       |  |
| conditions – N  | Votifiers &        | Queues – Producer Consumer design patterns   |           |       |         |            |  |
| <b>T</b> T <b>1</b>   |                    |  |           |       |         |            |  |
| Unit:4  | ta aianal a        | PC Based Data Acquisition  |           | Daa   | 12 ho   |            |  |
|   |                    | onditioning – Sampling fundamentals, ADCs,   |           |       |         |            |  |
| • •   |                    | its - Single-ended and differential inputs - Digi<br>uisition interface requirements - Issues involved |           |       |         |            |  |
|   | -                  | f timer-counter and analog outputs on the universa   |           |       |         | Jala       |  |
| acquisition ca  | 145 - 086 0        | i inter-counter and analog outputs on the universa   | I DAU     | Jaru  | •       |            |  |
| Unit:5  | Anal               | ysis Tools in Virtual Instrumentation  |           |       | 10 ha   | nirs       |  |
|   |                    | ation – Control design and simulation toolkit – D  | ata Con   | ımu   |         |            |  |
|   |                    | processing using Vision Assistant Module – Intro   |           |       |         |            |  |
| NXG.  | P                  |  |           | -     |         |            |  |
|   |                    |  |           |       |         |            |  |

| Uni | it:6                   | Contemporary Issues  | 2 hours              |
|-----|------------------------|--|----------------------|
| Tar | nk level co            | ntrol using LabVIEW, Implementation of Mathematical equation                             | is in LabVIEW        |
|     |                        |  |                      |
|     |                        | Total Lecture hours  | 60 hours             |
| Tex | <mark>(t Book(s</mark> |  |                      |
| 1   | Jovitha                | Jerome, "Virtual Instrumentation Using LabVIEW", Eastern Eco                             | onomy Edition, PHI   |
|     | Learnin                | g private ltd, 2010.   |                      |
|     |                        |  |                      |
| Ref | ference B              |  |                      |
| 1.  |                        | .Wells & Jeffery Travis," Lab VIEW For everyone", Prentice                               | e Hall, Publication, |
|     | 2000                   |  |                      |
| 2.  | S.Gupta                | a and J.P.Gupta, "PC Interfacing for Data Acquisition and Proc                           | cess Control"        |
|     |                        | ent society of America, 1 <mark>994</mark>   |                      |
| 3.  |                        | James, PC Interfacing and Data Acquisition: Techniques for I                             | Measurement,         |
|     | Instrum                | entation and Control, Newnes, 2011.  |                      |
| 4.  | Robert                 | H.Bishop, "Learning with LabVIEW" Prentice Hall, 2013.                                   |                      |
|     |                        |  |                      |
| Rel | 1                      | ne Cont <mark>ents [M</mark> OOC, SWAYAM, NPTEL, Websites etc.]                          |                      |
| 1   | http://w               | ww.ni.c <mark>om/pdf</mark> /manuals/373427j.pdf   |                      |
| 2   |                        | rpub.com   |                      |
| 3   | http://ee              | ce-r <mark>esearch.un</mark> m.edu/jimp/415/labview/LV_Intro <mark>_Six_Hours.pdf</mark> |                      |
|     |                        |  | × 4                  |
| Cou | urse Desig             | ned By: Dr.K.G.Padmasine   |                      |

| Mapping with Programme Outcomes |     |     |     |     |     |     |     |     |     |             |
|---------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-------------|
| COs                             | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | <b>PO10</b> |
| CO1                             | M   | S   | M   | L   | L   | M   | M   | S   | S   | S           |
| <b>CO2</b>                      | M   | S   | М   | L   | L   | S   | M   | M   | S   | S           |
| CO3                             | S   | S   | S   | S   | S   | S   | S   | S   | S   | S           |

\*S-Strong; M-Medium; L-Low

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| Course<br>code      | 23D                   | <b>INTRODUCTION TO INDUSTRY 4.0</b>   | L              | Т      | Р        | С        |
|---------------------|-----------------------|---|----------------|--------|----------|----------|
|                     | e/Supportive          | Core  | 4              | 0      | 0        | 4        |
| Pre-requis          | ••                    | Basic mathematics and programming automation knowledge is Essential   | Sylla<br>Versi |        | 2021     | -22      |
| Course Obj          |                       |   |                |        |          |          |
|                     |                       | s course are to:  |                |        |          |          |
|                     |                       | ted learning techniques.  |                |        |          |          |
| 2. To stu           | idy the techniq       | ues of knowledge representation.  |                |        |          |          |
| Expected C          | Course Outcon         | nes:  |                |        |          |          |
|                     |                       | etion of the course, student will be able to:   |                |        |          |          |
| 1 Under             | stand the repre       | esentation of knowledge   |                |        | K2       | 2        |
|                     | stand machine ations. | e learning, AI and RPA techniques in developing   | real wo        | rld    | K2       | 2        |
|                     |                       | nderstand; K3 - Apply; K4 - Analyze; K5 - Evalu   | ate; K         | 6 - C1 | reate    |          |
| TT •4 4             |                       |   |                |        | 10 1     |          |
| Unit:1              | C                     | Industry 4.0  |                |        | 12 ho    |          |
|                     |                       | pting Industry 4.0 - Definition – Goals and   |                |        |          |          |
|                     |                       | 4.0 – Big Data – Artificial Intelligence (AI)   | – Indu         | strial | Interr   | net of   |
| Things - Cy         | ber Security –        | Cloud – Augmented Reality.  |                |        |          |          |
| Unit:2              | E                     | Machine Learning  |                |        | 12 h     | ours     |
|                     |                       | duction – Definition – Types of Machine Learn   |                |        |          |          |
|                     |                       | tent Learning – Algorithms for Machine Learnin<br>for Machine Learning - Applications areas of Ma   |                |        |          | ed by    |
| Unit:3              |                       | Artificial Intelligence   | 2              |        | 12 h     | ours     |
|                     |                       | What & Why? - History of AI - Foundations o |                |        |          |          |
|                     |                       | ifluences of AI - Application Domains and To  | ols - A        | ssoci  | ated     |          |
| Technologie         | es of AI - Futu       | re Prospects of AI - Challenges of AI   |                |        |          |          |
| Unit:4              |                       | Debatia Ducases Automation (DDA)  |                | 1      | 12 h     | 01116    |
|                     | ages Automati         | <b>Robotic Process Automation (RPA)</b><br>ion (RPA): Introduction to RPA – Need for auto   | motion         | Dr     |          |          |
|                     |                       |   |                |        | U        | unnig    |
|                     |                       | ts and Softbots – RPA architecture and process $\mathbf{r}$   | netnod         | ologi  | es -     |          |
| Industries b        | est suited for R      | RPA - Risks & Challenges with RPA.  |                |        |          |          |
| Unit:5              |                       | Applications and Tools of Industry 4.0  |                |        | 10 ho    | ours     |
|                     |                       | Ianufacturing – Healthcare – Education – Aer  | rospace        | and    |          |          |
| **                  |                       | tion and Logistics – Impact of Industry 4.0   |                |        |          |          |
| •                   |                       | eople. Tools for Artificial Intelligence, Big Da  |                | •      | -        |          |
| Business C          |                       |   | und            | Lau    | - i inui | <i>y</i> |
|                     |                       | ed Reality, IoT, Robotics.  |                |        |          |          |
| Virtual Real        |                       | ed Reality, IoT, Robotics.  |                |        | 2 h      | 01175    |
| Virtual Real Unit:6 | lity, Augmente        | ed Reality, IoT, Robotics.<br>Contemporary Issues   | Artifici       | al In  |          | ours     |
| Virtual Real Unit:6 | lity, Augmente        | ed Reality, IoT, Robotics.  | Artifici       | al In  |          |          |

| Те | ext Book(s)   |
|----|---|
| 1  | P. Kaliraj, T. Devi, Higher Education for Industry 4.0 and Transformation to Education 5.0, |
|    | 2020  |

#### **Reference Books**

- 1 Stuart J. Russell, Peter Norvig, "Artificial Intelligence A Modern Approach", Third Edition, Pearson Publishers, 2015
- 2 S.N. Sivanandam, S.N. Deepa, "Principles of Soft Computing", Second Edition, Wiley-India, 2007

#### Related Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]

- 1 https://nptel.ac.in/courses/106/105/106105195/
- 2 https://nptel.ac.in/courses/106/106/106106139/
- 3 https://nptel.ac.in/courses/106/105/106105077/
- 4 https://nptel.ac.in/courses/112/101/112101098/

Course Designed By: Dr.J.Vijayakumar

| Mappi | Mapping with Programme Outcomes |     |     |     |     |     |     |     |     |      |  |
|-------|---------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|------|--|
| COs   | PO1                             | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |  |
| CO1   | S                               | S   | S   | S   | S   | M   | M   | S   | S   | S    |  |
| CO2   | S                               | S   | S   | S   | S   | S   | М   | М   | S   | S    |  |

\*S-Strong; M-Medium; L-Low

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| Course<br>code | 23P  | ARM PROCESSO                              | R LABORATORY           | L<br>0         | T<br>0        | P<br>3  | C<br>3 |
|----------------|--|---|------------------------|----------------|---------------|---------|--------|
| Pre-requi      | isite                                      | Basic C Language                          |                        | Sylla<br>Versi |               | 2021-22 |        |
| Course Ob      | jectives:                                  |   |                        |                | I             |         |        |
| The main c     | bjectives of thi                           | s course are to:                          |                        |                |               |         |        |
| 1. Wri         | te programs in                             | ARM Processor.                            |                        |                |               |         |        |
| 2. Uno         | lerstand the fur                           | ctions of peripherals in A                | ARM Processor.         |                |               |         |        |
| 3. Sol         | ve the real wor                            | d problems through 32-bi                  | it processor.          |                |               |         |        |
| Expected (     | Course Outcor                              | ies:                                      |                        |                |               |         |        |
|                |  | tion of the course, studer                | nt will be able to:    |                |               |         |        |
|                | <u> </u>                                   | on ARM Processor.                         |                        |                |               | K4      |        |
|                |  | pability in ARM Process                   |                        |                |               | K.      |        |
|                |  | d embedded system desi                    |                        |                |               | K       | 5      |
| KI - Rem       | ember; $\mathbf{K}\mathbf{Z} - \mathbf{U}$ | derstand; K3 - Apply; K                   | 4 - Analyze; K5 - Eval | uate; K        | <b>)</b> - Cr | eate    |        |
|                |  | List of Experiments (A                    | ny 12 avravimanta)     |                |               |         |        |
| 1. Ten         | anaratura contr                            | List of Experiments (A oller application. | iny 12 experiments)    |                |               |         |        |
|                | -  | nd interrupt latency                      | R YA P                 |                |               |         |        |
|                |  | r an application                          |                        |                |               |         |        |
|                |  | e for an application.                     |                        |                |               |         |        |
|                | C interface for                            |   | 223115                 |                |               |         |        |
|                |  | rface for an application.                 |                        |                |               |         |        |
|                |  | cing for an application                   |                        |                |               |         |        |
|                |  | rol for an application                    | 2/5                    |                |               |         |        |
|                |  | C motor using PWM                         | 251                    | 23             |               |         |        |
|                | 4 matrix Keypa                             |   |                        | S              |               |         |        |
|                | communicatio                               | <b>U</b>                                  |                        | 8              |               |         |        |
|                | RT communication                           |   | 6.9                    |                |               |         |        |
|                | ne delay utility                           | 5/5 A                                     | 91                     |                |               |         |        |
|                | ary encoder int                            | erfacing                                  | யாதது                  |                |               |         |        |
|                | •  | i node for monitoring de                  | vices                  |                |               |         |        |
| 10.215         |  | CATE TO                                   |                        |                |               |         |        |
|                |  |   | <b>Total Lecture </b>  | nours          |               | 45 ho   | urs    |
| Course De      | esigned By: Dr                             | S.Rathinavel                              |                        |                |               |         |        |

| Mappi | Mapping with Programme Outcomes |     |     |     |     |     |     |     |     |      |  |
|-------|---------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|------|--|
| COs   | PO1                             | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |  |
| CO1   | S                               | S   | S   | S   | S   | S   | S   | S   | М   | S    |  |
| CO2   | S                               | S   | М   | М   | S   | М   | M   | S   | S   | S    |  |
| CO3   | S                               | S   | М   | S   | S   | S   | М   | S   | S   | S    |  |

| Course     | 220              | INTELLIGENT INSTRUMENTATION   | L   | Т       | Р                   | C    |
|------------|------------------|---|---|---------|---------------------|------|
| code       | 23Q              | & MEDICAL ELECTRONICS<br>LABORATORY   | 0   | 0       | 3                   | 3    |
| Pre-requi  | site             | Student should have the basic knowledge<br>on circuit design                          | Sylla<br>Versi                                |         | 2021-               | 22   |
| Course Ob  | jectives:        |   |   | I       |                     |      |
| The main o | bjectives of th  | is course are to:   |   |         |                     |      |
| 1. Prov    | vide knowledg    | ge about data acquisition and control an external m                                   | easurin                                       | g dev   | ice by              |      |
| int        | erfacing to a c  | computer.   |   |         |                     |      |
| 2. Far     | niliarize in sig | nal conditioning and various processing tools.  |   |         |                     |      |
| 3. Bec     | come compete     | nt in designing virtual instruments for various indu                                  | ustrial r                                     | neasu   | remen               | ts   |
|            | d applications.  |   |   |         |                     |      |
|            | Course Outco     |   |   |         |                     |      |
| On the suc | cessful compl    | etion of the course, student will be able to:   |   |         |                     |      |
| 1 Iden     | tify salient tra | its of a virtual instrument and incorporate these tra                                 | its in  |         | K4                  |      |
| proje      |                  |   |   |         |                     |      |
|            | · · ·            | ze and document in the laboratory prototype meas                                      | uremen  | t       | K5                  |      |
| -          | -                | omputer, plug-in DAQ interfaces and bench level                                       |   |         |                     |      |
|            | uments. Cours    |   | I IZA   |         | <u> </u>            |      |
|            |                  | Inderstand; K3 - Apply; K4 - Analyze; K5 - Evalu<br>FRUMENTATION LAB: (USING LabVIEW) |   |         |                     | te)  |
|            | verting VI in t  |   |   |         | 1 111101            | 113) |
| A A        | C using DAQ      |   |   |         |                     |      |
|            | C using DAQ      |   |   |         |                     |      |
|            | -                | rol using WSN   |   |         |                     |      |
|            | •                | f Digital filters using LabVIEW DSP Module  |   |         |                     |      |
| -          |                  | terface using LabVIEW ARM Module  | 29  |         |                     |      |
|            |                  | oring system using DAQ Interface  | S   |         |                     |      |
|            | 1 A *            | ol using DAQ Interface  | S I   |         |                     |      |
| 0. 114     | -                | EDICAL ELECTRONICS (Any 6 Experiment  | •<br>•  |         |                     |      |
| 1. Han     | d Grip heart ra  |   | <u>, , , , , , , , , , , , , , , , , , , </u> |         |                     |      |
|            |                  | O2 gas sensor.  |   |         |                     |      |
|            |                  | pressure using Sphygmomanometer and give the ta                                       | abular c                                      | olum    | n for               |      |
|            | rious stages.    | EDUCATE TO ELEVATE  |   |         |                     |      |
|            |                  | nd to measure the heart rate.   |   |         |                     |      |
|            |                  | to perform an air flow and lung volume.   |   |         |                     |      |
|            | d Dynamomet      | ter.  |   |         |                     |      |
| 7. pH      |                  | terraria forma of house interview iterrity and  |   |         | 090                 |      |
| ð. Ubs     | erve the outpu   | it wave form of heart rate monitoring using pulse                                     |   | er in I | <u>080</u><br>45 ho |      |
|            | 1                |   |   | 1       |                     | JULS |
| Course De  | signed Ry. Dr    | .K.G.Padmasine Total Lecture h  | louis   |         | 45 110              |      |

| Mappi | Mapping with Programme Outcomes |     |     |     |     |     |     |     |     |      |  |  |
|-------|---------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|------|--|--|
| COs   | PO1                             | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |  |  |
| CO1   | S                               | S   | S   | S   | L   | Μ   | S   | S   | S   | S    |  |  |
| CO2   | S                               | S   | S   | S   | L   | S   | S   | S   | S   | S    |  |  |



| Course code  | 33A  | PROCESS CONTROL   | L                             | Т                      | Р                            | C                    |
|--|--|---|-------------------------------|------------------------|------------------------------|----------------------|
| Core/Elective/S  |  | Core  | 4                             | 0                      | 0                            | 4                    |
|  | ••   | Basic understanding on Industrial   | Sylla                         | bus                    | 2021                         | <br>>>               |
| Pre-requisite  |  | Automations   | Versi                         | on                     | 2021-2                       | 22                   |
| Course Object  |  |   |                               |                        |                              |                      |
| The main object  |  |   |                               |                        |                              |                      |
|  |  | f various processes   |                               |                        |                              |                      |
|  |  | of various control actions  |                               |                        |                              |                      |
| *  | •  | the final control elements  |                               |                        |                              |                      |
|  |  | ion criteria and tuning techniques of controllers   |                               |                        |                              |                      |
|  |  | of multi loop control techniques  |                               |                        |                              |                      |
| Expected Cou   |  |   |                               |                        |                              |                      |
|  |  | etion of the co <mark>urse, student w</mark> ill be able to:  |                               |                        | V2                           |                      |
|  |  | the actuator and its applications   |                               |                        | K2                           |                      |
|  |  | Industrial automation   | - 4 17/                       | <u> </u>               | K3                           |                      |
| <b>NI</b> - Kememt   | er; <b>K</b> 2 - Ui                                  | nderstand; K3 - Apply; K4 - Analyze; K5 - Evalu   | ale; K                        | ) - UI                 | cale                         |                      |
| Unit:1   |  | Final Control Elements  |                               |                        | 12 ho                        | ire                  |
|  | operation  | Signal conversion, actuators, control element   | signe                         |                        |                              |                      |
|  |  | s, digital electrical signals, pneumatic signals  |                               |                        |                              |                      |
|  |  | olling devices – actuators: electrical actuators,   |                               |                        |                              |                      |
|  |  | nical, electrical, fluid walls.   | Jieum                         |                        | icidato                      | 10 -                 |
| control cicilie.   | ints. incentar                                       |   |                               |                        |                              |                      |
| Unit:2   |  | Discrete State Process Control  |                               |                        | 12 ho                        | urs                  |
| variables, pro<br>Controller M<br>Continuous c<br>control Mode   | cess specif<br>lodes: Two<br>ontrol Moc<br>e- Compos | state process control – characteristics of the s<br>ication, event sequence description –Controller r<br>o-position Mode, Multiposition Mode, Floati<br>des: Proportional control Mode, Integral control<br>ite Control Mode: Proportional –Integral Co<br>, Three Mode controller (PID). | nodes-<br>ng co<br>l Mod      | Disontrol<br>Disontrol | continu<br>Mode<br>erivativ  | ious<br>e –<br>re –  |
| Derivative CC  |  | , Three Mode controller (FID).  | <u>8</u>                      |                        |                              |                      |
| controllers: E<br>General featu<br>Programme L                   | rror detecto<br>res, Mode<br>ogic Contro             | Analog and Logic Controllers<br>log controllers: Physical layout, front panel, sic<br>or, Single mode, composite controller mode – P<br>Implementation – Relay controllers: Backgroun<br>ollers: Relay sequences, Programmable Logic Co<br>Functions of PLC software.                     | neuma<br>nd, La               | tic C<br>dder          | controll<br>diagra           | onic<br>ers:<br>ms-  |
| Unit:4   |  | Computer Based Control  |                               |                        | 12 ho                        | nrs                  |
| Digital applic<br>controllers:<br>requirements-<br>mode, derivat | Hardware<br>algorithms<br>tive mode,                 | gle and multivariable alarms, Two position control<br>configuration, Smart sensors, multiloop c<br>to implement the control equations: errors, propo<br>PID Control mode – Data Loggers – Supervise<br>field bus operations, General characteristics of bu                                | ontroll<br>ortional<br>ory co | lers-<br>l moc         | uter ba<br>Softw<br>le, inte | ised<br>vare<br>gral |
| Unit:5   |  | Control Loop Characteristics  |                               |                        | 10 ho                        | ure                  |
|  | m configu  | rations: Single variable, Cascade Control – N   | Aultive                       | riahl                  |                              |                      |
| system: analo  | og control,  | supervisory and direct digital control – Correspondence of quality – Stability: Transfer function fi  | ntrol s                       | ysten                  | n qual                       | lity:                |

stability criteria- Process Loop Tuning: Open Loop Transient Response Method, Ziegler-Nichols Method, Frequency Response Method .

| Unit:6 |              | Contemporary Issues   | 2 hours         |
|--------|--------------|---|-----------------|
| Mixing | g, Drying Pi | rocess in industry  |                 |
|        |              |   |                 |
|        |              | Total Lecture hours   | 60 hours        |
| Text E | Book(s)      |   |                 |
| 1      | Curtis D.    | Johnson, "Process control instrumentation Technology", Eight                          | editions,       |
|        | PrenticeH    | all of India, 2006.   |                 |
|        |              |   |                 |
| Refere | ence Books   |   |                 |
| 1      | Stephanopo   | oulos G, "Chemical Pro <mark>cess Control", P</mark> rentice Hall of India, New Delhi | , 2008.         |
| 2      | Donald R C   | Coughanowr, "Process Systems Analysis and Control", Tata McGraw H                     | ill Inc., 2006. |
| 3      |              | juette B. "Process Dynamics Modeling, Analysis and Simulation", Pren                  | tice Hall, 2003 |
| 4      | Liptak B G   | , "Process Control", Chilton Book Company, 2005.                                      |                 |
|        |              |   |                 |
| Relate | ed Online C  | Cont <mark>ents [M</mark> OOC, SWAYAM, NPTEL, We <mark>bsites et</mark> c.]           |                 |
| 1      | www.npt      |   |                 |
| 2      |              | vw.pc-education.mcmaster.ca/Lecture_Slides/Chap_01_Marlin_2                           | <u>002.pdf</u>  |
| 3      |              | turenotes.com   |                 |
| 4      | -            | es.google.com/a/nirmauni.ac.in/process-instrumentation-and-                           | × 4             |
|        | control      | - <u>1ecd03/course-contents/lecture-notes</u>   |                 |
|        |              | E AND THE REAL REAL   |                 |
| Course | e Designed l | By: Dr.K.G.Padmasine  |                 |

| Mappi | Mapping with Programme Outcomes |     |     |     |     |     |     |     |     |      |  |  |
|-------|---------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|------|--|--|
| COs   | PO1                             | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |  |  |
| CO1   | S                               | S   | М   | L   | L   | М   | M   | S   | S   | S    |  |  |
| CO2   | S                               | S   | М   | L   | L   | S   | М   | М   | S   | S    |  |  |



| Course code 33B                 | DIGITAL SIGNAL PROCESSING  | L        | T      | Р            | C     |
|---------------------------------|--|----------|--------|--------------|-------|
| <b>Core/Elective/Supportive</b> | Core   | 4        | 0      | 0            | 4     |
| Pre-requisite                   | The mathematics, signals & systems   | Sylla    |        | 2021-        | 22    |
| •                               | knowledge is most Important  | Versi    | on     | 2021         |       |
| Course Objectives:              |  |          |        |              |       |
| The main objectives of thi      |  | с        |        |              |       |
|                                 | to design Digital Filters, based on the Filter speci                         |          |        |              |       |
|                                 | are to different applications of digital signal proce                        | ssing a  | nd th  | e            |       |
| architectures of D              | DSP processors.  |          |        |              |       |
| Expected Course Outcor          | nes  |          |        |              |       |
|                                 | etion of the course, student will be able to:                                |          |        |              |       |
|                                 | d the Filter specifications and digital Filters                              |          |        | K4           |       |
| 2 Understand the differe        | nt applications of digital signal processing and the arc                     | hitectur | es     | K4           |       |
| of DSP processors               | 601 er er er 60  |          |        |              |       |
| K1 - Remember; K2 - U           | <mark>nde</mark> rstand; K3 - Apply; K4 - Anal <mark>yze; K5 - Ev</mark> alu | ate; K   | 6 - Cı | reate        |       |
|                                 |  |          |        |              |       |
| Unit:1                          | The Fast Fourier Transform   |          |        | 12 ho        |       |
|                                 | uation of the DFT-The Fast Fourier Transfor                                  |          | matio  | on-in-T      | ime   |
| Algorithm-Decimation-in-        | Frequency Algorithm-IDFT using FFT Algorithr                                 | 1        |        |              |       |
| Unit:2                          | Infinite Impulse Response Filters  |          |        | 12 ho        |       |
|                                 | wpass Filter Design - Steps to Design an Analog                              |          | rwort  |              |       |
|                                 | Analog Chebyshev Lowpass Filter- Compariso                                   | -        |        |              | ·     |
|                                 | ter-Frequency Transformation in Analog Domai                                 |          |        |              |       |
| -                               | ilters- Design of IIR Filters from Analog Filters                            |          | -      | n mgn        | pass, |
| -                               | Domain -Realization of Digital Filters                                       | Teque    | IIIC y |              |       |
|                                 | Domain - Realization of Digital Theis  | R        | -/-    |              |       |
| Unit:3                          | Finite Impulse Response Filters  | A C      | /      | 12 ho        | urs   |
| Introduction- Linear Pha        | ase FIR Filters-Frequency Response of Linea                                  | Phase    | e FII  |              |       |
| Location of the Zeros of        | Linear Phase FIR Filters-Design of FIR Filters u                             | sing W   | indo   | ws-Dig       | ital  |
|                                 | Sampling Method of Designing FIR Filters-Real                                | -        |        | •            |       |
|                                 | Stringer a Million   |          |        |              |       |
|                                 | pplications of Digital Signal Processing                                     |          |        | 10 ho        |       |
|                                 | essing - Speech Analysis-Speech Coding - Su                                  | oband    | codir  | ng-Cha       | nnel  |
| Vocoder - Homomorphic           | Vocoder - Digital Processing of Audio Signals.                               |          |        |              |       |
|                                 |  |          |        |              |       |
| Unit:5                          | Digital Signal Processors  |          |        | 12 ho        |       |
|                                 | al Processors-Selecting Digital Signal Processors                            |          |        |              |       |
|                                 | C50-Addressing modes-Instruction Set-Simple A                                | ssemb    | ly La  | anguag       | e     |
| Programs-Architecture of        | TMS320C54x-Accumulators.   |          |        |              |       |
| Unitik                          | Contomnovovy Issues  |          |        | <b>1</b> L - |       |
| Unit:6                          | Contemporary Issues<br>t System, Radar Signal Processing                     |          |        | 2 ho         | urs   |
| שמשמע שנמצעורנוולוו             | i System, Radai Signai i locessing   |          |        |              |       |
|                                 | Total Lecture hours  |          |        | 60 ha        | urs   |
|                                 | i otur Ecotur e nour   |          |        |              |       |

2\_wirjagal- Golo

| Te | ext Book(s)   |
|----|---|
| 1  | John G. Proakis & Dimitris G.Manolakis, Digital Signal Processing - Principles,     |
|    | Algorithms & Applications, Fourth Edition, Pearson Education / Prentice Hall, 2011. |
| 2  | Dr. P. Ramesh Babu, Digital Signal Processing, Seventh Edition SciTech publications |
|    | (India) pvt. Ltd., 2017.  |
|    |   |

#### **Reference Books**

1

- 1 Emmanuel C. Ifeachor & Barrie. W. Jervis, Digital Signal Processing, Second Edition, Pearson Education / Prentice Hall, 2002.
- 2 A. V. Oppenheim, R.W. Schafer and J.R. Buck, Discrete-Time Signal Processing<sup>||</sup>, 8th Indian Reprint, Pearson, 2004.
- 3 Sanjit K. Mitra, Digital Signal Processing A Computer Based Approach<sup>II</sup>, Tata Mc Graw Hill, 2007.
- 4 Andreas Antoniou, Digital Signal Processing, Tata Mc Graw Hill, 2006.

#### Related Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]

தந்து இந்தப்பாரை பாரா 10 த

- 1 https://nptel.ac.in/courses/117/104/117104070/
- 2 https://nptel.ac.in/courses/117/102/117102060/
- 3 https://nptel.ac.in/courses/108/105/108105055/

Course Designed By: Dr.J. Vijayakumar

| Mapping with Programme Outcomes |     |     |     |     |     |     |            |     |     |      |
|---------------------------------|-----|-----|-----|-----|-----|-----|------------|-----|-----|------|
| COs                             | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | <b>PO7</b> | PO8 | PO9 | PO10 |
| CO1                             | S   | S   | S   | L   | М   | S   | L          | S   | S   | S    |
| CO2                             | S   | S   | S   | L   | S   | М   | L          | S   | S   | S    |

| code   | 33C   | <b>VLSI DESIGN</b>  | L  | T   | Р   | С  |
|--|---|---|--|---|---|--|
|  | ve/Supportive   | Core  | 4  | 0   | 0   | 4  |
| Pre-requi  |   | An overall study of the fabrication of<br>MOS transistor, design process VHDL,<br>Verilog programming language and the<br>basics of IoT   | Sylla<br>Versi   | bus   | 2021  | -22  |
| Course Ob  | jectives:   |   |  |   |   |  |
|  | *   | s course are to:  |  |   |   |  |
| 1. To d  | levelop the basic   | idea about VLSI technology  |  |   |   |  |
| <b>2</b> . To le   | earn and attempt  | to execute the concepts of integrated circuit design a  | and test   | ing.  |   |  |
| Expected (   | Course Outcon   | nes:  |  |   |   |  |
|  |   | tion of the course, student will be able to:  |  |   |   |  |
|  |   | essor technology  |  |   | K1  |  |
| 2 Right  | ly apply the co   | ncepts in real time applications and to explain th  | e recer  | nt  | K3  |  |
|  | opments in the  |   |  |   |   |  |
|  | -   | <mark>f mod</mark> elling a digital system using Hardware De  | escription   | on  | K2  |  |
| langu  |   |   |  |   |   |  |
|  |   | ge of ASIC internals  |  |   | K2  |  |
|  |   | n ASIC types and tools used in the design   |  |   | K3  |  |
| $\mathbf{KI} - \text{Kem}$   |   |   | rolanoto.  | .VC   | Cuest   | h a  |
|  | ember; $\mathbf{K}\mathbf{Z} = \mathbf{U}$  | Inderstand; K3 – Apply; K4 – Analyze; K5 – Ev   | valuate  | ; K6 -  | - Creat   | te   |
|  | ember; $\mathbf{K}\mathbf{Z} = \mathbf{U}$  | A 2000 10 10 10 10 10 10 10 10 10 10 10 10  | valuate  | ; K6 -  |   |  |
| Unit:1   | N.  | Introduction to MOS technology  |  |   | 12 h  | ours   |
| Unit:1<br>Basic MOS  | transistors: Sy   | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr  | ansisto  | or ope  | 12 h<br>tration,  | ours<br>Basic  |
| Unit:1<br>Basic MOS<br>electrical p  | transistors: Sy<br>properties of M  | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview o  | ansisto<br>f silice  | or ope  | 12 h<br>ration,<br>emicon   | ours<br>Basic<br>ductor  |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:   | transistors: Sy<br>properties of N<br>NMOS fabrica  | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview o<br>ation, CMOS fabrication: n-well, p-well, twin tu  | ansisto<br>f silice  | or ope  | 12 h<br>ration,<br>emicon   | ours<br>Basic<br>ductor  |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:   | transistors: Sy<br>properties of M  | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview o<br>ation, CMOS fabrication: n-well, p-well, twin tu  | ansisto<br>f silice  | or ope  | 12 h<br>ration,<br>emicon   | ours<br>Basic<br>ductor  |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:   | transistors: Sy<br>properties of N<br>NMOS fabrica  | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview o<br>ation, CMOS fabrication: n-well, p-well, twin tu  | ansisto<br>f silice  | or ope  | 12 h<br>ration,<br>emicon<br>ects, B  | ours<br>Basic<br>ductor  |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2   | transistors: Sy<br>properties of N<br>NMOS fabrics<br>Latch up and p  | Introduction to MOS technology<br>ymbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview o<br>ation, CMOS fabrication: n-well, p-well, twin tu<br>revention.   | ansisto<br>f silico<br>b, inter  | or ope<br>on se<br>rconn  | 12 h<br>eration,<br>emicon<br>ects, B   | ours<br>Basic<br>ductor<br>sipolar   |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve  | transistors: Sy<br>properties of M<br>NMOS fabric:<br>Latch up and p<br>erter DC charac   | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview o<br>ation, CMOS fabrication: n-well, p-well, twin tu<br>revention.<br>MOS circuit design process  | ransistc<br>f silic<br>b, inter<br>ratio, '  | or ope<br>on se<br>rconn<br>Trans   | 12 h<br>pration,<br>emicon<br>ects, B<br>12 h<br>missio   | ours<br>Basic<br>ductor<br>ipolar<br>nours<br>n gate   |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve<br>NMOS and  | transistors: Sy<br>properties of M<br>NMOS fabrics<br>Latch up and p<br>tatch up and p<br>crter DC charac   | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview o<br>ation, CMOS fabrication: n-well, p-well, twin tu<br>revention.<br>MOS circuit design process<br>eteristics, Determination of pull up to pull down   | ransisto<br>f silico<br>b, inter<br>ratio, '<br>flip fl  | or ope<br>on se<br>rconn<br>Trans   | 12 h<br>pration,<br>emicon<br>ects, B<br>12 h<br>missio   | ours<br>Basic<br>ductor<br>ipolar<br>nours<br>n gate   |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS invo<br>NMOS and<br>Switch logi   | transistors: Sy<br>properties of M<br>NMOS fabrics<br>Latch up and p<br>tatch up and p<br>crter DC charac   | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview o<br>ation, CMOS fabrication: n-well, p-well, twin tu<br>revention.<br>MOS circuit design process<br>eteristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay   | ransisto<br>f silico<br>b, inter<br>ratio, '<br>flip fl  | or ope<br>on se<br>rconn<br>Trans   | 12 h<br>pration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (  | ours<br>Basic<br>ductor<br>ipolar<br>nours<br>n gate<br>CPTL,  |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve<br>NMOS and<br>Switch logi<br>Unit:3   | transistors: Sy<br>properties of M<br>NMOS fabrics<br>Latch up and p<br>erter DC charac<br>CMOS inver<br>c networks, Sti  | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview o<br>ation, CMOS fabrication: n-well, p-well, twin tu<br>revention.<br>MOS circuit design process<br>cteristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay<br>CMOS Subsystem Design  | ransisto<br>f silico<br>b, inter<br>ratio, '<br>flip fl<br>yout.   | or ope<br>on se<br>rconn<br>Trans<br>lops u                                   | 12 h<br>rration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (<br>12 h  | ours<br>Basic<br>ductor<br>ipolar<br>n gate<br>CPTL,<br>ours   |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve<br>NMOS and<br>Switch logi<br>Unit:3<br>Alternative  | transistors: Sy<br>properties of M<br>NMOS fabric:<br>Latch up and p<br>erter DC charact<br>CMOS inver<br>c networks, Sti<br>Gate circuits, I   | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview of<br>ation, CMOS fabrication: n-well, p-well, twin tu<br>revention.<br>MOS circuit design process<br>eteristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay<br>CMOS Subsystem Design<br>Design of different types of Adders, Manchester  | ransisto<br>f silico<br>b, inter<br>ratio, '<br>flip fl<br>yout.   | or ope<br>on se<br>rconn<br>Trans<br>lops u<br>chain                          | 12 h<br>rration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (<br>12 h<br>adder,  | ours<br>Basic<br>ductor<br>sipolar<br>n gate<br>CPTL,<br>ours<br>Carry                                 |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve<br>NMOS and<br>Switch logi<br>Unit:3<br>Alternative<br>Look Ahead  | transistors: Sy<br>properties of M<br>NMOS fabrics<br>Latch up and p<br>erter DC charac<br>CMOS inver<br>c networks, Sti<br>Gate circuits, I<br>d, Carry Select   | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview of<br>ation, CMOS fabrication: n-well, p-well, twin ture<br>revention.<br>MOS circuit design process<br>teristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay<br>CMOS Subsystem Design<br>Design of different types of Adders, Manchester<br>Adder, Carry skip adder, Design of different ty  | ransisto<br>f silico<br>b, inter<br>ratio, '<br>flip fl<br>yout.   | or ope<br>on se<br>rconn<br>Trans<br>lops u<br>chain<br>multi                 | 12 h<br>rration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (<br>12 h<br>adder,<br>pliers:   | ours<br>Basic<br>ductor<br>ipolar<br>n gate<br>CPTL,<br>ours<br>Carry<br>Braun                         |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve<br>NMOS and<br>Switch logi<br>Unit:3<br>Alternative<br>Look Ahead<br>array, Baug   | transistors: Sy<br>properties of M<br>NMOS fabrics<br>Latch up and p<br>erter DC charace<br>CMOS inver<br>c networks, Sti<br>Gate circuits, I<br>d, Carry Select<br>gh-woolly array   | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview of<br>ation, CMOS fabrication: n-well, p-well, twin tu<br>revention.<br>MOS circuit design process<br>eteristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay<br>CMOS Subsystem Design<br>Design of different types of Adders, Manchester<br>Adder, Carry skip adder, Design of different ty<br>y, Wallace tree multiplier, systolic array multiplier, | ransisto<br>f silico<br>b, inter<br>ratio, '<br>flip fl<br>yout.   | or ope<br>on se<br>rconn<br>Trans<br>lops u<br>chain<br>multi                 | 12 h<br>rration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (<br>12 h<br>adder,<br>pliers:   | ours<br>Basic<br>ductor<br>ipolar<br>n gate<br>CPTL,<br>ours<br>Carry<br>Braun                         |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve<br>NMOS and<br>Switch logi<br>Unit:3<br>Alternative<br>Look Ahead<br>array, Baug   | transistors: Sy<br>properties of M<br>NMOS fabrics<br>Latch up and p<br>erter DC charac<br>CMOS inver<br>c networks, Sti<br>Gate circuits, I<br>d, Carry Select   | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview of<br>ation, CMOS fabrication: n-well, p-well, twin tu<br>revention.<br>MOS circuit design process<br>eteristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay<br>CMOS Subsystem Design<br>Design of different types of Adders, Manchester<br>Adder, Carry skip adder, Design of different ty<br>y, Wallace tree multiplier, systolic array multiplier, | ransisto<br>f silico<br>b, inter<br>ratio, '<br>flip fl<br>yout.   | or ope<br>on se<br>rconn<br>Trans<br>lops u<br>chain<br>multi                 | 12 h<br>rration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (<br>12 h<br>adder,<br>pliers:   | ours<br>Basic<br>ductor<br>ipolar<br>n gate<br>CPTL,<br>ours<br>Carry<br>Braun                         |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve<br>NMOS and<br>Switch logi<br>Unit:3<br>Alternative<br>Look Ahead<br>array, Baug   | transistors: Sy<br>properties of M<br>NMOS fabrics<br>Latch up and p<br>erter DC charace<br>CMOS inver<br>c networks, Sti<br>Gate circuits, I<br>d, Carry Select<br>gh-woolly array   | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview of<br>ation, CMOS fabrication: n-well, p-well, twin tu<br>revention.<br>MOS circuit design process<br>eteristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay<br>CMOS Subsystem Design<br>Design of different types of Adders, Manchester<br>Adder, Carry skip adder, Design of different ty<br>y, Wallace tree multiplier, systolic array multiplier, | ransisto<br>f silico<br>b, inter<br>ratio, '<br>flip fl<br>yout.   | or ope<br>on se<br>rconn<br>Trans<br>lops u<br>chain<br>multi                 | 12 h<br>rration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (<br>12 h<br>adder,<br>pliers:<br>hes an   | ours<br>Basic<br>ductor<br>ipolar<br>n gate<br>CPTL,<br>ours<br>Carry<br>Braun                         |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS invo<br>NMOS and<br>Switch logi<br>Unit:3<br>Alternative<br>Look Ahead<br>array, Baug<br>flops, Barre<br>Unit:4<br>Introduction   | transistors: Sy<br>properties of M<br>NMOS fabric:<br>Latch up and p<br>erter DC charace<br>CMOS inver<br>c networks, Sti<br>Gate circuits, I<br>d, Carry Select<br>gh-woolly array<br>el shifter, Memo                                       | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview of<br>ation, CMOS fabrication: n-well, p-well, twin ture<br>revention.<br>MOS circuit design process<br>teristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay<br>CMOS Subsystem Design<br>Design of different types of Adders, Manchester<br>Adder, Carry skip adder, Design of different ty<br>y, Wallace tree multiplier, systolic array multion<br>ory structures.   | ransisto<br>f silice<br>ib, inter<br>ratio, '<br>flip fl<br>yout.<br>carry o<br>pes of<br>tiplier,           | or ope<br>on se<br>rconn<br>Trans<br>lops u<br>chain<br>multi<br>Latc         | 12 h<br>rration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (<br>12 h<br>adder,<br>pliers:<br>hes an<br>10 h                                       | ours<br>Basic<br>ductor<br>ipolar<br>n gate<br>CPTL,<br>CPTL,<br>Carry<br>Braun<br>d flip              |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve<br>NMOS and<br>Switch logi<br>Unit:3<br>Alternative<br>Look Ahead<br>array, Baug<br>flops, Barre<br>Unit:4<br>Introduction   | transistors: Sy<br>properties of M<br>NMOS fabric:<br>Latch up and p<br>erter DC charace<br>CMOS inver<br>c networks, Sti<br>Gate circuits, I<br>d, Carry Select<br>gh-woolly array<br>el shifter, Memo                                       | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview of<br>ation, CMOS fabrication: n-well, p-well, twin ture<br>revention.<br>MOS circuit design process<br>eteristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay<br>CMOS Subsystem Design<br>Design of different types of Adders, Manchester<br>Adder, Carry skip adder, Design of different ty<br>y, Wallace tree multiplier, systolic array multion<br>ory structures.<br>ASIC<br>IC, Design flow of VLSI, Types of simulation, p   | ransisto<br>f silice<br>ib, inter<br>ratio, '<br>flip fl<br>yout.<br>carry o<br>pes of<br>tiplier,           | or ope<br>on se<br>rconn<br>Trans<br>lops u<br>chain<br>multi<br>Latc         | 12 h<br>rration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (<br>12 h<br>adder,<br>pliers:<br>hes an<br>10 h                                       | ours<br>Basic<br>ductor<br>ipolar<br>n gate<br>CPTL,<br>CPTL,<br>Carry<br>Braun<br>d flip              |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve<br>NMOS and<br>Switch logi<br>Unit:3<br>Alternative<br>Look Ahead<br>array, Baug<br>flops, Barre<br>Unit:4<br>Introduction<br>Floor plann                          | transistors: Sy<br>properties of M<br>NMOS fabrics<br>Latch up and p<br>erter DC charace<br>CMOS inver<br>c networks, Sti<br>d, Carry Select<br>gh-woolly array<br>el shifter, Memo   | Introduction to MOS technology<br>mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview of<br>ation, CMOS fabrication: n-well, p-well, twin ture<br>revention.<br>MOS circuit design process<br>eteristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay<br>CMOS Subsystem Design<br>Design of different types of Adders, Manchester<br>Adder, Carry skip adder, Design of different ty<br>y, Wallace tree multiplier, systolic array multi-<br>ory structures.<br>ASIC<br>IC, Design flow of VLSI, Types of simulation, p<br>Partitioning and routing.   | ransisto<br>f silico<br>b, inter<br>ratio, '<br>flip fl<br>yout.<br>carry o<br>pes of<br>tiplier,<br>program | or ope<br>on se<br>rconn<br>Trans<br>lops u<br>chain<br>multi<br>Latc         | 12 h<br>rration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (<br>12 h<br>adder,<br>pliers:<br>hes an<br>10 h<br>le ASI<br>le ASI                   | ours<br>Basic<br>ductor<br>sipolar<br>n gate<br>CPTL,<br>Carry<br>Braun<br>d flip<br>C,<br>C,          |
| Unit:1<br>Basic MOS<br>electrical p<br>technology:<br>transistors,<br>Unit:2<br>CMOS inve<br>NMOS and<br>Switch logi<br>Unit:3<br>Alternative<br>Look Ahead<br>array, Baug<br>flops, Barre<br>Unit:4<br>Introduction<br>Floor plann<br>Unit:5<br>Program str | transistors: Sy<br>properties of M<br>NMOS fabric:<br>Latch up and p<br>erter DC charace<br>CMOS inver<br>c networks, Sti<br>Gate circuits, I<br>d, Carry Select<br>gh-woolly array<br>el shifter, Memo<br>ing, Placement<br>ructure, types a | Introduction to MOS technology<br>(mbols, Enhancement mode, Depletion mode tr<br>MOS and BICMOS circuits, An overview of<br>ation, CMOS fabrication: n-well, p-well, twin ture<br>revention.<br>MOS circuit design process<br>teristics, Determination of pull up to pull down<br>ter, Pass transistor, Design of logic gates and<br>ck diagrams for logic gates, Design rules and lay<br>CMOS Subsystem Design<br>Design of different types of Adders, Manchester<br>Adder, Carry skip adder, Design of different ty<br>y, Wallace tree multiplier, systolic array multion<br>ory structures.<br>ASIC<br>IC, Design flow of VLSI, Types of simulation, p<br>Partitioning and routing.  | ransisto<br>f silico<br>b, inter<br>ratio, '<br>flip fl<br>yout.<br>carry o<br>pes of<br>tiplier,<br>program | or ope<br>on se<br>rconn<br>Trans<br>lops u<br>chain<br>multi<br>Latc<br>nmab | 12 h<br>rration,<br>emicon<br>ects, B<br>12 h<br>missio<br>using (<br>12 h<br>adder,<br>pliers:<br>hes an<br>10 h<br>le ASI<br>le ASI<br>12 h<br>kages, | ours<br>Basic<br>ductor<br>ipolar<br>n gate<br>CPTL,<br>ours<br>Carry<br>Braun<br>d flip<br>C,<br>ours |

| Unit:6                     | Contemporary Issues  | 2 hours         |
|----------------------------|--|-----------------|
| Application<br>application | Specific Internet of Things: Application or field of use - sensor                            | specific to the |
| 11                         |  |                 |
|                            | Total Lecture hours  | 60 hours        |
| Text Boo                   | k(s)   |                 |
| 1 Doug                     | las Pucknell, "Basic VLSI Design systems and circuits" Prentice Hall                         | PTR, 2005       |
|                            | ael John Sebastian Smith, "Application Specific Integrated Circuits" A                       |                 |
| 1 <sup>st</sup> ed         | ition, 1997  |                 |
|                            |  |                 |
| Reference                  |  |                 |
| 1 Mich                     | ael P.Lukas, "Distributed Co <mark>ntrol Systems"</mark> , Van Nostrand Reinfold Co          | mpany,2000      |
| 2 Neil                     | Weste & Kamarn E <mark>shr</mark> angian <mark>, "Principles of CMOS VL</mark> SI design" Ad | dision Wesley,  |
| $2^{nd} E$                 | dition, 1998   |                 |
| 3 Jacob                    | Baker, Harry, David E.Boyce, "CMOS circuit design, layout and sim                            | ulation"        |
| Prent                      | ice Hall India, 1998   |                 |
|                            | ker J. " A VHDL Primer" Pearson Eduction, 3 <sup>rd</sup> Edition, 1999                      |                 |
| 5 John                     | Wakerly, "Digital Design Priciples & Practices", 3rd Edition, Pearson                        | Education, 2002 |
|                            |  |                 |
|                            | Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]   |                 |
|                            | ://nptel.ac.in/courses/108/107/108107129/  |                 |
| · ·                        | ://nptel.ac.in/courses/117/101/117101105/  |                 |
|                            | ://nptel.ac.in/courses/117/101/117101004/  |                 |
|                            | ://nptel.ac.in/courses/117/108/117108040/  |                 |
| 5 https                    | ://swayam.g <mark>ov.in/nd1_noc20_ee05/preview</mark>  |                 |
| a 5                        |  |                 |
| Course De                  | esigned By: Dr.Azha.Periasamy  |                 |
|                            | S S S S S S S S S S S S S S S S S S S  |                 |

| Mappi      | Mapping with Programme Outcomes |     |     |     |         |     |     |     |     |      |  |  |
|------------|---------------------------------|-----|-----|-----|---------|-----|-----|-----|-----|------|--|--|
| COs        | PO1                             | PO2 | PO3 | PO4 | PO5     | PO6 | PO7 | PO8 | PO9 | PO10 |  |  |
| CO1        | S                               | S   | S   | S   | S       | S   | Sal | S   | S   | S    |  |  |
| CO2        | S                               | S   | S   | S.  | S       | S   | N S | S   | S   | S    |  |  |
| CO3        | S                               | S   | S   | S   | LIS 60) | S   | S   | S   | S   | S    |  |  |
| <b>CO4</b> | S                               | S   | S   | S   | TESTO   | S   | S   | S   | S   | S    |  |  |
| CO5        | S                               | S   | S   | S   | S       | S   | S   | S   | S   | S    |  |  |

| Course         | 33P                          | DIGITAL SIGNA                                      | L   | T         | P       | C       |      |  |  |
|----------------|------------------------------|--|---|-----------|---------|---------|------|--|--|
| code           |                              | LABOR  |   | 0         | 0       | 3       | 3    |  |  |
| <b>D</b> • • 4 |                              | mathematics, signals & s<br>ramming knowledge is m | Syllabus<br>Version   |           | 2021-22 |         |      |  |  |
| Course Ob      |                              |  |   | ·         |         |         |      |  |  |
|                | •                            | is course are to:                                  |   |           |         |         |      |  |  |
|                |                              | signal processing operation                        |   |           |         |         | D    |  |  |
|                |                              | to Correlation, Cross Correlation                  |   |           | ın M.   | ATLA    | В.   |  |  |
|                | Course Outco                 | and IIR filters in MATLA                           | AB and DSP Processor.   |           |         |         |      |  |  |
|                |                              | etion of the course, studen                        | t will be able to:  |           |         |         |      |  |  |
|                |                              | al processing operations.                          |   |           |         | K2      |      |  |  |
|                |                              | ent the FIR and IIR Filters                        | s in DSP Processor for  | perform   | ning    | K4      |      |  |  |
|                |                              | ver real-time signals.                             | 2812  | P         |         |         |      |  |  |
|                |                              |  |   |           |         |         |      |  |  |
|                |                              | nderstand; K3 - Apply; K                           |   | uate; K   | 6 - Cr  | eate    |      |  |  |
|                |                              |  |   |           |         |         |      |  |  |
|                |                              | LATION USING MATI                                  |   | ents)     |         |         |      |  |  |
|                |                              | nentary Discrete-Time seq                          | uences  |           |         |         |      |  |  |
|                |                              | ar convolutions                                    |   |           |         |         |      |  |  |
|                |                              | nd Cross Correlation                               | ~ 24 19   |           |         |         |      |  |  |
|                | luency Analys                |  |   |           |         |         |      |  |  |
|                | •                            | ers (LPF/HPF/BPF/BSF) a                            | And A water and a second se | -         | •       |         |      |  |  |
|                | •                            | orth and Chebyshev IIR fi                          | lters (LPF/HPF/BPF/B  | SF) and   | demo    | onstrat | e    |  |  |
|                | iltering ope <mark>ra</mark> |  |   |           |         | . /     |      |  |  |
|                | -                            | hev IIR filters (LPF/HPF/I                         | 3PF/BSF) and demonst  | trate the | filter  | ing     |      |  |  |
| oper           | ations.                      |  | 2   | 29        |         | 7       |      |  |  |
| US             | ING TMS32                    | 0C5X/TMS320C54XX/T                                 | MS320C67XX (Any (   | 6 Exper   | imen    | ts)     |      |  |  |
|                | hmetic operat                |  |   | 6°        |         | (5)     |      |  |  |
|                |                              |  |   |           |         |         |      |  |  |
|                | -                            | and effect of under samp                           | -   |           |         |         |      |  |  |
|                | uency Analys                 |  |   |           |         |         |      |  |  |
|                | ign of FFT Co                | mutations  | IT 2- ILITE   |           |         |         |      |  |  |
|                | C                            | ar convolutions of two disc                        |   |           |         |         |      |  |  |
|                |                              | stration of FIR Filter for I                       |   | and nase  | sand    |         |      |  |  |
| Ban            | d stop filtering             |  |   | •         |         |         |      |  |  |
|                |                              | nstration of Butter worth an                       |   | rs for L  | ow pa   | iss,    |      |  |  |
| Higl           | n pass, Band p               | ass and Band stop filtering                        |   |           | 1       | 45 1    |      |  |  |
| Course D-      | aionad Dry D                 |  | <b>Total Lecture</b>  | hours     |         | 45 ho   | ours |  |  |
|                | $\mathbf{N}$                 | .J.Vijayakumar                                     |   |           |         |         |      |  |  |

| Mappi | Mapping with Programme Outcomes |     |     |     |     |     |     |     |     |      |  |  |
|-------|---------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|------|--|--|
| COs   | PO1                             | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |  |  |
| CO1   | S                               | S   | L   | S   | S   | L   | S   | S   | М   | S    |  |  |
| CO2   | S                               | S   | L   | M   | S   | L   | M   | S   | S   | S    |  |  |
| CO3   | S                               | S   | L   | М   | S   | L   | М   | S   | S   | S    |  |  |

| Course Code       Do       3       3       3         Pre-requisite       Making students to understand, execute<br>his knowledge in the VLSI work bench,<br>FPGA kit with cadence and xilinix<br>software       Syllabus       2021-22         Course Objectives:       The main objectives of this course are to:       1       1       0       3       3         The main objectives of this course are to:       1       0       1       0       1       0       1       0       2         Course Objectives:       1       0       0       1       0       0       1       0       0       0       0       0       0       0 </th <th>Course code</th> <th>33Q</th> <th>VLSI LABORATORY</th> <th>I.</th> <th>Т</th> <th>Р</th> <th>С</th>   | Course code     | 33Q                        | VLSI LABORATORY  | I.  | Т      | Р       | С    |
|---|-----------------|----------------------------|--|---|--------|---------|------|
| Pre-requisite       his knowledge in the VLSI work bench,<br>FPGA kit with cadence and xilinix       Syllabus<br>Version       2021-22         Course Objectives:   |                 | 55Q                        | VESTEADORATORI   | 0     0       e     Syllabus       version     20   an dynamic industry in the second s |        |         |      |
| The main objectives of this course are to:  1. To prepare the students to be able to have a successful career in dynamic industry that is global, multi-disciplinary, and evolving  2. Develop their engineering skills in problem solving, design and innovation as they work individually and/or in multi-disciplinary teams with sense of professional ethics and social responsibility.  3. Communicate effectively and manage resources skillfully as members and leaders of the profession.  Expected Course Outcomes:  On the successful completion of the course, student will be able to:  1. Understand and develop the test bench code for combinational circuits and sequential circuits  2. Simulate various combinational and sequential logic circuits and verify the simulation with truth table through EDA tools 3. Document the experimental process and corresponding outcomes.  K3 K1 - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create  1. LIST OF EXPERIMENTS (any 12 experiments)  1. VLSI Design flow and the tools used in cadence  1. INVERT 2. Buffer 3. Transmission Gates(TG) 4. Logic Gates AND,OR,NAND,NOR,XOR,XNOR 5. Flip Flops JK,MS,SR,D,T 6. Synchronous Counter 7. Asynchronous Counter 8. Parallel Adder 9. Serial Adder 1. I. PART B: Analog Design PART B[1] : Schematic Simulation: Procedure for creating the schematic simulation   | Pre-requisite   | ;                          | his knowledge in the VLSI work bench,<br>FPGA kit with cadence and xilinix |   |        | 2021    | -22  |
| <ol> <li>To prepare the students to be able to have a successful career in dynamic industry that is global, multi-disciplinary, and evolving</li> <li>Develop their engineering skills in problem solving, design and innovation as they work individually and/or in multi-disciplinary teams with sense of professional ethics and social responsibility.</li> <li>Communicate effectively and manage resources skillfully as members and leaders of the profession.</li> <li>Expected Course Outcomes:         <ul> <li>On the successful completion of the course, student will be able to:</li> <li>Understand and develop the test bench code for combinational circuits and sequential circuits</li> <li>Simulate various combinational and sequential logic circuits and verify the simulation with truth table through EDA tools</li> <li>Document the experimental process and corresponding outcomes.</li> <li>K3</li> <li>K1 - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create</li> </ul> </li> <li>LIST OF EXPERIMENTS (any 12 experiments)</li> <li>I. VLSI Design flow and the tools used in cadence</li> <li>II. PART A: Digital Simulation</li> <li>Procedure for creating digital simulation using Verilog and cadence digital tool</li> <li>I. Inverter</li> <li>Buffer</li> <li>Transmission Gates(TG)</li> <li>Superformous Counter</li> <li>Asynchronous Counter</li> <li>Asynchronous Counter</li> <li>Asynchronous Counter</li> <li>Parallel Adder</li> <li>Serial Adder</li> <li>Serial Adder</li> <li>Parallel Adder</li> <li>Berial Adder</li> <li>Berial Adder</li> <li>Berial Adder</li> </ol>  |                 |                            |  |   |        |         |      |
| global, multi-disciplinary, and evolving         2. Develop their engineering skills in problem solving, design and innovation as they work individually and/or in multi-disciplinary teams with sense of professional ethics and social responsibility.         3. Communicate effectively and manage resources skillfully as members and leaders of the profession.         Expected Course Outcomes:         On the successful completion of the course, student will be able to:         1       Understand and develop the test bench code for combinational circuits and sequential circuits and verify the simulation with truth table through EDA tools         3       Document the experimental process and corresponding outcomes.         K3       K3         K1 - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create         LIST OF EXPERIMENTS (any 12 experiments)         1. VLS1 Design flow and the tools used in cadence         1. PART A: Digital Simulation         Procedure for creating digital simulation using Verilog and cadence digital tool         1. Inverter         2. Buffer         3. Transmission Gates(TG)         5. Flip Flops JK,MS,SR,D,T         6. Synchronous Counter         7. Asynchronous Counter         8. Parallel Adder         9. Serial Adder         9. Serial Adder         9. Serial Adder         9. Serial Adder <td< td=""><td>The main object</td><td>ctives of thi</td><th>s course are to:</th><td></td><td></td><td></td><td></td></td<>   | The main object | ctives of thi              | s course are to:   |   |        |         |      |
| <ul> <li>2. Develop their engineering skills in problem solving, design and innovation as they work individually and/or in multi-disciplinary teams with sense of professional ethics and social responsibility.</li> <li>3. Communicate effectively and manage resources skillfully as members and leaders of the profession.</li> <li>Expected Course Outcomes: <ul> <li>On the successful completion of the course, student will be able to:</li> <li>1 Understand and develop the test bench code for combinational circuits and sequential circuits</li> <li>2 Simulate various combinational and sequential logic circuits and verify the simulation with truth table through EDA tools</li> <li>3 Document the experimental process and corresponding outcomes.</li> <li>K3</li> <li>K1 - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create</li> </ul> </li> <li>LIST OF EXPERIMENTS (any 12 experiments)</li> <li>I. VLSI Design flow and the tools used in cadence</li> <li>II. PART A: Digital Simulation</li> <li>Procedure for creating digital simulation using Verilog and cadence digital tool</li> <li>I. Inverter</li> <li>Buffer</li> <li>Transmission Gates(TG)</li> <li>Sinchronous Counter</li> <li>Asynchronous Counter</li> <li>Parallel Adder</li> <li>Serial Adder</li> <li>Serial Adder</li> <li>Parallel Adder</li> <li>Parallel Adder</li> <li>Procedure for creating the schematic simulation:</li> </ul>  | 1 1             |                            |  | namic i   | ndust  | try tha | t is |
| individually and/or in multi-disciplinary teams with sense of professional ethics and social responsibility. 3. Communicate effectively and manage resources skillfully as members and leaders of the profession.  Expected Course Outcomes: On the successful completion of the course, student will be able to: 1. Understand and develop the test bench code for combinational circuits and sequential circuits 2. Simulate various combinational and sequential logic circuits and verify the simulation with truth table through EDA tools 3. Document the experimental process and corresponding outcomes. K3 K1 - Remember; K2 - Understand; K3 - Apply: K4 - Analyze; K5 - Evaluate; K6 - Create  LIST OF EXPERIMENTS (any 12 experiments) I. VLSI Design flow and the tools used in cadence II. PART A: Digital Simulation Procedure for creating digital simulation using Verilog and cadence digital tool 1. Inverter 2. Buffer 3. Transmission Gates(TG) 4. Logic Gates AND,OR,NAND,NOR,XOR,XNOR 5. Flip Flops JK,MS,SR,D,T 6. Synchronous Counter 7. Asynchronous Counter 8. Parallel Adder 9. Serial Adder III. PART B: Analog Design PART B[1]: Schematic Simulation: Procedure for creating the schematic simulation  |                 |                            |  |   |        | 1       |      |
| responsibility.         3. Communicate effectively and manage resources skillfully as members and leaders of the profession.         Bayential completion of the course, student will be able to:         1       Understand and develop the test bench code for combinational circuits and sequential circuits and sequential circuits and sequential circuits and verify the simulation with truth table through EDA tools         3       Document the experimental process and corresponding outcomes.       K3         KI - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create       IST OF EXPERIMENTS (any 12 experiments)         I. VLSI Design flow and the tools used in cadence       II. PART A: Digital Simulation         Procedure for creating digital simulation using Verilog and cadence digital tool       1. Inverter         2. Buffer       3. Transmission Gates(TG)       Superimental Context (Context (Contex | -               | -                          |  |   |        | •       |      |
| 3. Communicate effectively and manage resources skillfully as members and leaders of the profession.         Expected Course Outcomes:         On the successful completion of the course, student will be able to:         1       Understand and develop the test bench code for combinational circuits and sequential logic circuits and verify the simulation with truth table through EDA tools         3       Document the experimental process and corresponding outcomes.       K3         K1 - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create       LIST OF EXPERIMENTS (any 12 experiments)         I. VLSI Design flow and the tools used in cadence       III. PART A: Digital Simulation         Procedure for creating digital simulation using Verilog and cadence digital tool       1. Inverter         2. Buffer       3. Transmission Gates(TG)       SLUMENDE 2         3. Flip Flops JK,MS,SR,D,T       6. Synchronous Counter       7. Asynchronous Counter         7. Asynchronous Counter       8. Parallel Adder       9. Serial Adder         HI. PART B: Analog Design       PART B[1] : Schematic Simulation:       Procedure for creating the schematic simulation   |                 | •                          | i muni-disciplinary teams with sense of profess                            | ionai ei  | mes    | anu sc  |      |
| profession.  Expected Course Outcomes: On the successful completion of the course, student will be able to:  I Understand and develop the test bench code for combinational circuits and k2 sequential circuits  Simulate various combinational and sequential logic circuits and verify the k3 simulation with truth table through EDA tools Document the experimental process and corresponding outcomes. K3 K1 - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create  LIST OF EXPERIMENTS (any 12 experiments)  I. VLSI Design flow and the tools used in cadence II. PART A: Digital Simulation Procedure for creating digital simulation using Verilog and cadence digital tool  I. Inverter Buffer S. Transmission Gates(TG) Logic Gates AND,OR,NAND,NOR,XOR,XNOR S. Flip Flops JK,MS,SR,D,T 6. Synchronous Counter 7. Asynchronous Counter 8. Parallel Adder 9. Serial Adder III. PART B: Analog Design PART B[1]: Schematic Simulation: Procedure for creating the schematic simulation   |                 |                            | ely and manage resources skillfully as members a                           | and lead  | ers o  | f the   |      |
| On the successful completion of the course, student will be able to:       Image: Completion of the course, student will be able to:         1       Understand and develop the test bench code for combinational circuits and sequential circuits and sequential logic circuits and verify the simulation with truth table through EDA tools       K3         2       Simulate various combinational and sequential logic circuits and verify the simulation with truth table through EDA tools       K3         3       Document the experimental process and corresponding outcomes.       K3         K1 - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create       Image: K6 - Create         LIST OF EXPERIMENTS (any 12 experiments)         I. VLSI Design flow and the tools used in cadence       Image: K6 - Create         INPART A: Digital Simulation         Procedure for creating digital simulation using Verilog and cadence digital tool         1. Inverter       Image: Complex Compl   | profession.     | 1                          |  |   |        |         |      |
| 1       Understand and develop the test bench code for combinational circuits and sequential circuits       K2         2       Simulate various combinational and sequential logic circuits and verify the simulation with truth table through EDA tools       K3         3       Document the experimental process and corresponding outcomes.       K3         K1       - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create         LIST OF EXPERIMENTS (any 12 experiments)         I. VLSI Design flow and the tools used in cadence         II PART A: Digital Simulation         Procedure for creating digital simulation using Verilog and cadence digital tool         1. Inverter       Suffer         3. Transmission Gates(TG)       Suffer         4. Logic Gates AND,OR,NAND,NOR,XOR,XNOR       Flip Flops JK,MS,SR,D,T         6. Synchronous Counter       Synchronous Counter         7. Asynchronous Counter       Serial Adder         9. Serial Adder       Serial Adder         III. PART B: Analog Design         Parcedure for creating the schematic simulation:  |                 |                            |  |   |        |         |      |
| 2       Simulate various combinational and sequential logic circuits and verify the simulation with truth table through EDA tools       K3         3       Document the experimental process and corresponding outcomes.       K3         K1 - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create       Image: Content through EDA tools used in cadence         LIST OF EXPERIMENTS (any 12 experiments)         I. VLSI Design flow and the tools used in cadence         II. PART A: Digital Simulation         Procedure for creating digital simulation using Verilog and cadence digital tool         1. Inverter       2. Buffer         3. Transmission Gates(TG)       Simulation         4. Logic Gates AND,OR,NAND,NOR,XOR,XNOR       5. Flip Flops JK,MS,SR,D,T         6. Synchronous Counter       7. Asynchronous Counter         8. Parallel Adder       9. Serial Adder         II. PART B: Analog Design         PART B[1] : Schematic Simulation:   | 1 Understa      | nd and deve                |  | ts and  |        | K2      | 2    |
| K1 - Remember; K2 - Understand; K3 - Apply; K4 - Analyze; K5 - Evaluate; K6 - Create         LIST OF EXPERIMENTS (any 12 experiments)         I. VLSI Design flow and the tools used in cadence         II. PART A: Digital Simulation         Procedure for creating digital simulation using Verilog and cadence digital tool         1. Inverter         2. Buffer         3. Transmission Gates(TG)         4. Logic Gates AND,OR,NAND,NOR,XOR,XNOR         5. Flip Flops JK,MS,SR,D,T         6. Synchronous Counter         7. Asynchronous Counter         8. Parallel Adder         9. Serial Adder         III. PART B: Analog Design         PART B[1] : Schematic Simulation:         Procedure for creating the schematic simulation  | 2 Simulate      | various con                |  | fy the  |        | K3      | \$   |
| LIST OF EXPERIMENTS (any 12 experiments)  I. VLSI Design flow and the tools used in cadence II. PART A: Digital Simulation Procedure for creating digital simulation using Verilog and cadence digital tool  1. Inverter 2. Buffer 3. Transmission Gates(TG) 4. Logic Gates AND,OR,NAND,NOR,XOR,XNOR 5. Flip Flops JK,MS,SR,D,T 6. Synchronous Counter 7. Asynchronous Counter 8. Parallel Adder 9. Serial Adder III. PART B: Analog Design PART B[1] : Schematic Simulation: Procedure for creating the schematic simulation   | 3 Documer       | nt t <mark>he exper</mark> | imental process and corresponding outcomes.                                |   |        | K3      | 5    |
| I. VLSI Design flow and the tools used in cadence<br>II. PART A: Digital Simulation<br>Procedure for creating digital simulation using Verilog and cadence digital tool<br>1. Inverter<br>2. Buffer<br>3. Transmission Gates(TG)<br>4. Logic Gates AND,OR,NAND,NOR,XOR,XNOR<br>5. Flip Flops JK,MS,SR,D,T<br>6. Synchronous Counter<br>7. Asynchronous Counter<br>8. Parallel Adder<br>9. Serial Adder<br>III. PART B: Analog Design<br>PART B[1] : Schematic Simulation:<br>Procedure for creating the schematic simulation  | K1 - Rememb     | per; <mark>K2</mark> - Ui  | nderstand; K3 - Apply; K4 - Analyze; K5 - Eval                             | uate; K   | 6 - Cı | reate   |      |
| I. VLSI Design flow and the tools used in cadence<br>II. PART A: Digital Simulation<br>Procedure for creating digital simulation using Verilog and cadence digital tool<br>1. Inverter<br>2. Buffer<br>3. Transmission Gates(TG)<br>4. Logic Gates AND,OR,NAND,NOR,XOR,XNOR<br>5. Flip Flops JK,MS,SR,D,T<br>6. Synchronous Counter<br>7. Asynchronous Counter<br>8. Parallel Adder<br>9. Serial Adder<br>III. PART B: Analog Design<br>PART B[1] : Schematic Simulation:<br>Procedure for creating the schematic simulation  |                 |                            |  |   |        |         |      |
| <ul> <li>II. PART A: Digital Simulation</li> <li>Procedure for creating digital simulation using Verilog and cadence digital tool <ol> <li>Inverter</li> <li>Buffer</li> <li>Transmission Gates(TG)</li> <li>Logic Gates AND,OR,NAND,NOR,XOR,XNOR</li> <li>Flip Flops JK,MS,SR,D,T</li> <li>Synchronous Counter</li> <li>Asynchronous Counter</li> <li>Parallel Adder</li> <li>Serial Adder</li> </ol> </li> <li>HI. PART B: Analog Design</li> <li>PART B[1]: Schematic Simulation:</li> </ul>   |                 |                            |  |   |        |         |      |
| <ol> <li>Inverter</li> <li>Buffer</li> <li>Transmission Gates(TG)</li> <li>Logic Gates AND,OR,NAND,NOR,XOR,XNOR</li> <li>Flip Flops JK,MS,SR,D,T</li> <li>Synchronous Counter</li> <li>Asynchronous Counter</li> <li>Parallel Adder</li> <li>Serial Adder</li> <li>III. PART B: Analog Design</li> <li>PART B[1]: Schematic Simulation:</li> <li>Procedure for creating the schematic simulation</li> </ol>   |                 |                            |  | D <sub>lb</sub>   |        | 7       |      |
| <ul> <li>2. Buffer</li> <li>3. Transmission Gates(TG)</li> <li>4. Logic Gates AND,OR,NAND,NOR,XOR,XNOR</li> <li>5. Flip Flops JK,MS,SR,D,T</li> <li>6. Synchronous Counter</li> <li>7. Asynchronous Counter</li> <li>8. Parallel Adder</li> <li>9. Serial Adder</li> <li>III. PART B: Analog Design</li> <li>PART B[1] : Schematic Simulation:</li> <li>Procedure for creating the schematic simulation</li> </ul>  | Procedure fo    | r creating                 | d <mark>igital simulation using Verilog</mark> and cadence c               | ligital t   | ool    | 1       |      |
| <ul> <li>3. Transmission Gates(TG)</li> <li>4. Logic Gates AND,OR,NAND,NOR,XOR,XNOR</li> <li>5. Flip Flops JK,MS,SR,D,T</li> <li>6. Synchronous Counter</li> <li>7. Asynchronous Counter</li> <li>8. Parallel Adder</li> <li>9. Serial Adder</li> <li>III. PART B: Analog Design</li> <li>PART B[1] : Schematic Simulation:</li> <li>Procedure for creating the schematic simulation</li> </ul>   | 1. Inverte      | r Og                       | e.e  |   |        |         |      |
| <ul> <li>4. Logic Gates AND, OR, NAND, NOR, XOR, XNOR</li> <li>5. Flip Flops JK, MS, SR, D, T</li> <li>6. Synchronous Counter</li> <li>7. Asynchronous Counter</li> <li>8. Parallel Adder</li> <li>9. Serial Adder</li> <li>III. PART B: Analog Design</li> <li>PART B[1] : Schematic Simulation:</li> <li>Procedure for creating the schematic simulation</li> </ul>   | 2. Buffer       |                            | S. Commissione   |   |        |         |      |
| <ul> <li>4. Logic Gates AND, OR, NAND, NOR, XOR, XNOR</li> <li>5. Flip Flops JK, MS, SR, D, T</li> <li>6. Synchronous Counter</li> <li>7. Asynchronous Counter</li> <li>8. Parallel Adder</li> <li>9. Serial Adder</li> <li>III. PART B: Analog Design</li> <li>PART B[1] : Schematic Simulation:</li> <li>Procedure for creating the schematic simulation</li> </ul>   | 3. Transm       | ission Gate                | s(TG) & 55 ( users a wind a  |   |        |         |      |
| <ul> <li>5. Flip Flops JK,MS,SR,D,T</li> <li>6. Synchronous Counter</li> <li>7. Asynchronous Counter</li> <li>8. Parallel Adder</li> <li>9. Serial Adder</li> <li>III. PART B: Analog Design</li> <li>PART B[1] : Schematic Simulation:</li> <li>Procedure for creating the schematic simulation</li> </ul>   |                 |                            | OR.NAND.NOR.XOR.XNOR   |   |        |         |      |
| <ul> <li>6. Synchronous Counter</li> <li>7. Asynchronous Counter</li> <li>8. Parallel Adder</li> <li>9. Serial Adder</li> <li>III. PART B: Analog Design</li> <li>PART B[1] : Schematic Simulation:</li> <li>Procedure for creating the schematic simulation</li> </ul>   | -               |                            |  |   |        |         |      |
| <ul> <li>7. Asynchronous Counter</li> <li>8. Parallel Adder</li> <li>9. Serial Adder</li> <li>III. PART B: Analog Design</li> <li>PART B[1] : Schematic Simulation:</li> <li>Procedure for creating the schematic simulation</li> </ul>   | -               | -                          |  |   |        |         |      |
| <ul> <li>8. Parallel Adder</li> <li>9. Serial Adder</li> <li>III. PART B: Analog Design</li> <li>PART B[1] : Schematic Simulation:</li> <li>Procedure for creating the schematic simulation</li> </ul>  | •               |                            |  |   |        |         |      |
| <ul> <li>9. Serial Adder</li> <li>III. PART B: Analog Design</li> <li>PART B[1] : Schematic Simulation:</li> <li>Procedure for creating the schematic simulation</li> </ul>   | •               |                            |  |   |        |         |      |
| III. PART B: Analog Design<br>PART B[1] : Schematic Simulation:<br>Procedure for creating the schematic simulation  |                 |                            |  |   |        |         |      |
| PART B[1] : Schematic Simulation:<br>Procedure for creating the schematic simulation  |                 |                            | esign  |   |        |         |      |
| Procedure for creating the schematic simulation   |                 | -                          | -  |   |        |         |      |
| -   |                 |                            |  |   |        |         |      |
|   |                 | -                          |  |   |        |         |      |

**Total Practical hours** 

45 hours

- 2. Common Source Amplifier Schematic and test Cell View
- 3. Common Drain Amplifier Schematic and test Cell View
- 4. Differential Amplifier Schematic and test Cell View
- 5. Operational Amplifier Schematic and test Cell View
- 6. R-2R DAC Schematic and test Cell View

PART B[1] : Layout Simulation

### Layout Design Rules

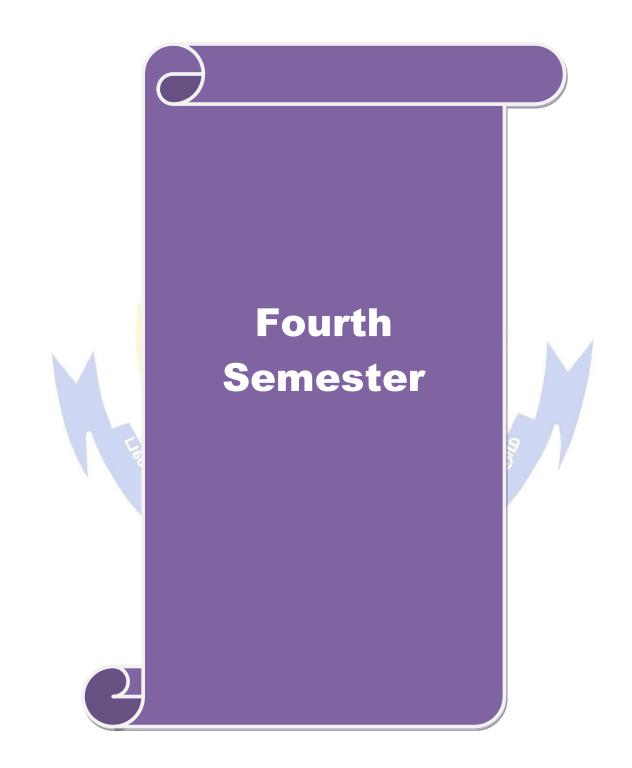
#### Procedure for creating the layout and simulating

- 1. Inverter Layout Design
- 2. Common Source Amplifier Layout Design
- 3. Common Drain Amplifier Layout Design
- 4. Differential Amplifier Layout Design
- 5. Operational Amplifier Layout Design

Course Designed By: Dr. Azha. Periasamy

| Mapping with Programme Outcomes |     |     |     |     |     |     |            |     |            |      |
|---------------------------------|-----|-----|-----|-----|-----|-----|------------|-----|------------|------|
| COs                             | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | <b>PO7</b> | PO8 | <b>PO9</b> | PO10 |
| <b>CO1</b>                      | S   | S   | S   | S   | S   | S   | S          | S   | S          | S    |
| CO2                             | S   | S   | S   | S   | S   | S   | S          | S   | S          | S    |
| CO3                             | S   | S   | S   | S   | S   | S   | S          | S   | S          | S    |

கும் குது இத்தப்பாரை உயர்த்திட குறுக



| Course<br>code | 43A                            | PLC AND ITS APPLICATIONS  | L                    | Т      | Р        | C     |
|----------------|--------------------------------|---|----------------------|--------|----------|-------|
|                | ve/Supportive                  | Core  | 4                    | 0      | 0        | 4     |
| Pre-requi      | site                           | <b>Basic Electrical and Electronics equipment</b><br>operation knowledge is Necessary | Sylla<br>Versi       |        | 2021-2   | 22    |
| Course Ob      | 0                              |   |                      |        |          |       |
|                |                                | s course are to:  |                      |        |          |       |
|                |                                | nowledge of PLC and SCADA   |                      |        |          |       |
|                | -                              | ms from PLC, SCADA functions and Data Handling F                                      |                      | IS.    |          |       |
| 3. Crea        | ite PLC and SCA                | ADA systems in their applications to various industries                               | •                    |        |          |       |
| Expected (     | Course Outcor                  | nes   |                      |        |          |       |
|                |                                | etion of the co <mark>urse, student w</mark> ill be able to:                          |                      |        |          |       |
|                | 1                              | te ladder diagrams from PLC and SCADA function  | ns.                  |        | K6       |       |
|                |                                | and apply PLC and SCADA systems in their appl   |                      | is to  | K4       |       |
|                | is industries                  |   |                      |        |          |       |
| K1 - Reme      | ember; <b>K2 - U</b>           | nderstand; K3 - Apply; K4 - Analyze; K5 - Evalua                                      | ate; K               | 6 - Cr | eate     |       |
|                |                                |   |                      |        |          |       |
| Unit:1         | G                              | Basic PLC Programming   |                      |        | 12 ho    |       |
| General PL     | C programmi.                   | ng procedures - Programming on/off inputs and   | <mark>d o</mark> utp | uts:   | Relatio  | n of  |
| digital gate   | logic to conta                 | act/ coil logic - Creating ladder diagrams from p                                     | process              | s con  | trol     |       |
| descriptions   | s - Log <mark>ic gates.</mark> | PLC Register Basics.  |                      | Å      |          |       |
|                | E                              |   |                      |        |          |       |
| Unit:2         |                                | LC Function and Intermediate Function   |                      |        | 12 ho    |       |
| -              | -                              | n Delay Timer Instruction - Off Delay Timer Ins                                       |                      |        | -        | -     |
|                |                                | own Counter. Math Instruction - Addition - Subtr                                      |                      |        | -        |       |
|                | Number com                     | parison functions - Numbering systems and PL  | C nur                | nber   | convei   | sion  |
| functions.     | 2                              | A A A A A A A A A A A A A A A A A A A   | G                    |        |          |       |
| TI '4 0        |                                |   |                      | -      | 10.1     |       |
| Unit:3         | 25                             | ling Functions and PLC Functions Working W<br>Bits                                    | 1                    |        | 10 ho    |       |
| The PLC S      | KIP and MAS                    | STER CONTROL RELAY functions - JUMP F   | unctio               | ns -   | Data N   | love  |
| Systems - C    | Other PLC Dat                  | a Handling Functions - Digital Bit Functions and                                      | Appli                | cation | ns -     |       |
| Sequencer f    | functions - Cor                | trolling Robot with a PLC - Matrix functions.   |                      |        |          |       |
| Unit:4         | PLC Inst                       | allation Practices, Editing and Troubleshooting                                       | 5                    |        | 12 ho    | urs   |
| PLC Enclos     | sures - Electric               | al Noise - Leaky Inputs and Outputs - Groundin  | g - Vo               | oltage | Varia    | tions |
| -              | -                              | ting - Programming and Monitoring - Preventive  |                      |        |          |       |
| Troublesho     | oting - Connec                 | ting your Personal Computer and Your Programm   | able L               | ogic   | Contro   | ller. |
| Unit:5         |                                | Introduction to SCADA   |                      |        | 12 ho    | urs   |
| SCADA de       | efinitions, SCA                | ADA Functional requirements and components,   | SCA                  | DA 1   | Hierarc  | hical |
| concept, SC    | CADA architec                  | ture, General features, SCADA Applications, Ben                                       | efits. I             | Remo   | te Terr  | ninal |
| Unit (RTU      | ), Interface un                | nits, Human- Machine Interface Units (HMI), I   | Displa               | y Mo   | onitors/ | Data  |
| , ,            |                                | ent Electronic Devices (IED). Introduction - Con                                      | -                    | -      |          |       |
|                | -                              | Control systems and Control panels. Introduction                                      |                      |        |          |       |
|                | CS and SCADA                   |   |                      |        |          |       |
|                |                                |   |                      |        |          |       |

| Un    | it:6 Contemporary Issues   | 2 hours              |  |  |  |  |  |  |
|-------|--|----------------------|--|--|--|--|--|--|
| Intro | oduction to Industrial Automation, Architecture of Industrial Automation | Systems              |  |  |  |  |  |  |
|       | Total Lecture h  | ours 60 hours        |  |  |  |  |  |  |
| Те    | xt Book(s)   |                      |  |  |  |  |  |  |
| 1     | John W. Webb & Ronald A., Reis, "Programmable Logic Controllers F        | rinciples and        |  |  |  |  |  |  |
| 1     | Applications", Fifth Edition, Prentice Hall Publication, New Delhi, 20   | *                    |  |  |  |  |  |  |
| 2     |  |                      |  |  |  |  |  |  |
| 2     | Education Private Limited, 2010.   |                      |  |  |  |  |  |  |
| 3     | Stuart A. Boyer: "SCADA-Supervisory Control and Data Acquisition"        | Instrument Society   |  |  |  |  |  |  |
| 5     | of America Publications,USA,2011   | , mistrument Society |  |  |  |  |  |  |
| 4     | David Bailey, Edwin Wright, Practical SCADA for industry, Newnes,        | 2010                 |  |  |  |  |  |  |
| 4     | David Baney, Edwin Wight, Hactear SCADA for industry, Newnes,            | 2010                 |  |  |  |  |  |  |
| Re    | ference Books  |                      |  |  |  |  |  |  |
| 1     | Michael P.Lukas, "Distributed Control Systems", Van Nostrand Reinf       | old Company,2000     |  |  |  |  |  |  |
| 2     | Gordon Clarke, Deon Reynders: "Practical Modern SCADA Protocols          | : DNP3, 60870.5 and  |  |  |  |  |  |  |
|       | Related Systems", Newnes Publications, Oxford, UK, 2014.                 |                      |  |  |  |  |  |  |
|       |  |                      |  |  |  |  |  |  |
| Re    | lated Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]               |                      |  |  |  |  |  |  |
| 1     | https://nptel.ac.in/courses/108/105/108105088/                           |                      |  |  |  |  |  |  |
| 2     | https://nptel.ac.in/courses/108/105/108105063/                           |                      |  |  |  |  |  |  |
| 3     | http://www.nptelvideos.in/2012/11/industrial-automation-and-control      | html                 |  |  |  |  |  |  |
| 0     |  |                      |  |  |  |  |  |  |
| Co    | urse Designed By: Dr. J. Vijayakumar                                     |                      |  |  |  |  |  |  |

| Mapping with Programme Outcomes |     |     |     |     |     |     |     |      |     |      |
|---------------------------------|-----|-----|-----|-----|-----|-----|-----|------|-----|------|
| COs                             | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8  | PO9 | PO10 |
| CO1                             | S   | S29 | S   | S   | S   | M   | S   | CS S | S   | S    |
| CO2                             | S   | S 📎 | S   | S   | S   | S   | S   | S    | S   | S    |

\*S-Strong; M-Medium; L-Low

Page 40 of 72

| 0                |                               |   |                                       | T                | T      | n                   |               |
|------------------|-------------------------------|---|---------------------------------------|------------------|--------|---------------------|---------------|
| Course<br>code   | 43P                           | PLC, SCADA LABO   | RATORY                                |                  | T<br>0 | P<br>3              | C<br>3        |
| Pre-requi        | site                          | Basic Electrical and Electro<br>operation knowledge is Necc       |                                       | Syllab<br>Versio |        | 2021-               | 22            |
| Course Ob        | jectives:                     |   | N N N N N N N N N N N N N N N N N N N | 1                | 1      |                     |               |
|                  | bjectives of thi              |   |                                       |                  |        |                     |               |
|                  | *                             | nowledge of PLC and SCADA   |                                       |                  |        |                     |               |
|                  |                               | ams from PLC, SCADA functi  |                                       |                  | nctio  | ns                  |               |
| <b>3</b> . Crea  | ale PLC and SC                | ADA systems in their applicat                                     | ions to various ind                   | ustries.         |        |                     |               |
| Expected C       | Course Outcor                 | es:   |                                       |                  |        |                     |               |
|                  |                               | tion of the course, student will                                  | be able to:                           |                  |        |                     |               |
|                  | 1                             | e ladder diagrams from PLC a                                      |                                       | ons.             |        | K2                  |               |
| 2 Under          | rstand, anal <mark>yze</mark> | and apply PLC and SCADA   | systems in their ap                   | plicatio         | ons    | K4                  |               |
|                  | ious in <mark>dustries</mark> | A Second  | VENE                                  |                  |        |                     |               |
| <b>K1</b> - Reme |                               | derstand; K3 - Apply; K4 - A                                      |                                       | ate; K6          | - Cre  | eate                |               |
| 1 D              |                               | ST OF EXPERIMENTS(any   | 12 experiments)                       |                  |        |                     |               |
|                  |                               | Gates Function in PLC   |                                       |                  |        |                     |               |
| -                | U                             | ematical Operations in PLC  | · · · NG                              |                  |        |                     |               |
| -                |                               | -to-subroutine & return operat                                    |                                       |                  |        |                     |               |
|                  |                               | e control circuit for dynamic b                                   | raking of DC moto                     | r using          | ladde  | er                  |               |
|                  |                               | er and UP/Down Counter).  |                                       | 13               |        |                     |               |
|                  | -                             | e control circuit for Conveyor                                    |                                       |                  |        |                     |               |
|                  | -                             | circuit for automatic tank filli                                  |                                       | NT /             | -      | _                   |               |
|                  | =                             | circuit for automatic Traffic I                                   |                                       |                  | -      |                     |               |
|                  | -                             | circuit for automatic Bottle fi                                   |                                       | orogram          | ming   |                     |               |
|                  | -                             | atic Vehicle parking using lade<br>e control circuit for Conveyor |                                       |                  |        |                     |               |
|                  | -                             |   |                                       |                  |        |                     |               |
|                  | *                             | circuit for automatic tank filli                                  |                                       | •                |        |                     |               |
|                  | -                             | circuit for automatic Traffic I                                   |                                       | •                |        |                     |               |
|                  |                               | circuit for automatic Bottle fi                                   |                                       | a system         | 1.     |                     |               |
|                  | *                             | atic Vehicle parking using SCA with SCADA system.                 | ADA system.                           |                  |        |                     |               |
|                  | •                             | •   | r control process                     |                  |        |                     |               |
| ro. mtei         |                               | with SCADA system for moto  | Total Lecture                         | houre            |        | 45 ho               | nire          |
| Course De        | signed By: Dr.                | .Vijayakumar  |                                       | 10013            |        | <del>-1</del> 5 III | <i>i</i> ui 3 |
|                  | <u> </u>                      |   |                                       |                  |        |                     |               |

# Mapping with Programme Outcomes

| COs | <b>PO1</b> | PO2 | PO3 | PO4 | PO5 | PO6 | <b>PO7</b> | PO8 | PO9 | PO10 |
|-----|------------|-----|-----|-----|-----|-----|------------|-----|-----|------|
| CO1 | S          | S   | S   | S   | S   | S   | S          | S   | S   | S    |
| CO2 | S          | S   | S   | S   | М   | S   | М          | S   | S   | S    |



| Course<br>code      | 1EA                          | ELECTRONIC TEST INSTRUMENTS   | L                    | Т        | Р            | С            |
|---------------------|------------------------------|---|----------------------|----------|--------------|--------------|
| <b>Core/Electiv</b> | ve/Supportive                | Elective  | 4                    | 0        | 0            | 4            |
| Pre-requi           | site                         | In depth study about basic electronic<br>devices, active and passive circuit<br>devices, wave shaping instruments,<br>test and measurements | Sylla<br>Versi       |          | 2021         | l <b>-22</b> |
| Course Ob           | jectives:                    |   |                      |          | I            |              |
|                     |                              | s course are to:  |                      |          |              |              |
| 1. Dev              | elop skills to               | become professional technician with capabili  | ty to 1              | neasu    | ire ele      | ctrical      |
| pai                 | rameters using               | various instruments.  |                      |          |              |              |
| 2. By 1             | learning this c              | ourse students will able to know basics of var  | ious Ir              | strum    | nents,       |              |
| tra                 | nsducers and                 | working of electronic circuits used in electror   | nic test             | and      | measu        | ring         |
| ins                 | truments                     | 0)55500   |                      |          |              | -            |
|                     |                              | 100 00 00 00 00 00 00 00 00 00 00 00 00   |                      |          |              |              |
|                     | Course Outcon                |   |                      |          |              |              |
| 1                   |                              | etion of the course, student will be able to:   |                      |          |              |              |
|                     |                              | etrical parameters with accuracy, precision, reso   | lution.              |          | K3           |              |
|                     |                              | l <mark>ges</mark> for relevant parameter measurement.  |                      |          | K3           | , K4         |
|                     |                              | assive or active transducers for measurement of p   | physica (California) | ıl       | K3           |              |
|                     | omenon                       |   |                      |          |              |              |
|                     | •                            | r, frequency counter, CRO and digital IC tester   | for                  |          | K3,K4        |              |
|                     | priate measure               |   |                      |          |              |              |
| 5 Test a            | and troubleshoe              | ot electronic circuits using various measuring ins  | trumer               | nts      | K3,K4,<br>K5 |              |
| 6 Maint             | ain various <mark>typ</mark> | es of test and measuring instruments.   |                      |          | K3           |              |
| K1 - Reme           | ember; K2 - <mark>U</mark> 1 | nderstand; K3 - Apply; K4 - Analyze; K5 - Eval  | uate; I              | <u> </u> | reate        |              |
|                     | E                            | 2   | X                    | 2        |              |              |
| Unit:1              |                              | aracteristics of measurements and bridges   | S                    |          |              | ours         |
| Accuracy,           | precision, reso              | lution, error and noise, Types of errors, Limitiz   | ng of                | errors   | ,Whea        | tstone       |
| bridge, Kelv        | vin's double bri             | idge, <mark>Max</mark> well's <mark>bridge, Hay bri</mark> dge, Schering bri  | dge.                 |          |              |              |
|                     |                              |   |                      |          |              |              |
| Unit:2              |                              | Basic parameter measurements  |                      |          |              | iours        |
| e                   | •                            | g iron type instruments,DC and AC voltmet   | ·                    |          |              |              |
| (DVM), Ty           | pes-ramp type                | , integrating type and successive approximation   | type I               | OVMs     | ,Watt        | meter,       |
| Energy met          | er, clip-on met              | er,Hot wire instrument, LCR-Q meter : Basic ci  | rcuit, a             | pplic    | ations,      | Series       |
| and parallel        | •                            |   |                      |          |              |              |
|                     | 1                            |   |                      |          |              |              |
| Unit:3              |                              | Oscilloscopes   |                      | <u> </u> |              | ours         |
|                     | *                            | and Inductor. Block diagram of CRO, Cathod  | •                    |          |              |              |
| -                   | -                            | les, Vertical deflection system, Horizontal defle   |                      | -        |              | •            |
| Measureme           | nt of frequence              | y, time delay, phase angle and modulation in  | dex(tra              | apezo    | idal m       | ethod,       |
| Oscilloscop         | e probe: struct              | ture of 1:1 and 10:1 probes, multiple trace CRO   | ), Digi              | tal sto  | orage        |              |
| oscilloscop         | e and its feature            | es.   |                      |          |              |              |
| <b>^</b>            |                              |   |                      |          |              |              |
| Unit:4              |                              | Transducers   |                      |          |              | nours        |
| Classification      | on of transduce              | ers, Unbounded strain gauge, Displacement trans   | ducers,              | LVD      | T,Capa       | acitive      |

transducers,Inductive transducers,Resistive and capacitive touch screen transducer used in mobile,Resistive and capacitive touch screen transducer used in mobile,Velocity transducer,RPM measurement technique, Temperature measurement: Thermocouples: See beck, Peltier Effect, J,K,R,S,T Types, Thermistors,Resistance thermometer RTDs –PTC,PT-100 (2-3-4 Wire systems-only circuit).

| Unit:5   | Test and measuring instruments  | 12 hours     |  |  |  |  |  |  |  |  |
|--|---|--------------|--|--|--|--|--|--|--|--|
| Function g   | enerator, Audio frequency signal generation, Sweep frequency generator                              | r, Pulse and |  |  |  |  |  |  |  |  |
| square w   | ave generator, Simple frequency counter, Display counter,   | Cascading    |  |  |  |  |  |  |  |  |
| counters,M   | counters, Multiplexing of display in frequency counter, Digital IC tester, Logic analyzer, Spectrum |              |  |  |  |  |  |  |  |  |
| analyzer, Harmonic distortion analyzer, Field strength meter (dB meter). |   |              |  |  |  |  |  |  |  |  |

Unit:6Contemporary Issues2 hoursData acquisition systems for personal computer: Essential features of Data acquisition boards -<br/>The Dasylab Data acquisition and processing software .>

|    | Total Lecture hours62 hours  |
|----|--|
| Te | tt Book(s)   |
| 1  | Electronic Instruments and Measurement Techniques, Cooper, W.D. Halfrick, A.B.PHI            |
|    | Learning, New Delhi, latest edition  |
| 2  | Electrical and Electronic Measurements, Sahani, A.K.,Dhanpat Rai, New Delhi, latest          |
|    | edition  |
| 3  | Elements of Electronic Instrumentation and Measurement, Joseph, J. Carr, Pearson, New Delhi, |
|    | latest edition   |
| 4  | Electronic Instrumentation and Measurements, David, Bell, PHINew Delhi, latest edition       |

5 Electronic Measurements and Instrumentation, Kishor, K Lal, Pearson, New Delhi, latest edition

#### **Reference Books**

- 1 Michael P.Lukas, "Distributed Control Systems", Van Nostrand Reinfold Company,2000
- 2 Neil Weste & Kamarn Eshrangian, "Principles of CMOS VLSI design" Addison Wesley, 2<sup>nd</sup> Edition, 1998
- 3 Jacob Baker, Harry, David E.Boyce, "CMOS circuit design, layout and simulation" Prentice Hall India, 1998
- 4 Bhasker J. " A VHDL Primer" Pearson Eduction, 3<sup>rd</sup> Edition, 1999
- 5 John Wakerly, "Digital Design Priciples & Practices", 3<sup>rd</sup> Edition, Pearson Education, 2002
- Ernest O Doebelin, Dhanesh N Manik, "Doebelin's Measurement Systems, 6<sup>th</sup> Edition, Tata Mc Graw Hill, India, 2011

#### Related Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]

- 1 Electronic Workbench/MultiSIM/Circuit Maker
- 2 www.ocw.mit.edu
- 3 www.home.agilent.com
- 4 http://www.mhhe.com/doebelin/ms6e
- Course Designed By: Dr.Azha.Periasamy

| Mappi | ng with | Program | mme Ou | itcomes |     |     |     |     |     |      |
|-------|---------|---------|--------|---------|-----|-----|-----|-----|-----|------|
| COs   | PO1     | PO2     | PO3    | PO4     | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |
| CO1   | L       | М       | L      | S       | S   | S   | S   | S   | S   | S    |
| CO2   | L       | M       | L      | S       | S   | S   | S   | S   | S   | S    |
| CO3   | L       | М       | L      | S       | S   | S   | S   | S   | S   | S    |
| CO4   | L       | М       | L      | S       | S   | S   | S   | S   | S   | S    |
| CO5   | L       | М       | L      | S       | S   | S   | S   | S   | S   | S    |
| CO6   | L       | М       | L      | S       | S   | S   | S   | S   | S   | S    |



| Course<br>code                  | 1EA   | <b>BIO MEDICAL INSTRUMENTATION</b>  | L              | Т             | Р              | С      |
|---------------------------------|---|---|----------------|---------------|----------------|--------|
|                                 | ve/Supportive   | Elective  | 4              | 0             | 0              | 4      |
| Pre-requi                       | site  | Making knowledge about the physiology,<br>study of medical equipments, knowing<br>the patient and his safety measures.                  | Sylla<br>Versi |               | 2021           | -22    |
| Course Ob                       | jectives:   |   |                |               |                |        |
| 17. To e<br>18. Prov            | ducate students<br>ride an exposure                   | s course are to:<br>on the various physiological systems of human body<br>to the medical instruments<br>s on the patient safety systems | 7              |               |                |        |
| Expected (                      | Course Outcon   | nes:  |                |               |                |        |
| On the suc<br>1 Under<br>electr | ccessful comple<br>rstand the phys<br>odes used in th | etion of the course, student will be able to:<br>ical foundations of biological systems and the v<br>e medical field                    |                |               | K2             |        |
| measu                           | arements in the                                       |   |                |               | K2             |        |
| 3 Gain body                     | knowledge on  | the measurement of non-electrical parameter in t  | the hun        | nan           | K3             |        |
| applic                          | ations  | c concepts of various medical imaging technique   | es and t       | heir          | K2             |        |
|                                 |   | assisting and therapy equipment's   |                |               | K2             |        |
| K1 - Rem                        | ember; <mark>K2 - U</mark>                            | nderstand; K3 - Apply; K4 - Analyze; K5 - Eva   | luate; H       | <u> 6 - C</u> | reate          |        |
| Unit:1                          |   | Physiology and transducers  |                |               | 12 h           | 01115  |
|                                 | iment system.   | problems encountered in measuring a living  | syster         | n. tra        | and the second |        |
|                                 |   | Cell and its structure, resting and action potenti  |                |               |                |        |
|                                 |   | ardiovascular system, electrophysiology of card   |                | /             |                |        |
| •                               |   | bry system, nervous system, Electrode theory, bi  | 433            |               | •              |        |
|                                 |   | Colimbatore   | - /-           |               |                |        |
| Unit:2                          |   | Electrophysiological measurement  |                |               |                | ours   |
| •                               |   | ethods and typical waveforms of ECG, Vector<br>hods and typical waveforms of EMG,ERG,EOC  | -              | graphy        | , EEG          | Lead   |
| Unit:3                          | Ν   | on electrical parameter measurements  |                |               | 12 h           | ours   |
| Measureme                       |   | essure, blood flow and cardiac output, plethysmo  | ograph         | y Mea         | surem          | ent of |
| heart sound                     | s, Gas Analyze  | ers, Blood gas analyzers, Oximeters   |                |               |                |        |
| Unit:4                          |   | Medical Imaging and Telemetry   |                |               | 10 h           | ours   |
|                                 |   | iography, computer tomography, MRI, Diagn<br>nce tomography, thermography, biotelemetry   | nostic         | ultras        | ound,          | PET,   |
| Unit:5                          |   | Assisting and therapeutic device  |                |               | 12 h           | ours   |
|                                 | . Defibrillators                                      | s, Ventilator, Heart lung machine, Kidney mach  | nine. D        | iather        |                |        |
|                                 |   | pmedicine, Discussion of research papers on the   |                |               | •              |        |
| -                               |   | various aspects.  |                |               | ••             |        |
|                                 |   | <b>r</b>  |                |               |                |        |

| Robotics in medical industry: Industrial and non-industrial robots, remote controlled robot typical examples of automated industries.         Total Lecture hours         Total Lecture hours         Control Lecture hours         Total Lecture hours         Control Lecture hours         Mathematical Instrumentation" 2 <sup>nd</sup> Edition, Tata Mc Grave 101         Control Sensing vision and intelligence, Graw Hill 2008         And M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015         Reference Books | 2 hours  |
|---|----------|
| Total Lecture hours       Total Lecture hours         Text Book(s)       I         1       Leslie Cromwell, Fred, J.Weibell and Erich A. Pleiffer, "Biomedical Instrumentation Measurements" 2 <sup>nd</sup> Edition, Prentice Hall of India, 2014         2       Kandpur, R.S. "Handbook of Biomedical Instrumentation" 2 <sup>nd</sup> Edition, Tata Mc Graver 2011         3       K.S.Fu,R.C. Gonazlez, CSG, Lee Robotics, Control sensing vision and intelligence, Graw Hill 2008         4       M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015  | ts,      |
| Text Book(s)         1       Leslie Cromwell, Fred, J.Weibell and Erich A. Pleiffer, "Biomedical Instrumentation Measurements" 2 <sup>nd</sup> Edition, Prentice Hall of India, 2014         2       Kandpur, R.S. "Handbook of Biomedical Instrumentation" 2 <sup>nd</sup> Edition, Tata Mc Graw Hill 2008         3       K.S.Fu,R.C. Gonazlez, CSG, Lee Robotics, Control sensing vision and intelligence, Graw Hill 2008         4       M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015   |          |
| Text Book(s)         1       Leslie Cromwell, Fred, J.Weibell and Erich A. Pleiffer, "Biomedical Instrumentation Measurements" 2 <sup>nd</sup> Edition, Prentice Hall of India, 2014         2       Kandpur, R.S. "Handbook of Biomedical Instrumentation" 2 <sup>nd</sup> Edition, Tata Mc Graw Hill 2008         3       K.S.Fu,R.C. Gonazlez, CSG, Lee Robotics, Control sensing vision and intelligence, Graw Hill 2008         4       M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015   |          |
| <ol> <li>Leslie Cromwell, Fred, J.Weibell and Erich A. Pleiffer, "Biomedical Instrumentation<br/>Measurements" 2<sup>nd</sup> Edition, Prentice Hall of India, 2014</li> <li>Kandpur, R.S. "Handbook of Biomedical Instrumentation" 2<sup>nd</sup> Edition, Tata Mc Graven 2011</li> <li>K.S.Fu,R.C. Gonazlez, CSG, Lee Robotics, Control sensing vision and intelligence,<br/>Graw Hill 2008</li> <li>M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015</li> </ol>  | 50 hours |
| Measurements" 2 <sup>nd</sup> Edition, Prentice Hall of India, 2014         2       Kandpur, R.S. "Handbook of Biomedical Instrumentation" 2 <sup>nd</sup> Edition, Tata Mc Gr. 2011         3       K.S.Fu,R.C. Gonazlez, CSG, Lee Robotics, Control sensing vision and intelligence, Graw Hill 2008         4       M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015  |          |
| <ul> <li>2 Kandpur, R.S. "Handbook of Biomedical Instrumentation" 2<sup>nd</sup> Edition, Tata Mc Gr. 2011</li> <li>3 K.S.Fu,R.C. Gonazlez, CSG, Lee Robotics, Control sensing vision and intelligence, Graw Hill 2008</li> <li>4 M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015</li> </ul>   | on and   |
| 2011         3       K.S.Fu,R.C. Gonazlez, CSG, Lee Robotics, Control sensing vision and intelligence,<br>Graw Hill 2008         4       M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015   |          |
| <ul> <li>K.S.Fu,R.C. Gonazlez, CSG, Lee Robotics, Control sensing vision and intelligence,<br/>Graw Hill 2008</li> <li>M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015</li> </ul>  | aw Hill, |
| Graw Hill 2008         4         M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015   |          |
| Graw Hill 2008         4         M.Arumugam, "Biomedical Instrumentation" Anuradha Publications, 2015   | Tata Mc  |
|   |          |
|   |          |
|   |          |
| 1 John G.Webster, Editor, "Medical Instrumentation, Application and Design" John V  | Wiley    |
| and Sons Inc. 2009  | 2        |
| 2 Morelli S Salerno S, Ahmed H, Piscioneri A, DeBartolo L, "Recent strategies com   | bining   |
| biomaterials and Stem cells for bone, liver and skin Regenerations" Current stem ce   | •        |
| Research & therapy, 2016  |          |
|   |          |
| Related Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]  |          |
| 1 https://nptel.ac.in/courses/127/106/127106134/  |          |
| 2 https://nptel.ac.in/courses/108/105/108105101/  |          |
| 3 https://swayam.gov.in/nd1_noc19_ge33/preview  |          |
| 4 https://swayam.gov.in/nd1_noc19_bt28/preview  |          |
|   |          |
| Course Designed By: Dr. Azha. Periasasmy  | 1        |

# Coimbatore

| Марр | ing wit | h Progi | ramme | Outcor | nes | a H | N EP       |     |     |      |
|------|---------|---------|-------|--------|-----|-----|------------|-----|-----|------|
| COs  | PO1     | PO2     | PO3   | PO4    | PO5 | PO6 | <b>PO7</b> | PO8 | PO9 | PO10 |
| CO1  | S       | M       | S     | М      | S   | М   | S          | S   | S   | S    |
| CO2  | S       | M       | S     | М      | S   | M   | S          | S   | S   | S    |
| CO3  | S       | M       | S     | М      | S   | M   | S          | S   | S   | S    |
| CO4  | S       | М       | S     | М      | S   | M   | S          | S   | S   | S    |
| CO5  | S       | Μ       | S     | М      | S   | Μ   | S          | S   | S   | S    |

| Course code   | 1EA   | POWER PLANT INSTRUMENTATION   | L                    | Т       | P         | С     |
|---|---|---|----------------------|---------|-----------|-------|
| Core/Elective/S   | upportive   | Elective  | 4                    | 0       | 0         | 4     |
| Pre-requisite   |   | Basic knowledge in instrumentation  | Sylla<br>Versi       |         | 2021      | -22   |
| <b>Course Object</b>  |   |   |                      |         |           |       |
| The main object   | ctives of thi   | s course are to:  |                      |         |           |       |
| <ul><li>power plat</li><li>2. Learn the environme</li><li>3. Gain the k</li></ul> | nts and con<br>practices for<br>ental condit<br>mowledge of | rocesses and cycles followed in Thermal Power P<br>aponents used in the power plants<br>llowed in Thermal Power Plant and Nuclear Pow<br>ions and the safety measures<br>on steam power plants, steam generators and gas t<br>and fluidized bed combustion, ash handling syst | ver Plan<br>aurbine  | ıts, to | bette     |       |
| -   |   | on Power Load calculation, distribution and optim   |                      | ding    | . etc.,   |       |
|   | -   | COLORAD COLORAD   |                      | 2       |           |       |
| Expected Cou  | rse Outcon  | nes:  |                      |         |           |       |
| On the succes   | sful co <mark>mple</mark>                                   | tion of the course, student will be able to:  |                      |         |           |       |
| nuclear   | power plan  | ses and cycles followed in Thermal Power Plants<br>ts and components used in the power plants and i<br>ter efficiency.  |                      |         | K4        | ł     |
| generate<br>the therr   | ors <mark>and gas</mark><br>mal losses.                     | ge gained by analyzing the steam power plants, s<br>turbine power plants, to improve the efficiency and   | nd redu              |         | K3        | 3     |
| 3 Develop<br>instrume   |   | ds for the Economies of Power Generation and P  | <mark>owe</mark> r p | lant    | Ke        | 5     |
| 4 Apply t<br>Distribu   |   | lge in calculating the Power Load Calculations  | s and                |         | K         | 3     |
|   |   | nderstand; K3 - Apply; K4 - Analyze; K5 - Evalu   | ate; K               | 5 – C   | reate     |       |
| Unit:1  | CA<br>CA  | Fundamentals Of Power Plant   |                      | _       | /<br>0 h/ | ours  |
|   | of Power  | Plant- Energy and Power- Power Distribution i   | n India              | - Po    |           | Jurs  |
| generation- P   | ower corpo  | rations- Classifications of Power Plant Cycle- F<br>Condenser- Turbines.  |                      |         |           | ion-  |
|   |   | 55ULITON 2-MIL  |                      |         | 111       |       |
|   | Automatic 1   | Steam Power Plant<br>er Plant Equipment- Coal handling- Fuel Burning<br>Boiler Control- Pulverized Coal- Water Walls-<br>Collectors.  |                      |         |           | od of |
| Unit:3  |   | Steam Generator   |                      |         | 12 ho     | ours  |
|   |   | Boilers- Cochran Boiler- Lancashire Boiler-<br>ement of Good Boiler- High Pressure Boiler.  | Locon                | notiv   | e Boi     | iler- |
| Unit:4  |   | Steam Turbine   |                      |         | 12 ho     | ours  |
| Impulse Turb<br>Reaction Turb   | ine- Compo<br>pine- Steam                                   | nd operation of steam Turbine- Classification of<br>ound Impulse Turbine- Pressure Compound Imp<br>n Turbine Governing- Steam Turbine Testing- G<br>Generators- Steam Turbine Specifications.   | ulse Tu              | ırbine  | e- Imp    |       |

| Unit:5        | Nuclear Power Plant And Pollution Control                        | 14 hours            |
|---------------|--|---------------------|
| Atomic Strue  | cture- Nuclear Energy Concepts and Terms- Nuclear Fusion and     | nd Fission- Nuclear |
|               | mparison of Nuclear Power Plant and Steam Power Plant.           |                     |
| Environment   | al Pollution due to Energy use, Industrial Trail Emission and Ro | ad Transport Noise  |
| Pollution and | l Control- Pollution due to Combustion of fuel- Air Pollution    | and water pollution |
| by thermal po | ower plants- Radiations from Nuclear Power Plant Effluents.      |                     |
| Unit:6        | Contemporary Issues  | 2 hours             |
| Hydroelectric | e power plants, Hydro turbines                                   |                     |
|               | Total Lecture hours  | 60 hours            |
|               |  | 00 11001 5          |
| Text Book(s)  |  | : 1: 2000           |
|               | ant Engineering, A.K. Raja, Amit Prakash Srivastava, Manish D    |                     |
|               | ant Instrumentation, K. Krishnaswamy, M. Ponni Bala, Prentice    |                     |
| 3 Power Pla   | ant Instrumentation and Controls, Philip Kiameh, McGraw-Hill,    | 2014                |
|               |  |                     |
| Reference B   |  |                     |
|               | ant Performance, A.B.Gill, Elsevier India, New Delhi, 2003.      |                     |
|               | Boiler Operations, S.M.Elonko and A.L.Kohal, McGraw Hill, N      | ew Delhi, 1994      |
|               | trol of Boiler, Sam G. Duke Low, ISA Press, 1991.                |                     |
| 4 Mechani     | cal and Industrial Measurements, R.K.Jain, Khanna Publishers,    | New Delhi, 1995     |
|               |  |                     |
|               | ine Contents [MOOC, SWAYAM, NPTEL, Websites etc.]                |                     |
| A             | ptel.ac.in/courses/112/107/112107291/                            |                     |
|               | /ww.energy.gov/eere/water/types-hydropower-plants                |                     |
| 3 https://w   | /ww.nationalgeographic.org/encyclopedia/hydroelectric-energy/    |                     |
| C D :         |  | 3                   |
| Course Desig  | ned By: Dr. Sujith Raman   | 9                   |
|               | SALAN SHAD INNY AND  |                     |

| Mappir | ng with l  | Program | me Out | comes |     |      |            | 0.0        | 1   |      |
|--------|------------|---------|--------|-------|-----|------|------------|------------|-----|------|
| COs    | <b>PO1</b> | PO2     | PO3    | PO4   | PO5 | PO6  | <b>PO7</b> | <b>PO8</b> | PO9 | PO10 |
| CO1    | L          | S       | L/ C   | S     | L   | L    | L          | S          | S   | S    |
| CO2    | L          | S       | L 🧐    | M     | L   | PLUI | L          | S          | S   | S    |
| CO3    | L          | S       | L      | EM    | S   | STE  | L          | S          | S   | S    |
| CO4    | L          | S       | L      | M     | S   | М    | L          | S          | S   | S    |

| Course code                        | 2EB                         | COMMUNICATION SYSTEM AND<br>FIBER OPTICS  | L              | Т      | Р               | С     |
|------------------------------------|-----------------------------|---|----------------|--------|-----------------|-------|
| Core/Elective/S                    | upportive                   | Elective  | 4              | 0      | 0               | 4     |
| Pre-requisite                      | ••                          | Basic knowledge in Communication  | Sylla<br>Versi |        | 2021            | -22   |
| <b>Course Object</b>               | ives:                       |   |                | -      |                 |       |
| The main object                    | tives of thi                | s course are to:  |                |        |                 |       |
| 1. Understan<br>transmissi         |                             | optic concepts and identify the elements of an o  | ptical fi      | ber    |                 |       |
| 2. Understan                       | d optical fil               | per structure, wave guiding and fabrication   |                |        |                 |       |
| 3. Understan                       | d the variou                | is modes in slab waveguide, step index fiber and  | l graded       | inde   | x fiber         | •     |
| Expected Cou                       | rse Outcon                  | 105'  |                |        |                 |       |
| A                                  |                             | tion of the course, student will be able to:  |                |        |                 |       |
| 1 Understa                         | and the co                  | ncepts of different modes in step index fiber   | and gra        | ded    | K2              | 2     |
| index fit                          |                             |   |                |        |                 |       |
|                                    |                             | les of operation and properties of optoelectronic<br>las the signal guiding characteristics of glass fil                                |                |        | K <sup>2</sup>  | 1     |
| K1 - Rememb                        | er; <mark>K2</mark> - U1    | nderstand; K3 - Apply; K4 - Analyze; K5 - Eval  | uate; K        | 6 – C  | reate           |       |
|                                    | 461                         |   |                |        |                 |       |
| Unit:1                             |                             | Linear Modulation   |                |        | 9 ho            | ours  |
| Modulation To                      | ech <mark>niques</mark> -   | Munication system – Need for Modulation<br>- AM – frequency spectrum – Representation of<br>SC - SSB – Suppression of unwanted sideband | AM - P         |        |                 |       |
| Unit:2                             | 2                           | Angle And Pulse Modulation  | 10             | 1      | 12 ho           | ours  |
|                                    |                             | m – Pre-emphasis and De-emphasis – FM M<br>- Pulse Modulation: PAM, PWM, PPM, PCM.  | ethods:        | Direc  | et met          | hod,  |
| Unit:3                             | - V)                        | Padia Dessivers And Transmitters  | 50             |        | 11 h.           |       |
|                                    | ere classi                  | <b>Radio Receivers And Transmitters</b><br>fication – low level and high level –FM transmi  | tter R         | dia    | 11 ho<br>Receiv |       |
|                                    |                             | terodyne receiver –AM Receiver – envelop de   |                |        |                 |       |
|                                    |                             | M demodulators. UIT 600 2-41  |                |        |                 |       |
|                                    |                             | EDUCATE TO ELEVALE  |                |        |                 |       |
| Unit:4                             |                             | Optical Fiber   |                |        | 14 ho           |       |
|                                    |                             | active index – Snell"s Law – Total internal refle   |                |        |                 |       |
|                                    |                             | v optics representation -Numerical Aperture -   |                |        |                 |       |
| -                                  |                             | k fiber structure – Fibre materials and propertie   | -              | -      |                 |       |
| · ·                                |                             | of attenuation - Attenuation units - scattering   | and abs        | orptio | on los          | ses - |
| core & claddin                     | ng losses -                 | Bending losses.   |                |        |                 |       |
| Unit:5                             |                             | Optical Sources   |                |        | 12 ho           | ours  |
| LED: LED str                       | ructures, L                 | ight source materials, Quantum efficiency,  | Modulat        | ion (  |                 |       |
| Transient respo<br>resonant freque | onse, Power<br>encies, stru | -Bandwidth Product. LASER Diodes: Modes and cture and radiation pattern, Single mode lase   | nd thresh      | nold o | conditi         | ions, |
| Diodes, Tempe                      |                             | 515.  |                |        |                 |       |
|                                    |                             |   |                |        |                 |       |

5.91- Calo

| Unit:6     | Contemporary Issues   | 2 hours               |
|------------|---|-----------------------|
| Photo a    | etectors, Fourier series  | •                     |
|            |   | 1                     |
|            | Total Lecture hours   | 60 hours              |
| Text B     | pok(s)  |                       |
|            | ctronic Communication Systems, George Kennedy, Bernard Davis &      | SRM Prasanna, Tata    |
| Mc         | Graw Hill , 2011  |                       |
| 2 Opt      | cal Fiber Communications, Gerd Keiser, McGraw Hill, 2017            |                       |
|            |   |                       |
| Refere     | ice Books   |                       |
| 1 Co       | mmunication systems, Simon S. Haykin, Wiley Publication, 2011       |                       |
| 2 Op<br>20 | tical Fiber Communication, J M Senior, Principles & Practice by–Pre | entice Hall of India- |
| 1          | <b>1</b> 00000  |                       |
| Relate     | Online Contents MOOC, SWAYAM, NPTEL, Websites etc.]                 |                       |
| 1 ht       | os://nptel.ac.in/courses/108/104/108104113/                         |                       |
| 2 ht       | ps://nptel.ac.in/courses/117/105/117105143/                         |                       |
|            |   |                       |
| Course     | Designed By: Dr. Sujith Raman                                       |                       |
|            |   |                       |
|            |   |                       |

| mapping | g with P | rogram | me Outc | omes |     |     |     |     | X   |      |
|---------|----------|--------|---------|------|-----|-----|-----|-----|-----|------|
| COs     | PO1      | PO2    | PO3     | PO4  | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |
| CO1     | S        | S      | S       | М    | S   | М   | М   | M   | S   | S    |
| CO2     | S        | S      | S       | M    | S   | M   | М   | S   | S   | S    |

\*S-Strong; M-Medium; L-Low

3153

| code  | <b>2EB</b>  | COMPUTER AIDED<br>INSTRUMENTATION  | L   | Т   | Р  | C  |
|---|---|--|---|---|--|--|
|   | ive/Supportive  |  | 4   | 0   | 0  | 4  |
| Pre-requi   |   | Basic knowledge of analog and digital Systems  | yllal<br>ersi   |   | 2021   | -22  |
| <b>Course Ob</b>  |   |  |   |   |  |  |
|   |   | s course are to:   |   |   |  |  |
|   |   | ous data transmission and computer aided tools that ca   | an b  | e imp   | olemen   | ted  |
|   | ous industrial a  |  |   |   |  |  |
|   |   | nderstanding of the common instrument interfaces, d  | iffei   | ent   |  |  |
|   |   | s and Ethernet.  |   |   |  |  |
|   | Course Outcon   |  |   |   |  |  |
|   |   | etion of the course, student will be able to:  |   |   | K5   |  |
|   |   | d tools for various industrial applications.<br>nunication protocol with PC in real time, different con  |   | 210   | K5<br>K6   |  |
|   |   | ce and idea about Ethernet.  | 111110  | 511   | KU   |  |
|   |   | nderstand; K3 - Apply; K4 - Analyze; K5 - Evaluate   | · KA  | Cr  | ente   |  |
|   |   | iderstand, KS - Appry, K4 - Anaryze, K5 - Evaluate   | , <b>n</b> u  | <b>-</b> CI   | cate   |  |
| Unit:1  | Data Aca  | uisition Systems and Digital Signal Transmission   |   |   | 12 ho  | urs  |
|   |   | $\frac{1}{100}$ single and multichannel DAS – A/D and D/A conv   | erte  | rs = 1  |  |  |
|   |   |  |   |   | -  |  |
| -   |   | mple and Hold Circuit – Anti-aliasing filter –Introd   |   |   |  |  |
| -   | -   | luction to protocols and standards - Data Transmiss  | ion   | syste   | ms – I   | ulse   |
|   | ts – An <mark>alog</mark> and   | d Digital modulation Techniques .  |   |   | $\mathbf{A}$   |  |
| Unit:2  |   | Telemetry and Industrial Ethernet  |   |   | 12 ho  |  |
| Telemetry :   | systems – R <mark>F</mark>  | network analyzer – Higher frequency signal sourc   | es -  | - Intr  | oduction   | on to  |
| wireless co   | mmunication -   | Introduction-IEEE standards – Ethernet MAC laye  | er –  | IEEE  | E 802.2  | 2 and  |
| Ethernet SN   | IAP – OSI a <mark>nc</mark>   | l IEEE 802.3 standard. Ethernet transceivers, Ethern   | et ty   | pes,  | switch   | ~~ P-  |
| switching h   | ubs, 10 Mbps  |  |   |   |  | $les \alpha$   |
| -   |   | Ethernet, 100 Mbps Ethernet, Gigabit Ethernet. TC  | 1 AL 1  | ove   | rview-   |  |
| internet lay  | er protocols – I  | Ethernet, 100 Mbps Ethernet, Gigabit Ethernet. TC<br>Host-to-Host layer.   | 1 AL 1  | ove   | rview-   |  |
| internet lay  | er protocols – I  | Ethernet, 100 Mbps Ethernet, Gigabit Ethernet. TC<br>Host-to-Host layer.   | 1 AL 1  | ove   | rview-   |  |
| Unit:3  |   |  | 1 AL 1  | ove   | rview-   | -  |
| Unit:3<br>Current loc<br>Networking   | op, RS 232c/R<br>Basics for ind   | Host-to-Host layer.  | XI,   | SCX<br>2, IEC   | <b>12 ho</b><br>I and  | urs<br>PXI:  |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe   | op, RS 232c/R<br>Basics for ind   | Host-to-Host layer.<br><b>Common Instrument Interfaces</b><br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Instrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MO   | XI,   | SCX<br>2, IEC   | <b>12 ho</b><br>I and<br>C/ISA I   | urs<br>PXI:<br>Field   |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4   | pp, RS 232c/R<br>Basics for ind<br>e and Bluetoot   | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Justrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MO<br>Devicenet   | XI,<br>422<br>D B   | SCX<br>2, IEC<br>US.  | 12 ho<br>I and<br>C/ISA I<br>11 ho   | urs<br>PXI:<br>Field   |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4<br>Overview -   | op, RS 232c/R<br>Basics for ind<br>e and Bluetoot<br>- layers. Profi  | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>lustrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MO<br>Devicenet<br>ibus-overview-protocol stack. HART protocol –Fo  | XI,<br>422<br>D B   | SCX<br>2, IEC<br>US.<br>ation   | <b>12 ho</b><br>I and<br>C/ISA I<br><b>11 ho</b><br>I field  | urs<br>PXI:<br>Field   |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4<br>Overview -<br>layers – Er  | pp, RS 232c/R<br>Basics for ind<br>and Bluetoot<br>and Bluetoot   | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Iustrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MO<br>Devicenet<br>ibus-overview-protocol stack. HART protocol –Fo<br>and Diagnostics. Local interconnect networks, Redu  | XI,<br>422<br>D B   | SCX<br>2, IEC<br>US.<br>ation   | <b>12 ho</b><br>I and<br>C/ISA I<br><b>11 ho</b><br>field<br>Overvi  | urs<br>PXI:<br>Field<br>bus-<br>ew -   |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4<br>Overview -<br>layers – Eri<br>Actuator- so   | pp, RS 232c/R<br>Basics for ind<br>e and Bluetoot<br>- layers. Profi<br>ror Detection a<br>ensor Interface  | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Justrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MO<br>Devicenet<br>ibus-overview-protocol stack. HART protocol –Fc<br>and Diagnostics. Local interconnect networks, Redu<br>- CAN bus – overview-layers. Device Net and SDS   | XI,<br>422<br>D B<br>ound<br>anda<br>S (Si  | SCX<br>2, IEC<br>US.<br>ation<br>ncy (<br>mart                                    | <b>12 ho</b><br>I and<br>C/ISA I<br><b>11 ho</b><br>field<br>Overvi<br>Distrib   | urs<br>PXI:<br>Field<br>bus-<br>ew –   |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4<br>Overview -<br>layers – Er<br>Actuator- se  | pp, RS 232c/R<br>Basics for ind<br>e and Bluetoot<br>- layers. Profi<br>ror Detection a<br>ensor Interface  | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Iustrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MO<br>Devicenet<br>ibus-overview-protocol stack. HART protocol –Fo<br>and Diagnostics. Local interconnect networks, Redu  | XI,<br>422<br>D B<br>ound<br>anda<br>S (Si  | SCX<br>2, IEC<br>US.<br>ation<br>ncy (<br>mart                                    | <b>12 ho</b><br>I and<br>C/ISA I<br><b>11 ho</b><br>field<br>Overvi<br>Distrib   | urs<br>PXI:<br>Field<br>ours<br>bus-<br>ew –   |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4<br>Overview -<br>layers – Er<br>Actuator- so<br>Systems)-P  | pp, RS 232c/R<br>Basics for ind<br>and Bluetoot<br>- layers. Profi<br>ror Detection a<br>ensor Interface<br>hysical Layer a   | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Instrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MO<br>Devicenet<br>ibus-overview-protocol stack. HART protocol –Fc<br>and Diagnostics. Local interconnect networks, Redu<br>- CAN bus – overview-layers. Device Net and SDS<br>and Wiring Rules- The Data link Layer- The Applicat  | XI,<br>422<br>D B<br>ound<br>anda<br>S (Si  | SCX<br>2, IEC<br>US.<br>ation<br>ncy (<br>mart                                    | <b>12 ho</b><br>I and<br>C/ISA I<br><b>11 ho</b><br>field<br>Overvi<br>Distrib<br>r.   | urs<br>PXI:<br>Field<br>bus-<br>bus-<br>outed  |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4<br>Overview -<br>layers – Er<br>Actuator- se<br>Systems)-P<br>Unit:5  | pp, RS 232c/R<br>Basics for ind<br>e and Bluetoot<br>- layers. Profi<br>for Detection a<br>ensor Interface<br>hysical Layer a<br>PC in  | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Iustrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MOD<br>Devicenet<br>ibus-overview-protocol stack. HART protocol –Foc<br>and Diagnostics. Local interconnect networks, Redu<br>- CAN bus – overview-layers. Device Net and SDS<br>and Wiring Rules- The Data link Layer- The Applicat<br>Real Time Environment and Programming   | CP/II<br>XI,<br>422<br>D B<br>ound<br>anda<br>S (Si<br>tion   | SCX<br>2, IEC<br>US.<br>ation<br>ncy (<br>mart<br>Laye                            | 12 ho<br>I and<br>C/ISA I<br>II ho<br>field<br>Overvi<br>Distrib<br>r.<br>11 ho  | urs<br>PXI:<br>Field<br>bus-<br>bus-<br>buted  |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4<br>Overview -<br>layers – Err<br>Actuator- se<br>Systems)-P.<br>Unit:5<br>Introduction  | pp, RS 232c/R<br>Basics for ind<br>e and Bluetoot<br>- layers. Profi<br>ror Detection a<br>ensor Interface<br>hysical Layer a<br>PC in<br>n-PC system a                                       | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Justrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MOI<br>Devicenet<br>ibus-overview-protocol stack. HART protocol –Foc<br>and Diagnostics. Local interconnect networks, Redu<br>- CAN bus – overview-layers. Device Net and SDS<br>and Wiring Rules- The Data link Layer- The Applicat<br>Real Time Environment and Programming<br>and facilities – PC BUS and signals – Interrupts   | CP/II<br>XI,<br>422<br>D B<br>D D<br>D D<br>D D<br>D D<br>D D<br>D D<br>D D<br>D D<br>D D   | SCX<br>2, IEC<br>US.<br>ation<br>.ncy (<br>mart<br>Laye                           | 12 ho<br>I and<br>C/ISA I<br>Distrib<br>Tield<br>Overvi<br>Distrib<br>r.<br>11 ho<br>cing F                                    | urs<br>PXI:<br>Field<br>bus:<br>bus-<br>buted<br>purs<br>C to                              |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4<br>Overview -<br>layers – Er<br>Actuator- se<br>Systems)-P<br>Unit:5<br>Introduction<br>outside wo                            | pp, RS 232c/R<br>Basics for ind<br>and Bluetoot<br>- layers. Profi<br>ror Detection a<br>ensor Interface<br>hysical Layer a<br>PC in<br>n-PC system a<br>rld – PC in                          | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Instrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MOI<br>Devicenet<br>ibus-overview-protocol stack. HART protocol –Fo<br>and Diagnostics. Local interconnect networks, Redu<br>- CAN bus – overview-layers. Device Net and SDS<br>and Wiring Rules- The Data link Layer- The Application<br>Real Time Environment and Programming<br>and facilities – PC BUS and signals – Interrupts<br>real time environment - Real-Time applications of  | EP/II<br>XI,<br>422<br>D B<br>D D<br>D B<br>D B<br>D D<br>D B<br>D D<br>D B<br>D D<br>D B<br>D D<br>D B<br>D D<br>D B<br>D D<br>D D | SCX<br>2, IEC<br>US.<br>ation<br>ncy (<br>mart<br>Laye<br>nterfa                  | 12 ho<br>I and<br>C/ISA I<br>II ho<br>field<br>Overvi<br>Distrib<br>r.<br>II ho<br>cing F<br>PC b                              | urs<br>PXI:<br>Field<br>bussew -<br>puted<br>puted<br>C to<br>passed                       |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4<br>Overview -<br>layers – Er<br>Actuator- se<br>Systems)-P<br>Unit:5<br>Introduction<br>outside wo<br>distributed             | pp, RS 232c/R<br>Basics for ind<br>and Bluetoot<br>- layers. Profi<br>ror Detection a<br>ensor Interface<br>hysical Layer a<br><b>PC in</b><br>n-PC system a<br>rld – PC in<br>control system | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Instrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MOD<br>Devicenet<br>ibus-overview-protocol stack. HART protocol –Foc<br>and Diagnostics. Local interconnect networks, Redu<br>- CAN bus – overview-layers. Device Net and SDS<br>and Wiring Rules- The Data link Layer- The Applicat<br>Real Time Environment and Programming<br>and facilities – PC BUS and signals – Interrupts<br>real time environment - Real-Time applications of<br>ns – Real time programming: Introduction – Mu | EP/IF<br>XI,<br>3 422<br>D B<br>ound<br>and<br>a<br>S (St<br>tion<br>– Ir<br>of F<br>Ilti-7   | SCX<br>2, IEC<br>US.<br>ation<br>ncy 0<br>mart<br>Laye<br>nterfa<br>PC –<br>Faski | <b>12 ho</b><br>I and<br>C/ISA I<br><b>11 hc</b><br>field<br>Overvi<br>Distrib<br>r.<br><b>11 hc</b><br>cing F<br>PC b<br>ng - | urs<br>PXI:<br>Field<br>bus-<br>buted<br>puted<br>putes<br>PC to<br>pasec<br>Task          |
| Unit:3<br>Current loc<br>Networking<br>Bus, ZigBe<br>Unit:4<br>Overview<br>layers – Eri<br>Actuator- se<br>Systems)-P<br>Unit:5<br>Introduction<br>outside woo<br>distributed<br>Manageme | pp, RS 232c/R<br>Basics for ind<br>and Bluetoot<br>- layers. Profi<br>ror Detection a<br>ensor Interface<br>hysical Layer a<br><b>PC in</b><br>n-PC system a<br>rld – PC in<br>control system | Host-to-Host layer.<br>Common Instrument Interfaces<br>S485, GPIB, interface buses: USB, PCMCIA, V2<br>Instrial automation instrumentation Bus – HART, RS<br>h - Open System interconnection (OSI) model – MOI<br>Devicenet<br>ibus-overview-protocol stack. HART protocol –Fo<br>and Diagnostics. Local interconnect networks, Redu<br>- CAN bus – overview-layers. Device Net and SDS<br>and Wiring Rules- The Data link Layer- The Application<br>Real Time Environment and Programming<br>and facilities – PC BUS and signals – Interrupts<br>real time environment - Real-Time applications of  | EP/IF<br>XI,<br>3 422<br>D B<br>ound<br>and<br>a<br>S (St<br>tion<br>– Ir<br>of F<br>Ilti-7   | SCX<br>2, IEC<br>US.<br>ation<br>ncy 0<br>mart<br>Laye<br>nterfa<br>PC –<br>Faski | <b>12 ho</b><br>I and<br>C/ISA I<br><b>11 hc</b><br>field<br>Overvi<br>Distrib<br>r.<br><b>11 hc</b><br>cing F<br>PC b<br>ng - | urs<br>PXI:<br>Field<br>bus-<br>ew -<br>buted<br>puted<br>putes<br>PC to<br>passec<br>Task |

| Unit  | Contemporary Issues  | 2 hours                       |
|-------|--|-------------------------------|
| Wirel | ess CCTV - ZigBee based monitoring through internet  | •                             |
|       |  | I                             |
|       | Total Lecture hours  | 60 hours                      |
|       | t Book(s)  |                               |
| 1     | John Park, Steve Mackey and Edwin Wright, "Data Communic   | ations for                    |
|       | Instrumentation and Control", Elsevier, 2003.  |                               |
| 2     | Steve Mackay, Edwin Wright and Deon Reynders, "Practical Industrial data                         | networks:                     |
|       | Design, Installation and troubleshooting", Elsevier international projects ltd.,                 | 2004.                         |
| 3     | Krishna Kant, "Computer Based Industrial Control", Prentice Hall India Ltd.                      | , 2004.                       |
| I     |  |                               |
| Refe  | erence Books   |                               |
|       | Bouwens, A.J., "Digital instrumentation", McGraw Hill, Reprint 2007.                             |                               |
| 2     | S. Gupta and J.P Gupta, "PC Interfacing for Data Acquisition and Proce                           | ss Control", 2 <sup>n</sup>   |
|       | Edition 2002.  |                               |
| 3     | M.M.S., Anand, Electronic Instruments and Instrumentation Technology, Pre                        | ntice Hall,                   |
|       | 2004.  | (1                            |
|       | Doeblin, "Measurement and system, Application and Design", McGraw-                               | Hill, 5 <sup>th</sup> Edition |
|       | 2003.  |                               |
|       | John lenk, D., "Handbook of Microcomputer based Instrumentation and cont                         | rol", Prentice                |
|       | Hall, 1984.  |                               |
| -     |  |                               |
| Rela  | ted Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]   |                               |
| 1 2   | https://nptel.ac.in/courses/108/105/108105064/   |                               |
| 2 3   | https://nptel.ac.in/courses/108/105/108105153/<br>https://nptel.ac.in/courses/112/105/112105232/ |                               |
| 5     | nups.//nptci.ac.in/courses/112/105/112105252/  |                               |
| Com   | rse Designed By: Dr.S.Rathinavel   | //                            |
| 204   |  |                               |
|       |  |                               |

| Mappi | ng with | Program | mme Ou | itcom <mark>es</mark> | Coimbate | ore |     | G          | 1   |      |
|-------|---------|---------|--------|-----------------------|----------|-----|-----|------------|-----|------|
| COs   | PO1     | PO2     | PO3    | PO4                   | PO5      | PO6 | PO7 | <b>PO8</b> | PO9 | PO10 |
| CO1   | S       | S       | S 🖧    | S                     | M        | М   | S   | S          | S   | S    |
| CO2   | S       | S       | S      | S                     | JISON    | S   | S   | S          | S   | S    |

\*S-Strong; M-Medium; L-Low LATE TO ELEVIN

| Core/Flective/S   | <b>2EB</b>  | <b>ROBOTICS AND AUTOMATION</b>   |                                  | T       | P   | C   |
|---|---|--|----------------------------------|---------|---|---|
| COLC/Elective/S   | upportive   | Elective   | 4                                | 0       | 0   | 4   |
| Pre-requisite   | 1   | Basic mathematics, mechanical knowledge is Important   | Sylla<br>Versi                   |         | 2021  | -22   |
| Course Object   | tives:  |  |                                  | 1       |   |   |
| The main object   | ctives of thi   | s course are to:   |                                  |         |   |   |
| 1. Study th   | ne various j  | parts of robots and fields of robotics.  |                                  |         |   |   |
| 2. Study th   | ne various l  | kinematics and inverse kinematics of robots.   |                                  |         |   |   |
| 3. Study th   | ne Euler, La  | agrangian formulation and trajectory planning of   | Robot d                          | lynar   | nics.   |   |
| 4. Study th   | ne control c  | of robots for some specific applications.  |                                  |         |   |   |
| 5. educate  | on various  | path planning techniques and dynamics and con  | trol of n                        | nanip   | ulato   | rs  |
| Expected Cou  | rse Outcor  | nes:   |                                  |         |   |   |
|   |   | etion of the course, student will be able to:  |                                  |         |   |   |
|   |   | ution of robot technology and mathematically rep   | resent                           |         | K   | 2   |
| different   | types o <mark>f rol</mark>  | bot.   |                                  |         |   |   |
|   | **  | ase studies and design of robot machine interface  |                                  |         | K   | 3   |
| 3 Familia   | rize vari <mark>ous</mark>  | s control schemes of Robotics control  |                                  |         | K   | 2   |
| K1 - Rememb   | oer; <b>K2</b> - U  | nderstand; K3 - Apply; K4 - Analyze; K5 - Evalu  | ate; K                           | 6 - Cı  | eate  |   |
|   |   |  |                                  |         |   |   |
| Unit:1  |   | Basic Concepts   |                                  |         | 12 h  | ours  |
|   |   | Power Sources, Sensors and Actuators<br>d electric drives: Design and control issues – of  |                                  |         | n of 1  | <b>ours</b><br>HP o                               |
|   |   | variable speed arrangements – path determination   |                                  | a atil. |   | nes ir  |
|   | hine vision   | - ranging – laser – acoustic – magnetic, fiber opt   |                                  | actile  |   | nes ir  |
|   | ् थ्  |  |                                  | actile  |   | nes ir<br>ors.                                    |
| robotics – macl<br>Unit:3<br>Construction   | Mani<br>of manipula<br>anipulator o   | – ranging – laser – acoustic – magnetic, fiber opt   | ic and t                         | onic    | e sens<br>12 h<br>and   | nes ir<br>ors.<br><b>ours</b>                     |
| robotics – macl<br>Unit:3<br>Construction<br>pneumatic ma   | Mani<br>of manipula<br>anipulator o   | – ranging – laser – acoustic – magnetic, fiber opt<br>ipulators and Grippers Differential Motion<br>ators – manipulator dynamics and force control   | ic and t                         | onic    | e sens<br><b>12 h</b><br>and<br>s – de  | nes in<br>ors.<br>ours<br>esign                   |
| robotics – macl<br>Unit:3<br>Construction of<br>pneumatic ma<br>considerations<br>Unit:4<br>Linear and ang<br>arm singularity | Mani<br>of manipula<br>anipulator o<br>s.<br>ular velocit<br>r - Static an            | – ranging – laser – acoustic – magnetic, fiber opt<br>ipulators and Grippers Differential Motion<br>ators – manipulator dynamics and force control<br>control circuits – end effectors – U various type  | ic and t<br>– electr<br>s of gri | onic    | $\frac{12 \text{ h}}{2 \text{ h}}$ | nes ir<br>ors.<br>ours<br>esign<br>ours<br>st and |
| robotics – macl<br>Unit:3<br>Construction of<br>pneumatic ma<br>considerations<br>Unit:4<br>Linear and ang                    | Mani<br>of manipula<br>anipulator o<br>s.<br>ular velocit<br>- Static an<br>anguages. | – ranging – laser – acoustic – magnetic, fiber opt<br>ipulators and Grippers Differential Motion<br>ators – manipulator dynamics and force control<br>control circuits – end effectors – U various type<br>Kinematics and Path Planning<br>ties-Manipulator Jacobian-Prismatic and rotary jo | ic and t<br>– electr<br>s of gri | onic    | e sens<br>12 h<br>and<br>s – do<br>12 h<br>-Wri<br>lem –  | nes in<br>ors.<br>ours<br>esign<br>ours<br>st and |

|    | nit:6                        | Contemporary Issues  | 2 hours               |
|----|------------------------------|--|-----------------------|
| ap | plication of Robo            | tic Painting, application of part transfer and machine tend            | ding                  |
|    |                              |  |                       |
|    |                              | Total Lecture hours  | 60 hours              |
| Т  | ext Book(s)                  |  |                       |
| 1  | Mikell P. We                 | iss G.M., Nagel R.N., Odraj N.G., Industrial Rob                       | otics, McGraw-Hill    |
|    | Singapore, 201               | 5.   |                       |
| 2  | Saeed B Niku,                | Introduction to Robotics, Analysis, Systems, Applicat                  | ions Prentice Hall, 3 |
|    | edition 2104.                |  |                       |
|    |                              |  |                       |
| R  | eference Books               |  |                       |
| 1  | Deb.S.R., Robe               | otics technology an <mark>d flexible Auto</mark> mation, John Wiley, U | SA 1992.              |
| 2  | Asfahl C.R., R               | obots and manufacturing Automation, John Wiley, USA                    | 1992.                 |
| 3  | Klafter R.D., C              | Chim <mark>ielewsk</mark> i T.A., Negin M., Robotic Engineering – Ar   | integrated approach,  |
|    | Prentice Hall o              | f <mark>India, New De</mark> lhi, 1994.                                |                       |
| 4  | R.K.Mittal and l             | .J. <mark>Nagrath,</mark> Robotics and Control, Tata McGraw Hill, Ne   | w Delhi,4th Reprint,  |
|    | 2005                         |  |                       |
| 5  | JohnJ.Craig,Int              | roduction to Robotics Mechanics and Control, Third edit                | on, Pearson           |
|    | Education,2009.              |  |                       |
| 6  | Issac Asimo <mark>v I</mark> | Robot, Ballantine Books, New York, 1986.                               |                       |
|    |                              | S AND STRUCT   |                       |
| R  |                              | ntents [MOOC, SWAYAM, NPTEL, Websites etc.]                            |                       |
| 1  |                              | .in/courses/112/101/112101098/   |                       |
| 2  |                              | .in/courses/112/105/112105249/   |                       |
| 3  | https://nptel.ac             | .in/courses/112/101/112101099/   | 3                     |
|    | 8                            |  | 9                     |
| C  | ourse Designed B             | y: Dr.J.Vijayakumar  |                       |

| Марр | ing with | Progra | mme O | utcomes    | Coimbai | laire |            | Cer        |     |      |
|------|----------|--------|-------|------------|---------|-------|------------|------------|-----|------|
| COs  | PO1      | PO2    | PO3   | PO4        | PO5     | PO6   | <b>PO7</b> | <b>PO8</b> | PO9 | PO10 |
| CO1  | S        | М      | S     | 5 <b>S</b> | M       | M     | S          | М          | S   | S    |
| CO2  | S        | М      | М     | EDSICA     | M       | М     | S          | S          | S   | S    |
| CO3  | S        | М      | S     | S          | М       | S     | S          | S          | S   | S    |

| Course code   | 3EC   | ANALYTICAL INSTRUMENTATION   |   | T                 | Р  | <b>C</b>  |
|---|---|--|---|-------------------|--|---|
| Core/Elective/S   | upportive   | Elective   | 4   | 0                 | 0  | 4   |
| Pre-requisite   |   | Student should have the basic knowledge<br>on Instrumentation  | Sylla<br>Versi  |                   | 2021   | 1-22  |
| Course Object   | ives:   |  |   |                   |  |   |
| 1. Provide a the spectru  | various tec   | s course are to:<br>hniques and methods of analysis which occur in<br>nods of analysis of industrial gases.  | the van   | rious             | regio  | ns of   |
|   |   | t radio chemical methods of analysis   |   |                   |  |   |
|   |   | · · · ·  |   |                   |  |   |
| Expected Cou  |   |  |   |                   |  |   |
| On the succes   | sful comple   | etion of the co <mark>urse, student w</mark> ill be able to:   |   |                   |  |   |
| 1 To explor<br>application  |   | imentation techniques for the various industrial   |   |                   | K1   |   |
| 2 Able to u   | nderstand tl  | he applications of biomedical instruments  |   |                   | K3   |   |
| 3 Will be fa  | miliarized  | with functions and feature of the instruments  |   |                   | K2   |   |
| K1 - Rememb   | er; K2 - Ur   | nderstand; K3 - Apply; K4 - Analyze; K5 - Evalu  | iate; <b>K</b>  | 6 – C             | reate  |   |
|   |   |  |   |                   |  |   |
| Unit:1  |   | Colorimetry and Spectrophotometry  |   |                   | 12 h   | ours  |
| Single and d<br>Attenuated to   | ou <mark>ble bear</mark><br>tal <mark>reflectar</mark>  | alysis- Beer-Lambert law-colorimeters-UV-Vis<br>m Instruments-Sources and detectors-IR Spec<br>nce flame photometers- Atomic absorption spect<br>trophotometers-Flame emission photometers.  | trophot   | omet              | otom<br>ers-T  | eters-<br>ypes-   |
| Single and d<br>Attenuated to<br>and detectors-   | ou <mark>ble bear</mark><br>tal <mark>reflectar</mark>  | alysis- Beer-Lambert law-colorimeters-UV-Vis<br>m Instruments-Sources and detectors-IR Spec-<br>nce flame photometers- Atomic absorption spect<br>trophotometers-Flame emission photometers.   | trophot   | omet              | otom<br>ærs-T<br>ærs-so  | eters-<br>ypes-<br>ources   |
| Single and d<br>Attenuated to<br>and detectors-<br>Unit:2<br>Different tech   | ouble bean<br>tal reflectar<br>FTIR Spect   | alysis- Beer-Lambert law-colorimeters-UV-Vis<br>m Instruments-Sources and detectors-IR Spec<br>nce flame photometers- Atomic absorption spect  | trophot   | omet              | otom<br>ers-T<br>ers-so<br><b>10 h</b>   | eters-<br>ypes-<br>ources   |
| Single and d<br>Attenuated to<br>and detectors-<br>Unit:2<br>Different tech   | ouble bean<br>tal reflectar<br>FTIR Spect   | alysis- Beer-Lambert law-colorimeters-UV-ViS<br>m Instruments-Sources and detectors-IR Spec<br>nee flame photometers- Atomic absorption spect<br>trophotometers-Flame emission photometers.<br>Chromotography<br>as chromatography – Detectors - Liquid chromatography   | trophot   | omet              | otom<br>ers-T<br>ers-so<br><b>10 h</b>   | eters-<br>ypes-<br>ources   |
| Single and d<br>Attenuated to<br>and detectors-<br>Unit:2<br>Different tech<br>- High pressur<br>Unit:3   | ouble bean<br>tal reflectar<br>FTIR Spect<br>niques - Ga<br>e liquid chr<br>Industr   | alysis- Beer-Lambert law-colorimeters-UV-ViS<br>m Instruments-Sources and detectors-IR Spect<br>ince flame photometers- Atomic absorption spect<br>trophotometers-Flame emission photometers.<br>Chromotography<br>as chromatography – Detectors - Liquid chromato<br>romatographs - Applications.   | ographs   |                   | otom<br>ers-T<br>ers-so<br><b>10 h</b><br>oplica<br><b>12 h</b>                    | eters-<br>ypes-<br>urces<br>ours<br>tions   |
| Single and d<br>Attenuated to<br>and detectors-<br>Unit:2<br>Different tech<br>- High pressur<br>Unit:3<br>Types of gas<br>analyzers, an  | ouble bean<br>tal reflectar<br>FTIR Spect<br>niques - Ga<br>e liquid chr<br>Industr<br>Analyzers<br>alysis base   | alysis- Beer-Lambert law-colorimeters-UV-ViS<br>m Instruments-Sources and detectors-IR Spec<br>nee flame photometers- Atomic absorption spect<br>trophotometers-Flame emission photometers.<br>Chromotography<br>as chromatography – Detectors - Liquid chromato<br>romatographs - Applications.   | bgraphs<br>, therm<br>to car  | a – Aj            | otom<br>ers-T<br>ers-so<br><b>10 h</b><br>oplica<br><b>12 h</b><br>onduc<br>monduc | eters-<br>ypes-<br>urces<br>ours<br>tions<br>tivity<br>oxide,                             |
| Single and d<br>Attenuated to<br>and detectors-<br>Unit:2<br>Different tech<br>- High pressur<br>Unit:3<br>Types of gas<br>analyzers, an<br>hydrocarbons,<br>Unit:4   | ouble bean<br>tal reflectar<br>FTIR Spect<br>niques - Ga<br>e liquid chr<br>Industr<br>Analyzers<br>alysis base<br>nitrogen ou<br>pH M  | alysis- Beer-Lambert law-colorimeters-UV-ViS<br>m Instruments-Sources and detectors-IR Spect<br>ince flame photometers- Atomic absorption spect<br>trophotometers-Flame emission photometers.<br>Chromotography<br>as chromatography – Detectors - Liquid chromato<br>romatographs - Applications.<br>rial Gas Analyzers and Pollution Monitoring<br>Instruments<br>s-Oxygen, NO2 and H2S types, IR analyzers,<br>ed on ionization of gases. Air pollution due<br>xides, sulphur dioxide estimation-dust and smoke<br>Ieters And Dissolve Component Analyzers  | trophot<br>trophoto<br>ographs<br>, therm<br>to car<br>e measu                        | a – Aj            | 10 h<br>oplica<br>12 h<br>onduc<br>ents<br>12 l                                    | eters-<br>ypes-<br>urces<br>ours<br>tions<br>tivity<br>oxide,                             |
| Single and d<br>Attenuated to<br>and detectors-<br>Unit:2<br>Different tech<br>- High pressur<br>Unit:3<br>Types of gas<br>analyzers, an<br>hydrocarbons,<br>Unit:4<br>Principle of                                     | ouble bean<br>tal reflectar<br>FTIR Spect<br>niques - Ga<br>e liquid chr<br>Industr<br>Analyzers<br>alysis base<br>nitrogen o<br>pH M<br>pH measur<br>electrodes,                             | alysis- Beer-Lambert law-colorimeters-UV-ViS<br>m Instruments-Sources and detectors-IR Spec<br>ince flame photometers- Atomic absorption spect<br>trophotometers-Flame emission photometers.<br>Chromotography<br>as chromatography – Detectors - Liquid chromatographs - Applications.<br>Fial Gas Analyzers and Pollution Monitoring<br>Instruments<br>s-Oxygen, NO2 and H2S types, IR analyzers,<br>ed on ionization of gases. Air pollution due<br>xides, sulphur dioxide estimation-dust and smoke<br>Inters And Dissolve Component Analyzers<br>rement, glass electrodes, hydrogen electrodes,<br>ammonia electrodes, biosensors, dissolved ox | trophot<br>trophoto<br>ographs<br>, therm<br>to car<br>e measu<br>, refere            | al cobon<br>aremo | 10 h<br>pplica<br>12 h<br>onduc<br>mono<br>ents<br>12 l                            | eters-<br>ypes-<br>urces<br>ours<br>tions<br>tivity<br>oxide,<br>hours<br>codes,          |
| Single and d<br>Attenuated to<br>and detectors-<br>Unit:2<br>Different tech<br>- High pressur<br>Unit:3<br>Types of gas<br>analyzers, an<br>hydrocarbons,<br>Unit:4<br>Principle of<br>selective ion<br>analyzer-silico | ouble bean<br>tal reflectar<br>FTIR Spect<br>riques - Ga<br>e liquid chr<br>Industr<br>Analyzers<br>alysis base<br>nitrogen of<br>pH M<br>pH measur<br>electrodes,<br>on analyzer<br>Radio Cl | alysis- Beer-Lambert law-colorimeters-UV-ViS<br>m Instruments-Sources and detectors-IR Spec<br>ince flame photometers- Atomic absorption spect<br>trophotometers-Flame emission photometers.<br>Chromotography<br>as chromatography – Detectors - Liquid chromatographs - Applications.<br>Fial Gas Analyzers and Pollution Monitoring<br>Instruments<br>s-Oxygen, NO2 and H2S types, IR analyzers,<br>ed on ionization of gases. Air pollution due<br>xides, sulphur dioxide estimation-dust and smoke<br>Inters And Dissolve Component Analyzers<br>rement, glass electrodes, hydrogen electrodes,<br>ammonia electrodes, biosensors, dissolved ox | trophot<br>trophoto<br>ographs<br>, therm<br>to car<br>e measu<br>, refere<br>tygen a | a – Aj            | 10 h<br>oplica<br>12 h<br>onduc<br>ents<br>12 l<br>electri<br>zer-so               | eters-<br>ypes-<br>urces<br>ours<br>tions<br>tivity<br>oxide,<br>bours<br>rodes,<br>odium |

| U  | iit:6 Contemporary Issues  | 2 hours                   |
|----|--|---------------------------|
| Bl | ood Gas Analysers, Blood Cell Counters,  |                           |
|    |  |                           |
|    | Total Lecture how  | urs 60 hours              |
| Te | xt Book(s)   |                           |
| 1  | R.S. Khandpur, "Handbook of Analytical Instruments" Tata Mc G                          | raw Hill publishing       |
|    | Co.Ltd.2006.   |                           |
| 2  | H.H.Willard, L.L.Merrit, J.A.Dean, F.A.Settle, "Instrumental method                    | ods of analysis" CBS      |
|    | publishing & distribution, 1995.   |                           |
|    |  |                           |
| Re | ference Books  |                           |
| 1  | Robert D.Braun, "Introduction to Instrumental Analysis" Mc Graw H                      | Hill, Singapore, 1987.    |
| 2  | G.W. Ewing, "Instrumental Methods of Analysis" Mc Graw Hill 199                        | 92.                       |
| 3  | DA Skoog and D.M.West, "Principles of Instrumental Analysis" Ha                        | arper and Row publishers, |
|    | 1974.  |                           |
|    |  |                           |
| Re | elated Online Con <mark>tents [MO</mark> OC, SWAYAM, NPTEL, We <mark>bsi</mark> tes et | c.]                       |
| 1  | Academy-Online/pdf   |                           |
| 2  | lecturenotes.in/instrumentation.pdf  |                           |
| 3  | https://nptel.ac.in/courses/103/108/103108100/   |                           |
|    |  |                           |
| Co | ourse Designed By: Dr.K.G.Padmasine  |                           |

| Mappi | ng with | Progra | mme Ou | tcomes | 24  |     | 115 |     |     |      |
|-------|---------|--------|--------|--------|-----|-----|-----|-----|-----|------|
| COs   | PO1     | PO2    | PO3    | PO4    | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |
| CO1   | S 2     | М      | М      | S      | S   | M   | M   | S   | SS  | S    |
| CO2   | S       | М      | М      | S      | S   | S   | М   | M   | S   | S    |
| CO3   | S       | S      | М      | S      | S   | M   | S   | М   | S   | S    |



| Course  | 350  | DATA COMMUNICATION   | т                     | T              | D                                     | C                              |
|---|--|--|-----------------------|----------------|---------------------------------------|--------------------------------|
| code  | 3EC  | NETWORKS   | L                     | T              | P                                     | C                              |
| Core/Electiv  | e/Supportive   | Elective   | 4                     | 0              | 0                                     | 4                              |
| Pre-requis  |  | Basic knowledge of analog and digital electronics  | Sylla<br>Versi        |                | 2021-                                 | 22                             |
| Course Obj  |  |  |                       |                |                                       |                                |
|   | 5  | s course are to:   |                       |                |                                       |                                |
|   |  | ng of different communication buses.   | . 1.1                 |                |                                       |                                |
|   | liarize with diff  | ferent transmission protocols used and made to unders  | stand the             | conc           | ept of                                |                                |
|   | 1 0  | er different interfacing of instruments  |                       |                |                                       |                                |
| <b>·</b>  |  |  |                       |                |                                       |                                |
| Expected C  | ourse Outcor   | nes:   |                       |                |                                       |                                |
|   |  | etion of the course, student will be able to:  |                       |                |                                       |                                |
| -   |  | different transmission protocols and interface buses   |                       |                | K3                                    |                                |
| -   |  | e concept of multiplexing, TCP/IP standards and IEE  | EΕ                    |                | K5                                    |                                |
| K1 Pama   |  | nderstand; K3 - Apply; K4 - Analyze; K5 - Eval   | unto: K               | 6 01           | vanta                                 |                                |
| KI - Kenie  | 1110er, <b>Kz - </b> 01  | iderstand, KS - Appry, K4 - Anaryze, KS - Evan   | uale, <b>N</b>        | <b>0 -</b> CI  | Cale                                  |                                |
| Unit:1  |  | Introduction   |                       |                | 12 ho                                 | urs                            |
|   | trumentation a   | and Control Systems – Introduction to Network  | <mark>s –2</mark> 32- | overv          |                                       |                                |
|   |  | op & EIA converters GPIB, interface buses:USE  |                       |                |                                       |                                |
|   |  | ics for industrial automation instrumentation Bu   |                       |                |                                       |                                |
|   | VISA Field Bu  |  |                       |                | , , ,                                 | ,                              |
| <u></u> , <u></u>   |  |  | 1                     |                |                                       |                                |
| Unit:2  |  | Transmission   |                       |                | 12 ho                                 | ours                           |
| D/D conversi  | ion: Line codin  | g, A/D conversion, PCM, Delta modulation, Paralle  | el and so             | erial t        | ransmis                               | sion.                          |
| D/A conversi  | on: ASK, FS <mark>K,</mark>  | PSK, DPSK and QPSK. MODEM.   | 19                    |                |                                       |                                |
|   | 2  |  | S                     |                |                                       |                                |
| Unit:3  |  | Multiplexing   |                       | 1              | 12 ho                                 |                                |
|   | • B Y .  | Itiple accesses: CSMA/CD, Polling and token passing  | g. Chann              | elizat         | ion: FD                               | MA,                            |
| I DMA and C   | DMA. LAN, V  | VAN and MAN  | -                     |                |                                       |                                |
| Unit:4  |  | Internet and Wireless Data Network   |                       |                | 11 ho                                 | ours                           |
| TCP/IP stan<br>ZigBee and   |  | IPv6, Worldwide web. Wireless LAN, IEEE st   | andards               | s: 802         | 2.11a/b                               | /g/n,                          |
| unu   |  |  |                       |                |                                       |                                |
| Unit:5  |  | Devicenet  |                       |                |                                       |                                |
|   |  | Devicenet  |                       |                | 11 ho                                 | Juis                           |
| DEVICENE  |  |  |                       |                |                                       |                                |
| Overview -  | - layers. Pro  | fibus -overview-protocol stack. HART proto   |                       |                | view-la                               | yers.                          |
| Overview -<br>Foundation  | – layers. Pro<br>field bus- lay  | fibus -overview-protocol stack. HART proto<br>yers – Error Detection and Diagnostics. Local  | interco               | onnec          | view-la<br>t netw                     | yers.<br>orks,                 |
| Overview -<br>Foundation<br>Redundancy  | – layers. Pro<br>field bus- lay<br>Overview –  | fibus -overview-protocol stack. HART proto<br>yers – Error Detection and Diagnostics. Local<br>Actuator- sensor Interface- CAN bus – overview  | interco<br>v-layers   | onnec<br>. Dev | view-la<br>t netw<br>ice Ne           | yers.<br>orks,<br>t and        |
| Overview -<br>Foundation<br>Redundancy<br>SDS (Smart                          | – layers. Pro<br>field bus- lay<br>Overview –<br>t Distributed   | fibus -overview-protocol stack. HART proto<br>yers – Error Detection and Diagnostics. Local  | interco<br>v-layers   | onnec<br>. Dev | view-la<br>t netw<br>ice Ne           | yers.<br>orks,<br>t and        |
| Overview -<br>Foundation<br>Redundancy  | – layers. Pro<br>field bus- lay<br>Overview –<br>t Distributed   | fibus -overview-protocol stack. HART proto<br>yers – Error Detection and Diagnostics. Local<br>Actuator- sensor Interface- CAN bus – overview  | interco<br>v-layers   | onnec<br>. Dev | view-la<br>t netw<br>ice Ne           | yers.<br>orks,<br>t and        |
| Overview -<br>Foundation<br>Redundancy<br>SDS (Smart<br>Application           | – layers. Pro<br>field bus- lay<br>Overview –<br>t Distributed   | fibus -overview-protocol stack. HART proto<br>yers – Error Detection and Diagnostics. Local<br>Actuator- sensor Interface- CAN bus – overview<br>Systems)-Physical Layer and Wiring Rules- Th                        | interco<br>v-layers   | onnec<br>. Dev | view-la<br>t netw<br>ice Ne<br>Layer- | yers.<br>orks,<br>t and<br>The |
| Overview -<br>Foundation<br>Redundancy<br>SDS (Smart<br>Application<br>Unit:6 | <ul> <li>layers. Pro<br/>field bus- lay</li> <li>Overview –</li> <li>t Distributed base</li> <li>Layer.</li> </ul> | fibus -overview-protocol stack. HART proto<br>yers – Error Detection and Diagnostics. Local<br>Actuator- sensor Interface- CAN bus – overview<br>Systems)-Physical Layer and Wiring Rules- Th<br>Contemporary Issues | interco<br>v-layers   | onnec<br>. Dev | view-la<br>t netw<br>ice Ne           | yers.<br>orks,<br>t and<br>The |
| Overview -<br>Foundation<br>Redundancy<br>SDS (Smart<br>Application<br>Unit:6 | – layers. Pro<br>field bus- lay<br>Overview –<br>t Distributed   | fibus -overview-protocol stack. HART proto<br>yers – Error Detection and Diagnostics. Local<br>Actuator- sensor Interface- CAN bus – overview<br>Systems)-Physical Layer and Wiring Rules- Th<br>Contemporary Issues | interco<br>v-layers   | onnec<br>. Dev | view-la<br>t netw<br>ice Ne<br>Layer- | yers.<br>orks,<br>t and<br>The |

| Te | xt Book(s)  |
|----|---|
| 1  | John Park, Steve Mackey and Edwin Wright, "Data Communications for  |
|    | Instrumentation and Control", Elsevier, 2003.   |
| 2  | Steve Mackay, Edwin Wright and Deon Reynders, "Practical Industrial data networks: Design,  |
|    | Installation and troubleshooting", Elsevier international projects ltd., 2004.  |
| 3  | Behrouz A. Forouzan, "Data Communications and Networking", 4 <sup>th</sup> Edition, Tata McGraw-Hill,   |
|    | Delhi, 2006.  |
|    |   |
| Re | ference Books   |
| 1  | William Buchanan, "Computer Buses-Design and Application", CRC Press, 2000  |
| 2  | Theodore S Rappaport, "Wireless Communications: Prentice and Practice", Prentice Hall PTR,  |
|    | second edition, 2002.   |
| 3  | Perry Marshall and John Rinaldi, "Industrial Ethernet", The Instrumentation, Systems and  |
|    | Automation Society, 2005  |
| 4  | Richard Zurawski ,"Industrial Communications Technology Handbook", CRC Press, 2005  |
|    |   |
| Re | lated Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]  |
| 1  | https://nptel.ac.in/courses/106/105/106105082/  |
| 2  | https://nptel.ac.in/courses/117/105/117105076/  |
| 3  | https://swayam.gov.in/nd1_noc20_cs23/preview  |
|    |   |
| Co | urse Designed By: Dr.S.Rathinavel   |
|    | Tour and and a set of the set of |
|    |   |

| COs          | PO1 | PO2     | PO3   | PO4 | PO5 | PO6 | PO7  | PO8 | PO9 | <b>PO10</b> |
|--------------|-----|---------|-------|-----|-----|-----|------|-----|-----|-------------|
| C <b>O</b> 1 | S 🖁 | S       | S     | S   | M   | М   | S    | S   | SS  | S           |
| C <b>O2</b>  | S   | S       | S     | S   | М   | S   | S    | S   | S   | S           |
|              | -   | ;; M-Me | 515   |     |     |     | - 91 |     |     |             |
|              |     |         | 291 6 |     |     |     |      |     |     |             |

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| Course code                    | 3EC                         | MICROWAVE THEORY AND<br>TECHNIQUES   | L              | Т      | P      | С    |
|--------------------------------|-----------------------------|--|----------------|--------|--------|------|
| Core/Elective/S                | upportive                   | Elective   | 4              | 0      | 0      | 4    |
| Pre-requisite                  |                             | Basic mathematics  | Sylla<br>Versi |        | 2021   | -22  |
| <b>Course Object</b>           | tives:                      |  | •              |        |        |      |
| The main object                | ctives of thi               | s course are to:   |                |        |        |      |
| 1. Understan                   | d the conce                 | pt of wave propagation especially in the microway  | e freq         | uenc   | y rang | e.   |
| 2. Understan                   | d the conce                 | pt of transmission lines and various analysis techn  | ique           |        |        |      |
| 3. Introduce                   | various mic                 | crowave components, devices and oscillators used   | in the         | field  | of     |      |
| microwav                       | e electronic                | S.   |                |        |        |      |
|                                | 0. /                        | as the second  |                |        |        |      |
| Expected Cour                  |                             |  |                |        |        |      |
|                                |                             | t <mark>ion of the course, student will be able to:</mark><br>about EM field propagation in free space and guid  | led            |        | K2     | )    |
| media                          | kilowiedge                  | about EN new propagation in nee space and gat  | icu            |        |        | •    |
| 2 Understa<br>signals          | ands the ge                 | neration, transmission and modification of microw  | ave            |        | K5     | ;    |
|                                | ne various c<br>ave generat | omponents and devices used for microwave researtion.   | ch and         | 1      | K3     | ,    |
| 4 Analyze                      | an <mark>d ev</mark> alua   | te various transmission lines parameters   |                | k      | K5     | ;    |
| K1 - Rememb                    | er; <mark>K2</mark> - U1    | nderstand; <mark>K3 - A</mark> pply; K4 - Analyze <mark>; K5</mark> - Evalua   | te; Ko         | 5 - C1 | eate   |      |
|                                | 1 3                         |  |                |        | 0.1    |      |
| Unit:1                         |                             | Introduction To Microwaves   |                |        |        | ours |
| microwaves in                  | n different                 | Frequency spectrum, Microwave frequency band<br>fields, Plane waves and free space propagation,<br>magnetic) waves, group and phase velocities                               |                |        |        |      |
| 12111 (11000)                  | 2                           |  | Ś              |        | /      |      |
| Unit:2                         | S M                         | i <mark>crowave Transmission Lines And Analy</mark> sis 🥢  | 5              | /      | 12 ho  | ours |
| wavelength a                   | nd half wa                  | lines, characteristic impedance-open circuit, clo<br>velength lines, Standing wave ratio, VSWR, R<br>axial, strip and microstrip transmission lines (intro-                  | eflecti        | on c   |        |      |
| Unit:3                         |                             | Waveguides And Devices   |                |        | 13 ho  | ours |
| fast waves, re                 | ctangular a                 | les, Propagation through wave guides, Guided wand circular wave guides, cut off frequency, group Race, Directional couplers, Isolators, attenuators,                         | veloc          | ity, V | Naveg  |      |
|                                |                             |  |                |        |        |      |
| Unit:4                         | Micro                       | owave Linear Beam Tubes And Cross Field<br>Devices   |                |        | 13 ho  | ours |
| cavity Klystr<br>diagrams, ref | on, re-enti<br>lex klystror | e tubes, limitations of conventional tubes, Transform<br>rant cavities, Velocity modulation and beam<br>n, magnetron, working of magnetron, travelling v<br>ation mechanism. | buncl          | ning,  | bunc   |      |

| Uni  | it:5         | Transferred Electron Devices And Transit Time                              | 12 hours            |
|------|--------------|--|---------------------|
| -    |              | Devices  |                     |
| Gur  | nn Effect a  | and Gunn diode-modes of operation, Microwave Semiconduc                    | tor devices, Tunnel |
|      |              | ive resistance-band theory for forward and reverse biasing, Sch            |                     |
| con  | tact diode   | s, Varactor diodes, IMPATTT diode-structure-negative resistan              | ce-efficiency and   |
| outp | put power,   | TRAPATT diode-principle of operation and performance.                      |                     |
|      |              |  |                     |
| Uni  |              | Contemporary Issues  | 2 hours             |
| Sm   | ith chart, I | mpedance matching  |                     |
|      |              | Total Lecture hours  | 60 hours            |
|      |              |  | ov nours            |
|      | t Book(s)    |  |                     |
| 1 .  | Microwav     | e Engineering, D. M. Pozar, John Wiley & Sons Inc, 2013.                   |                     |
| 2    | Foundatio    | ns for Microwave Engineering-2 <sup>nd</sup> Edition, R. E. Collin, Wiley- | IEEE Press, 2007.   |
| 3    | Microwav     | e Engineering, A. Das and S. K. Das, Tata McGraw-Hill, 2007                |                     |
| D (  | • D          |  |                     |
| Ref  | ference Bo   |  |                     |
| 1    |              | ve devices and circuits, Samuel Y. Lio, (Prentice Hall)-2003               |                     |
| 2    |              | c comm <mark>unicati</mark> on systems, Kennedy and Davis, – (Tata Mc G    | aw Hill) - 2011     |
| 3    | Microwa      | ve Engineering Passive Circuits, P. A. Rizzi, Pearson, 1998.               |                     |
|      |              |  |                     |
| Rel  |              | ne Contents [MOOC, SWAYAM, NPTEL, Websites etc.]                           |                     |
| 1    |              | otel.ac.in/courses/108/103/108103141/                                      |                     |
| 2    |              | otel.ac.in/courses/117/105/117105122/                                      |                     |
| 3    | https://np   | otel.ac.in/courses/108/101/108101112/                                      |                     |
| ~    |              |  |                     |
| Cot  | arse Desig   | ned By: Dr.Sujith Raman  |                     |
|      |              | 3 24 48  | 3                   |

| Mappin | ng with P | rogram | me Outo | omes   | R I     | NUV   |     | J.S |     |      |
|--------|-----------|--------|---------|--------|---------|-------|-----|-----|-----|------|
| COs    | PO1       | PO2    | PO3     | PO4    | PO5     | PO6   | PO7 | PO8 | PO9 | PO10 |
| CO1    | S         | S S    | S       | L      | L       | L     | М   | М   | S   | М    |
| CO2    | S         | S      | S/ C    | L      | S       | M     | 5 D | М   | S   | М    |
| CO3    | S         | S      | S       | ารถา   | JISTON  | 2L.   | S   | S   | S   | М    |
| CO4    | S         | S      | S       | EDSICA | TE LO E | EVSTE | L   | М   | S   | М    |
|        |           |        |         |        | 2002    |       |     |     |     |      |



| <ul> <li>2. Develop skill</li> <li>Expected Course</li> <li>On the successfu</li> <li>1 Understand</li> <li>2 Apply con<br/>application</li> <li>K1 - Remember;</li> <li>Unit:1</li> <li>Different Logic s</li> </ul>   | Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades<br>Grades | andamentals of Digital Electronics.<br>ications development with microprocessors<br>f the course, student will be able to:<br>ne concept of linear and digital electronic cin<br>n and software to create specific micropro-<br>nd; K3 - Apply; K4 - Analyze; K5 - Evalua<br>Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn              | rcuits.<br>ocesso<br>nte; <b>K(</b><br>nbol ar | or             | 0<br>2021<br>K2<br>K6 | 2        |
|---|--|--|--|----------------|-----------------------|----------|
| Course Objective         The main objective         The main objective         1. Expose the st         2. Develop skill         Expected Course         On the successfu         1       Understand         2       Apply con         application         K1 - Remember;         Unit:1         Different Logic §         De Morgan"s Th | s:<br>es of this cours<br>udents to the fu<br>in simple appl<br>Outcomes:<br>completion of<br>and analyze th<br>puting platform<br>s.<br>K2 - Understa<br>gates such as A<br>eorems: Stater  | ee are to:<br>indamentals of Digital Electronics.<br>ications development with microprocessors<br>f the course, student will be able to:<br>ie concept of linear and digital electronic cin<br>m and software to create specific micropro<br>nd; K3 - Apply; K4 - Analyze; K5 - Evalua<br>Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn | versi  | or             | K2                    | 2        |
| The main objectiv1. Expose the st2. Develop skillExpected CourseOn the successfu1Understand2Apply con<br>applicationK1 - Remember;Unit:1Different Logic g<br>De Morgan"s Th   | es of this cours<br>udents to the fu<br>in simple appl<br><b>Outcomes:</b><br>completion of<br>and analyze th<br>puting platform<br>s.<br><b>K2</b> - Understa<br>gates such as A<br>eorems: Stater  | andamentals of Digital Electronics.<br>ications development with microprocessors<br>f the course, student will be able to:<br>ne concept of linear and digital electronic cin<br>n and software to create specific micropro-<br>nd; K3 - Apply; K4 - Analyze; K5 - Evalua<br>Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn              | rcuits.<br>ocesso<br>nte; <b>K(</b><br>nbol ar |                | Ke                    |          |
| <ol> <li>Expose the st</li> <li>Develop skill</li> <li>Expected Course</li> <li>On the successfu</li> <li>Understand</li> <li>Apply con<br/>application</li> <li>K1 - Remember;</li> <li>Unit:1</li> <li>Different Logic g</li> <li>De Morgan"s Th</li> </ol>   | udents to the fu<br>in simple appl<br>Outcomes:<br>completion of<br>and analyze th<br>puting platform<br>s.<br>K2 - Understa<br>sates such as A<br>eorems: Stater  | andamentals of Digital Electronics.<br>ications development with microprocessors<br>f the course, student will be able to:<br>ne concept of linear and digital electronic cin<br>n and software to create specific micropro-<br>nd; K3 - Apply; K4 - Analyze; K5 - Evalua<br>Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn              | rcuits.<br>ocesso<br>nte; <b>K(</b><br>nbol ar |                | Ke                    |          |
| <ul> <li>2. Develop skill</li> <li>Expected Course</li> <li>On the successfu</li> <li>1 Understand</li> <li>2 Apply con<br/>application</li> <li>K1 - Remember;</li> <li>Unit:1</li> <li>Different Logic g</li> <li>De Morgan"s The</li> </ul>  | in simple appl<br>Outcomes:<br>completion of<br>and analyze th<br>puting platform<br>s.<br>K2 - Understa<br>gates such as A<br>eorems: Stater  | ications development with microprocessors<br>f the course, student will be able to:<br>ne concept of linear and digital electronic cin<br>m and software to create specific micropro-<br>nd; K3 - Apply; K4 - Analyze; K5 - Evalua<br>Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn   | rcuits.<br>ocesso<br>nte; <b>K(</b><br>nbol ar |                | Ke                    |          |
| <ul> <li>2. Develop skill</li> <li>Expected Course</li> <li>On the successfu</li> <li>1 Understand</li> <li>2 Apply con<br/>application</li> <li>K1 - Remember;</li> <li>Unit:1</li> <li>Different Logic g</li> <li>De Morgan"s The</li> </ul>  | in simple appl<br>Outcomes:<br>completion of<br>and analyze th<br>puting platform<br>s.<br>K2 - Understa<br>gates such as A<br>eorems: Stater  | ications development with microprocessors<br>f the course, student will be able to:<br>ne concept of linear and digital electronic cin<br>m and software to create specific micropro-<br>nd; K3 - Apply; K4 - Analyze; K5 - Evalua<br>Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn   | rcuits.<br>ocesso<br>nte; <b>K(</b><br>nbol ar |                | Ke                    |          |
| Expected Course<br>On the successfu<br>1 Understand<br>2 Apply con<br>application<br>K1 - Remember;<br>Unit:1 Different Logic §<br>De Morgan"s Th   | Outcomes:<br>completion of<br>and analyze th<br>puting platform<br>s.<br>K2 - Understa<br>ates such as A<br>eorems: Stater   | f the course, student will be able to:<br>ne concept of linear and digital electronic cin<br>n and software to create specific micropro<br>nd; <b>K3 -</b> Apply; <b>K4 -</b> Analyze; <b>K5 -</b> Evalua<br>Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn  | rcuits.<br>ocesso<br>nte; <b>K(</b><br>nbol ar |                | Ke                    |          |
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| 2Apply con<br>applicationK1 - Remember;Unit:1Different Logic g<br>De Morgan"s Th  | puting platform<br>s.<br><b>K2</b> - Understa<br>sates such as A<br>eorems: Stater   | n and software to create specific micropro<br>nd; K3 - Apply; K4 - Analyze; K5 - Evalua<br>Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn  | ocesso<br>nte; <b>K(</b><br>nbol an            |                | Ke                    |          |
| applicationK1 - Remember;Unit:1Different Logic gDe Morgan"s Th  | <b>K2</b> - Understa<br>ates such as A<br>eorems: Stater   | nd; <b>K3 - Apply; K4 - Analyze; K5 -</b> Evalua<br>Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn   | nte; <b>K</b> (                                |                |                       |          |
| K1 - Remember;<br>Unit:1<br>Different Logic g<br>De Morgan"s Th   | <b>K2</b> - Understa<br>ates such as A<br>eorems: Stater   | Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn   | nbol aı  | <u>6 - C</u> 1 |                       |          |
| Unit:1<br>Different Logic g<br>De Morgan"s Th   | ate <mark>s such as A</mark><br>eorem <mark>s: Stat</mark> er  | Logic Gates<br>ND, OR, NOT, NAND, NOR, EXOR, Syn   | nbol aı  | <u>- C</u>     | reate                 |          |
| Different Logic g<br>De Morgan"s Th   | eorems: Stater   | ND, OR, NOT, NAND, NO <mark>R, EXOR,</mark> Syn  |  |                |                       | ours     |
| De Morgan"s Th  | eorems: Stater   |  |  | nd T           |                       |          |
|   |  |  | idon L   |                |                       |          |
| Subtractor and It   | Il cuptro ator   | nent, verification and applications, Half-ad   | uer. r   | un a           | uuer,                 | пап      |
|   | Il subliación, S   |  |  |                |                       |          |
| Unit:2  |  | Number Systems   |  |                | 6 h                   | our      |
|   | · 1 D'   | Number Systems   |  | × 1            | -                     |          |
|   |  | y, Octal, Hexadecimal Number Systems, B  | CD C   | odes           | , Inter               | 1        |
| conversions of D  | ecimal, Binary   | , and BCD Numbers, Parity, Excess-3.   |  | _              |                       | <u> </u> |
| TING  | 5  |  | _  | _              |                       | <u>.</u> |
| Unit:3  |  | Microprocessor   |  | -              |                       | ours     |
|   |  | of 8085 - functional Block diagrams, bus sy  |  |                |                       |          |
|   | nodes- timing  | diagram and assembly level programme- I  | nterfa   | cing           | RAM                   | and      |
| ROM sections.   |  |  | 19   |                |                       |          |
|   | 2  |  | (9   | 1              |                       |          |
| Unit:4  | CA .   | Contemporary Issues  | 5  | 6              | 2 h                   | ours     |
| Introduction to A   | RM, Introduct  |  |  |                |                       |          |
|   | All Comments   | <b>Company Total Lecture hours</b>   |  |                | 20 ho                 | ours     |
| Text Book(s)  | 1500   | .91  |  |                |                       |          |
| 1 Microproces   | or Architectur   | e Programming and applications with 8085   | , Ram  | nesh           | Gaonk                 | ar,      |
|   |  | ning house,-2013   |  |                |                       |          |
| 2 Digital Princi  | oles and Applic  | cations, Donald P. Leach, Albert Paul Malvi  | ino, Ta  | ataM           | cGraw                 | v Hi     |
| Company – 2   | 010  |  |  |                |                       |          |
| <b>Reference Book</b>   |  |  |  |                |                       |          |
| 1 Electronic De   | vices and Circi  | uits, Salivahanan , Tata-McGraw Hill Comp  | any-20   | 011            |                       |          |
|   |  | OC, SWAYAM, NPTEL, Websites etc.]  |  |                |                       |          |
|   |  | 108/105/108105102/   |  |                |                       |          |
|   |  | 06/108/106108100/  |  |                |                       |          |
|   |  | 08/103/108103157/  |  |                |                       |          |
| Course Designed   |  |  |  |                |                       |          |
| <u> </u>  |  |  |  |                |                       |          |

| Mappin | Mapping with Programme Outcomes |     |     |     |     |     |     |     |     |      |  |  |  |
|--------|---------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|------|--|--|--|
| COs    | PO1                             | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |  |  |  |
| CO1    | M                               | M   | M   | М   | S   | S   | M   | M   | М   | М    |  |  |  |
| CO2    | М                               | S   | S   | М   | S   | S   | М   | М   | М   | М    |  |  |  |

| Course code  | GS   | MEDICAL ELECTRONICS AND<br>INSTRUMENTATION  | L  | Т               | Р  | С                          |
|--|--|---|--|-----------------|--|----------------------------|
| Core/Elective/S  | upportive  | Supportive  | 2  | 0               | 0  | 2                          |
| Pre-requisite  |  | Awareness study of the instruments<br>related with the medical field to the other<br>department students  | Syllabus<br>Version  |                 | 2021-22  |                            |
| <b>Course Object</b>   | tives:   |   |  |                 |  |                            |
| The main object  |  |   |  |                 |  |                            |
|  | •  | ut the various physiological parameters both electr   |  |                 |  | rical                      |
| and the  | methods of re  | ecording and also the method of transmitting these  | paran  | neters          | •  |                            |
| 2. Study a   | bout the vario   | ous assist devices used in the hospitals.   |  |                 |  |                            |
| 3. Gain kr   | nowledge abo   | ut equipment used for physical medicine and the v   | variou   | s rece          | ently  |                            |
| develop  | ed diagnostic  | and therapeutic techniques.   |  |                 |  |                            |
|  |  | an and an and a second  |  |                 |  |                            |
| Expected Cou   |  |   |  |                 |  |                            |
|  |  | on of the course, student will be able to:  |  |                 |  |                            |
|  |  | of medical instruments and its applications   |  |                 | K2   |                            |
|  |  | and various physiological information.  |  |                 | <u>K3</u><br>K4  |                            |
|  |  | the patient monitoring devices  |  |                 | <u>K4</u><br>K1K   | $\overline{\mathbf{r}}$    |
|  |  | erstand; K3 - Apply; K4 - Analyze; K5 - Evaluate;   | V  |                 |  | Z                          |
|  |  |   | • К А  | Creat           |  |                            |
|  | oci, <b>R2</b> - Olid  | erstand, KS - Appry, K4 - Anaryze, KS - Evaluate,   | ; K0 -   | Creat           | te   |                            |
| Unit:1   | , <b>K2</b> - Ond  | Medical Instrumentation Basics  | ; K0 -   | Creat           | 6 ho   | urs                        |
| Unit:1   | n U g  | Medical Instrumentation Basics  |  |                 | 6 ho   |                            |
| Unit:1<br>Cells and their  | · structure –  | Medical Instrumentation Basics<br>Transport of ions through the cell membrane -   | – Res  | ting a          | 6 hou<br>and ac  |                            |
| Unit:1<br>Cells and their<br>potentials Cha  | • structure –<br>racteristics of   | Medical Instrumentation Basics<br>Transport of ions through the cell membrane -<br>Resting potential - Bio-electric potentials – Des  | – Res  | ting a          | 6 hou<br>and ac  |                            |
| Unit:1<br>Cells and their<br>potentials Cha  | • structure –<br>racteristics of   | Medical Instrumentation Basics<br>Transport of ions through the cell membrane -   | – Res  | ting a          | 6 hou<br>and ac  |                            |
| Unit:1<br>Cells and their<br>potentials Char<br>Instruments – C  | • structure –<br>racteristics of   | Medical Instrumentation Basics<br>Transport of ions through the cell membrane -<br>Resting potential - Bio-electric potentials – Des<br>of the Bio-Medical Instrument System.   | – Res  | ting a          | 6 hou<br>and ac<br>lical   | tion                       |
| Unit:1<br>Cells and their<br>potentials Chai<br>Instruments – C<br>Unit:2  | • structure –<br>racteristics of<br>Components c   | Medical Instrumentation Basics<br>Transport of ions through the cell membrane -<br>Resting potential - Bio-electric potentials – Des<br>of the Bio-Medical Instrument System.<br>Biopotential Recorders   | - Res  | ting a<br>f Mec | 6 hou<br>and ac<br>lical<br>6 ho   | tion                       |
| Unit:1<br>Cells and their<br>potentials Char<br>Instruments – C<br>Unit:2<br>Electrocardiogra  | • structure –<br>racteristics of<br>Components c<br>aphy (ECG)   | Medical Instrumentation Basics         Transport of ions through the cell membrane -         Resting potential - Bio-electric potentials – Des         of the Bio-Medical Instrument System.         Biopotential Recorders         - Electroencephalography (EEG)–Electromy  | - Res  | ting a<br>f Mec | 6 hou<br>and ac<br>lical   | tion                       |
| Unit:1<br>Cells and their<br>potentials Char<br>Instruments – C<br>Unit:2<br>Electrocardiogra  | • structure –<br>racteristics of<br>Components c<br>aphy (ECG)   | Medical Instrumentation Basics<br>Transport of ions through the cell membrane -<br>Resting potential - Bio-electric potentials – Des<br>of the Bio-Medical Instrument System.<br>Biopotential Recorders   | - Res  | ting a<br>f Mec | 6 hou<br>and ac<br>lical<br>6 ho   | tion                       |
| Unit:1<br>Cells and their<br>potentials Char<br>Instruments – C<br>Unit:2<br>Electrocardiogra  | • structure –<br>racteristics of<br>Components c<br>aphy (ECG)   | Medical Instrumentation Basics         Transport of ions through the cell membrane -         Resting potential - Bio-electric potentials – Des         of the Bio-Medical Instrument System.         Biopotential Recorders         - Electroencephalography (EEG)–Electromy  | - Res  | ting a<br>f Mec | 6 hou<br>and ac<br>lical<br>6 ho   | urs                        |
| Unit:1<br>Cells and their<br>potentials Char<br>Instruments – C<br>Unit:2<br>Electrocardiogra<br>Electroretinogra<br>Unit:3  | • structure –<br>racteristics of<br>Components of<br>aphy (ECG)<br>phy (ERG) – E   | Medical Instrumentation Basics         Transport of ions through the cell membrane -         Resting potential - Bio-electric potentials – Des         of the Bio-Medical Instrument System.         Biopotential Recorders         - Electroencephalography (EEG)–Electromy         lectrooculography (EOG)  | - Res<br>sign of   | ting a f Mec    | 6 hou<br>and ac<br>dical<br>6 ho<br>(EMG)<br>6 ho                              | urs<br>urs                 |
| Unit:1<br>Cells and their<br>potentials Chai<br>Instruments – C<br>Unit:2<br>Electrocardiogra<br>Electroretinogra<br>Unit:3<br>Angiography –   | • structure –<br>racteristics of<br>Components of<br>phy (ECG)<br>phy (ERG) – E<br>Endoscopes -  | Medical Instrumentation Basics         Transport of ions through the cell membrane -         Resting potential - Bio-electric potentials – Des         of the Bio-Medical Instrument System.         Biopotential Recorders         - Electroencephalography (EEG)–Electromy         lectrooculography (EOG)         Specialized Medical Equipment  | - Res<br>sign of   | ting a f Mec    | 6 hou<br>and ac<br>dical<br>6 ho<br>(EMG)<br>6 ho                              | urs<br>urs                 |
| Unit:1<br>Cells and their<br>potentials Chai<br>Instruments – C<br>Unit:2<br>Electrocardiogra<br>Electroretinogra<br>Unit:3<br>Angiography –   | • structure –<br>racteristics of<br>Components of<br>phy (ECG)<br>phy (ERG) – E<br>Endoscopes -  | Medical Instrumentation Basics         Transport of ions through the cell membrane -         Resting potential - Bio-electric potentials – Des         of the Bio-Medical Instrument System.         Biopotential Recorders         - Electroencephalography (EEG)–Electromy         lectrooculography (EOG)         Specialized Medical Equipment         - Different types of endoscopes -Computer tomography   | - Res<br>sign of   | ting a f Mec    | 6 hou<br>and ac<br>dical<br>6 ho<br>(EMG)<br>6 ho                              | urs<br>urs                 |
| Unit:1<br>Cells and their<br>potentials Char<br>Instruments – G<br>Unit:2<br>Electrocardiogra<br>Electroretinogra<br>Unit:3<br>Angiography –<br>Computer tomo  | • structure –<br>racteristics of<br>Components of<br>phy (ECG)<br>phy (ERG) – E<br>Endoscopes -<br>ography - Ultr  | Medical Instrumentation Basics         Transport of ions through the cell membrane -         Resting potential - Bio-electric potentials – Des         of the Bio-Medical Instrument System.         Biopotential Recorders         - Electroencephalography (EEG)–Electromy         lectrooculography (EOG)         Specialized Medical Equipment         - Different types of endoscopes -Computer tomograsonic imaging systems.         Contemporary Issues  | - Res<br>sign of   | ting a f Mec    | 6 hou<br>and ac<br>dical<br>6 ho<br>(EMG)<br>6 ho                              | urs<br>urs<br>on of        |
| Unit:1<br>Cells and their<br>potentials Char<br>Instruments – G<br>Unit:2<br>Electrocardiogra<br>Electroretinogra<br>Unit:3<br>Angiography –<br>Computer tomo  | • structure –<br>racteristics of<br>Components of<br>phy (ECG)<br>phy (ERG) – E<br>Endoscopes -<br>ography - Ultr  | Medical Instrumentation Basics         Transport of ions through the cell membrane -         Resting potential - Bio-electric potentials – Des         of the Bio-Medical Instrument System.         Biopotential Recorders         - Electroencephalography (EEG)–Electromy         lectrooculography (EOG)         Specialized Medical Equipment         - Different types of endoscopes -Computer tomograsonic imaging systems.         Contemporary Issues         sonance imaging  | - Res<br>sign or<br>vograpl  | ting a f Mec    | 6 hor<br>and ac<br>lical<br>6 ho<br>(EMG)<br>6 ho<br>plicatio                  | urs<br>urs<br>on of<br>urs |
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| Unit:1<br>Cells and their<br>potentials Char<br>Instruments – G<br>Unit:2<br>Electrocardiogra<br>Electroretinogra<br>Unit:3<br>Angiography –<br>Computer tomo<br>Unit:4<br>X-ray machine<br>Text Book(s)<br>1 M.Aru<br>2 R.Ana<br>Reference Bo   | <ul> <li>structure –</li> <li>racteristics of Components of Comp</li></ul> | Medical Instrumentation Basics Transport of ions through the cell membrane - Resting potential - Bio-electric potentials – Des of the Bio-Medical Instrument System. Biopotential Recorders - Electroencephalography (EEG)–Electromy lectrooculography (EOG) Specialized Medical Equipment - Different types of endoscopes -Computer tomograsonic imaging systems. Contemporary Issues sonance imaging Total Lecture ho medical Instrumentation" Anuradha Publications, "Biomedical Instrumentation" PHI learning, 2009   | - Resign of a sign of a si | ting a f Mec    | 6 hou<br>and ac<br>dical<br>6 ho<br>(EMG)<br>6 ho<br>plicatio<br>2 ho<br>20 ho | urs<br>on of<br>urs        |
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| Unit:1<br>Cells and their<br>potentials Char<br>Instruments – O<br>Unit:2<br>Electrocardiogra<br>Electroretinogra<br>Unit:3<br>Angiography –<br>Computer tomo<br>Unit:4<br>X-ray machine<br>Text Book(s)<br>1 M.Aru<br>2 R.Ana<br>Reference Bo<br>1 R.S.Kl<br>2 <sup>nd</sup> Edi            | <ul> <li>structure –<br/>racteristics of<br/>Components of<br/>Components of<br/>Paphy (ECG)</li> <li>phy (ERG) – E</li> <li>Endoscopes -<br/>ography - Ultr</li> <li>Magnetic rest</li> <li>mugam, "Bio<br/>ndanatarajan,</li> <li>poks</li> <li>nandpur, "Ha</li> <li>ition, 2003</li> </ul>   | Medical Instrumentation Basics         Transport of ions through the cell membrane -         Resting potential - Bio-electric potentials – Desof the Bio-Medical Instrument System.         Biopotential Recorders         - Electroencephalography (EEG)-Electromy         lectrooculography (EOG)         Specialized Medical Equipment         - Different types of endoscopes -Computer tomograsonic imaging systems.         Contemporary Issues         sonance imaging         Total Lecture ho         omedical Instrumentation" Anuradha Publications,         * Biomedical Instrumentation" PHI learning, 2009         ndbook of Biomedical Instrumentation" Tata Mc Componention | - Ressign of a sign of a s | ting a f Mec    | 6 hou<br>and ac<br>dical<br>6 ho<br>(EMG)<br>6 ho<br>plicatio<br>2 ho<br>20 ho | urs<br>on of<br>urs        |
| Unit:1<br>Cells and their<br>potentials Char<br>Instruments – C<br>Unit:2<br>Electrocardiogra<br>Electroretinogra<br>Unit:3<br>Angiography –<br>Computer tomo<br>Unit:4<br>X-ray machine<br>Text Book(s)<br>1 M.Aru<br>2 R.Ana<br>Reference Bo<br>1 R.S.Kl<br>2 <sup>nd</sup> Edi<br>2 Ason, | <ul> <li>structure –<br/>racteristics of<br/>Components of<br/>Components of<br/>Paphy (ECG)</li> <li>phy (ERG) – E</li> <li>Endoscopes -<br/>ography - Ultr</li> <li>Magnetic rest</li> <li>mugam, "Bio<br/>ndanatarajan,</li> <li>poks</li> <li>nandpur, "Ha</li> <li>ition, 2003</li> </ul>   | Medical Instrumentation Basics         Transport of ions through the cell membrane -         Resting potential - Bio-electric potentials – Desof the Bio-Medical Instrument System.         Biopotential Recorders         - Electroencephalography (EEG)–Electromy         lectrooculography (EOG)         Specialized Medical Equipment         - Different types of endoscopes -Computer tomograsonic imaging systems.         Contemporary Issues         sonance imaging         Total Lecture homedical Instrumentation" Anuradha Publications, "Biomedical Instrumentation" PHI learning, 2009         ndbook of Biomedical Instrumentation and measurements" Notes                  | - Ressign of a sign of a s | ting a f Mec    | 6 hou<br>and ac<br>dical<br>6 ho<br>(EMG)<br>6 ho<br>plicatio<br>2 ho<br>20 ho | urs<br>on of<br>urs        |

| Rela | Related Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.] |  |  |  |  |  |  |
|------|--|--|--|--|--|--|--|
| 1    | https://nptel.ac.in/courses/127/106/127106134/               |  |  |  |  |  |  |
| 2    | https://nptel.ac.in/courses/108/105/108105101/               |  |  |  |  |  |  |
| 3    | https://swayam.gov.in/nd1_noc19_ge33/preview                 |  |  |  |  |  |  |
| 4    | https://swayam.gov.in/nd1_noc19_bt28/preview                 |  |  |  |  |  |  |
|      |  |  |  |  |  |  |  |
| Cou  | rse Designed By: Dr. Azha. Periasamy                         |  |  |  |  |  |  |

| Mappir | Mapping with Programme Outcomes |     |     |     |     |     |     |     |     |      |  |  |
|--------|---------------------------------|-----|-----|-----|-----|-----|-----|-----|-----|------|--|--|
| COs    | PO1                             | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 |  |  |
| CO1    | S                               | S   | S   | S   | M   | S   | М   | M   | М   | M    |  |  |
| CO2    | S                               | S   | S   | S   | М   | S   | M   | М   | М   | М    |  |  |
| CO3    | S                               | S   | S   | S   | M   | S   | M   | М   | М   | M    |  |  |
| CO4    | S                               | S   | S   | S   | М   | S   | М   | M   | М   | М    |  |  |

BOOLETE TO ELEVATE

| Core/Elective/S  | GS  | ANALYTICAL INSTRUMENTATION  | L                   | Т                    | P  | С                                |
|--|---|---|---------------------|----------------------|--|----------------------------------|
|  | upportive   | Supportive  | 2                   | 0                    | 0  | 2                                |
| Pre-requisite  |   | Student should have the basic knowledge on Instrumentation  | Syllabu<br>Versio   |                      | 2021-22  |                                  |
| Course Object  | ives:   |   | 1                   |                      |  |                                  |
| <ol> <li>Provide a the spectru</li> <li>To Study i</li> </ol>  | various tec<br>1m.<br>mportant n  | s course are to:<br>hniques and methods of analysis which occur in t<br>nethods of analysis of industrial gases.<br>rtant radio chemical methods of analysis.   | the vario           | ous re               | egions   | s of                             |
| Expected Cour  | *   | •   |                     |                      |  |                                  |
|  |   |   |                     |                      |  |                                  |
|  | _   | tion of the co <mark>urse, student w</mark> ill be able to:   |                     |                      | L IZ   | 1                                |
|  |   | mentation techniques for the various industrial ap  | plicatior           | 15                   | K  |                                  |
|  |   | ne applications of biomedical instruments   | -+ V(               | C                    | <u> </u>   | >                                |
| KI - Rememb  | er; <b>K2 -</b> Ur  | nderstand; K3 - Apply; K4 - Analyze; K5 - Evalua  | ate; <b>Ko</b> -    | – Cre                | ate  |                                  |
| Unit:1   |   | Calorimetry and Spectrophotometry   |                     |                      | 8 hou  | irs                              |
| Unit:2   |   | 26  |                     | ļ.                   |  |                                  |
| columnsThern   | nal condu   | Chromatography<br>ock diagram-Basic parts-Sample injection sys<br>activity detector - Liquid chromatograph<br>ressure liquid chromatographs   |                     |                      |  | phy                              |
| columnsThern   | nal condu<br>hy- High pi  | ock diagram-Basic parts-Sample injection sys<br>activity detector - Liquid chromatograph  |                     |                      | itogra   | phy<br>uic                       |
| columnsThern<br>chromatograph<br>Unit:3<br>Types of gas<br>analyzers, and                            | nal condu<br>hy- High pr<br>Industr<br>Analyzers<br>alysis base               | ock diagram-Basic parts-Sample injection sys<br>activity detector - Liquid chromatograph<br>ressure liquid chromatographs   | thermal<br>to carbo | of<br>con            | tograj<br>f liq<br><b>5 ho</b><br>ductivi                            | phy<br>uic<br>urs<br>vity        |
| columnsThern<br>chromatograph<br>Unit:3<br>Types of gas<br>analyzers, ana<br>hydrocarbons,<br>Unit:4 | nal condu<br>hy- High pr<br>Industr<br>Analyzers<br>alysis base<br>nitrogen o | ock diagram-Basic parts-Sample injection sys<br>activity detector - Liquid chromatograph<br>ressure liquid chromatographs<br>rial Gas Analyzers and Pollution Monitoring<br>Instruments<br>s-Oxygen, NO2 and H2S types, IR analyzers,<br>ad on ionization of gases. Air pollution due to<br>xides, sulphur dioxide estimation-dust and smoke<br>Contemporary Issues                       | thermal<br>to carbo | of<br>con            | tograj<br>f liq<br><b>5 ho</b><br>ductivi                            | phy<br>uic<br>urs<br>vity        |
| columnsThern<br>chromatograph<br>Unit:3<br>Types of gas<br>analyzers, ana<br>hydrocarbons,<br>Unit:4 | nal condu<br>hy- High pr<br>Industr<br>Analyzers<br>alysis base<br>nitrogen o | ock diagram-Basic parts-Sample injection sys<br>activity detector - Liquid chromatograph<br>ressure liquid chromatographs<br>rial Gas Analyzers and Pollution Monitoring<br>Instruments<br>-Oxygen, NO2 and H2S types, IR analyzers,<br>ed on ionization of gases. Air pollution due to<br>xides, sulphur dioxide estimation-dust and smoke   | thermal<br>to carbo | of<br>con            | togra<br>f liq<br><b>5 ho</b><br>ductivionox<br>ts                   | phy<br>uic<br>urs<br>vity<br>ide |
| columnsThern<br>chromatograph<br>Unit:3<br>Types of gas<br>analyzers, ana<br>hydrocarbons,<br>Unit:4 | nal condu<br>hy- High pr<br>Industr<br>Analyzers<br>alysis base<br>nitrogen o | ock diagram-Basic parts-Sample injection sys<br>activity detector - Liquid chromatograph<br>ressure liquid chromatographs<br>rial Gas Analyzers and Pollution Monitoring<br>Instruments<br>s-Oxygen, NO2 and H2S types, IR analyzers,<br>ad on ionization of gases. Air pollution due to<br>xides, sulphur dioxide estimation-dust and smoke<br>Contemporary Issues                       | thermal<br>to carbo | con<br>con m<br>emen | togra<br>f liq<br><b>5 ho</b><br>ductivionox<br>ts                   | urs                              |
| columnsThern<br>chromatograph<br>Unit:3<br>Types of gas<br>analyzers, ana<br>hydrocarbons,<br>Unit:4 | nal condu<br>hy- High pr<br>Industr<br>Analyzers<br>alysis base<br>nitrogen o | ock diagram-Basic parts-Sample injection sys<br>activity detector - Liquid chromatograph<br>ressure liquid chromatographs<br>rial Gas Analyzers and Pollution Monitoring<br>Instruments<br>s-Oxygen, NO2 and H2S types, IR analyzers,<br>ed on ionization of gases. Air pollution due to<br>xides, sulphur dioxide estimation-dust and smoke<br>Contemporary Issues<br>bod Cell Counters, | thermal<br>to carbo | con<br>con m<br>emen | tograj<br>f liq<br><b>5 ho</b><br>ductivitonox:<br>ts<br><b>2 ho</b> | urs<br>vity<br>ide               |

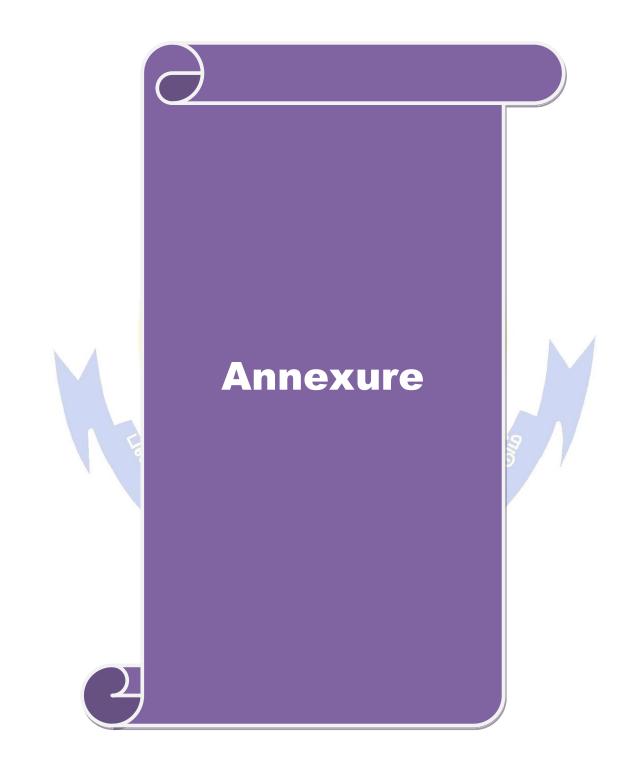
AL-CO

| Re | eference Books  |
|----|---|
| 1  | Robert D.Braun, "Introduction to Instrumental Analysis" Mc Graw Hill, Singapore, 1987.        |
| 2  | G.W. Ewing, "Instrumental Methods of Analysis" Mc Graw Hill 1992.                             |
| 3  | DA Skoog and D.M.West, "Principles of Instrumental Analysis" Harper and Row publishers, 1974. |
| Re | elated Online Contents [MOOC, SWAYAM, NPTEL, Websites etc.]                                   |
| 1  | Academy-Online/pdf  |
| 2  | lecturenotes.in/instrumentation.pdf   |

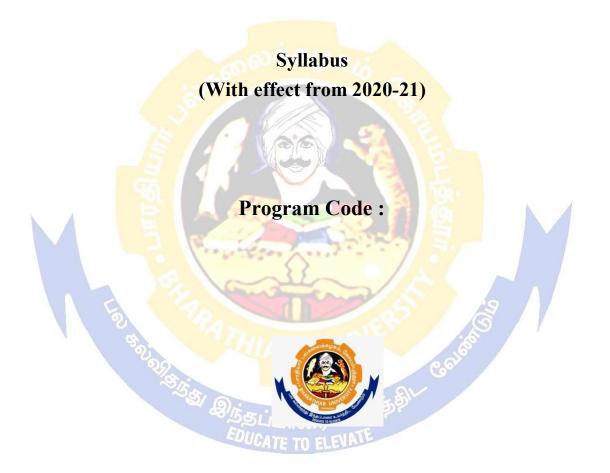
3 https://nptel.ac.in/courses/103/108/103108100/

Course Designed By: Dr. K. G. Padmasine

| Mapping with Programme Outcomes |     |     |     |     |     |     |            |     |     |      |  |
|---------------------------------|-----|-----|-----|-----|-----|-----|------------|-----|-----|------|--|
| COs                             | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | <b>PO7</b> | PO8 | PO9 | PO10 |  |
| CO1                             | S   | М   | М   | S   | S   | М   | M          | S   | S   | S    |  |
| CO2                             | S   | М   | М   | S   | S   | S   | M          | М   | S   | S    |  |



# M. Sc., Electronics and Instrumentation



# **DEPARTMENT OF ELECTRONICS AND INSTRUMENTATION**

**Bharathiar University** (A State University, Accredited with "A" Grade by NAAC and 13<sup>th</sup> Rank among Indian Universities by MHRD-NIRF) Coimbatore 641 046, INDIA

# BHARATHIAR UNIVERSITY : : COIMBATORE 641046 DEPARTMENT OF ELECTRONICS AND INSTRUMENTATION

# MISSION

To impart theoretical and practical training in advanced areas of Electronics and Instrumentation for acquiring knowledge through research which encourages innovation, creativity, insight development and a passion for science towards technological development.



| ONLINE COURSES      |   |  |  |  |  |  |  |  |
|---------------------|---|--|--|--|--|--|--|--|
| NPTEL online course | 2 |  |  |  |  |  |  |  |

| Course      | Title of the Course                           | Cuadita  | Н       | ours      | Maximum Marks |     |       |  |
|-------------|---|----------|---------|-----------|---------------|-----|-------|--|
| Code        | Title of the Course                           | Credits  | Theory  | Practical | CIA           | ESE | Total |  |
|             | FIF   | RST SEME | ESTER   |           |               |     |       |  |
| 1EA         | Electronic Test Instruments                   | 4        | 4       |           | 25            | 75  | 100   |  |
| 1EA         | <b>Bio-Medical Instrumentation</b>            | 4        | 4       |           | 25            | 75  | 100   |  |
| 1EA         | Power Plant Instrumentation                   | 4        | 4       |           | 25            | 75  | 100   |  |
| · · · · · · | SEC   | OND SEM  | IESTER  |           | •             |     |       |  |
| 2EB         | Communication System<br>and Fiber Optics      | 4        | 4       |           | 25            | 75  | 100   |  |
| 2EB         | Computer Aided<br>Instrumentation             | 4        | 4       |           | 25            | 75  | 100   |  |
| 2EB         | Robotics and Automation                       | 4        | 4       |           | 25            | 75  | 100   |  |
|             |   | IRD SEMI | ESTER   | 1         |               |     |       |  |
| 3EC         | Analytical Instrumentation                    | 4        | 4       |           | 25            | 75  | 100   |  |
| 3EC         | Data Communication<br>Networks                | 4        | 4       | G-        | 25            | 75  | 100   |  |
| 3EC         | M <mark>icrowave</mark> Theory and Techniques | 4        | 4       |           | 25            | 75  | 100   |  |
|             |   | 3        |         |           |               | 1   |       |  |
|             | SUPPO   | ORTIVE S | UBJECTS |           |               |     |       |  |
| GS          | Digital Electronics<br>and Microprocessor     | 2        | 2       |           | 12            | 38  | 50    |  |
| GS          | Medical Electronics and<br>Instrumentation    | 2        | 2       | Coller    | 12            | 38  | 50    |  |
| GS          | Analytical Instrumentation                    | 2        | 2       | /         | 12            | 38  | 50    |  |

## **ELECTIVE & SUPPORTIVE SUBJECTS**

இத்தப்பாரை உயர்த்து

# CERTIFICATE AND VALUE ADDED COURSES

| Title of the Course          | Credita      | Н           | ours          | Maximum Marks |            |       |  |  |  |  |
|------------------------------|--------------|-------------|---------------|---------------|------------|-------|--|--|--|--|
| The of the Course            | Credits      | Theory      | Practical     | Theory        | Practical  | Total |  |  |  |  |
| CERTIFICATE COURSES          |              |             |               |               |            |       |  |  |  |  |
| (Approved by UGC under       | er the Natio | onal Skills | Qualification | s Framewo     | ork (NSQF) |       |  |  |  |  |
| DSP Using MATLAB             | 2            | 40          | 40            | 50            | 50         | 100   |  |  |  |  |
| Embedded System Design Using | 2            | 10          | 40            | 50            | 50         | 100   |  |  |  |  |
| ARM/Cortex Microcontroller   | 2            | 40          | 40            | 50            | 50         | 100   |  |  |  |  |
|                              | VALUE A      | ADDED C     | OURSES        |               |            |       |  |  |  |  |
| Digital Tools                | 2            | 15          | 15            | 25            | 25         | 50    |  |  |  |  |
| (Lab Integrated Theory)      | 2            | 15          | 13            | 23            | 23         | 50    |  |  |  |  |
| NLP and NLP (Theory)         | 2            | 30          |               | 50            | _          | 50    |  |  |  |  |

